

Gravity: Water Pressure Sensor

SKU: SEN0257



Gravity: Analog Water Pressure Sensor SKU: SEN0257

This is a water pressure sensor that adopts DFRobot Gravity 3-pin interface. It supports standard 5V voltage input and 0.5~4.5V linear voltage output. It is compatible with multiple Arduino controllers. Coordinate with a DFRobot Gravity IO Expansion Shield, the water pressure sensor can be plugged into an Arduino board, wiring-free. Put it with a Solenoid Valve, a Water Turbine Generator and other sensors, you can build a smart water control system. Briefly speaking, this water pressure sensor is a stethoscope to a water pipe. It will help you to diagnose whether there is water, how strong the water pressure is. It can be widely applied to smart home control systems (SCS), Internet of Things (IoT) and device detection.

Features

- Support water pressure detection of living environmental water systems, such as houses, gardens and farms.
- Support water pressure detection of outdoor environment, such as rivers, lakes and sea.
- Support water pressure detection of tanks.
- Support liquid level detection in special situation.

Specification

Medium: liquid/gas without corrosion
 Wiring: Gravity-3Pin (Signal-VCC-GND)
 Pressure Measurement Range: 0~1.6 Mpa

Input Voltage: +5 VDCOutput Voltage: 0.5~4.5 V

Measurement Accuracy: 0.5%~1%FS (0.5%, 0~55°C)

Threadably: G1/4Adapter: G1/2 to G1/4Waterproof Level: IP68

Operating Temperature: -20~85°C

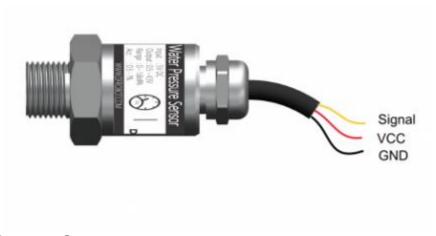
Response Time: <2.0 msQuiescent Current: 2.8 mA

• Normal Operating Pressure: ≤2.0 Mpa

Damaged Pressure: ≥3.0 Mpa

• Service Life: ≥10'000'000 times (10 million)

PinOut



PinOut-Water Preessure Sensor

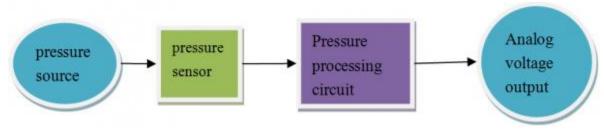
Label Name	Description
Yellow Signal(Output:0.5~4.	5V) Analog Signal
Red VCC(5VDC)	+
Black GND	-

Input & Output

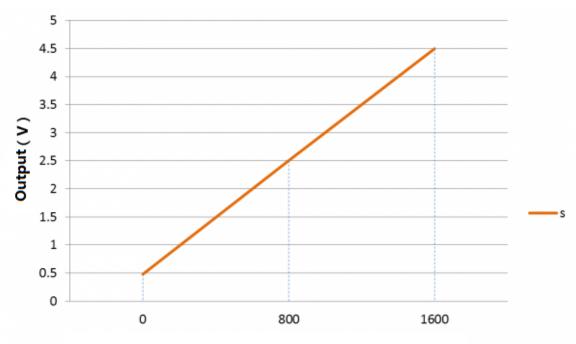
The monocrystallinesilicon is one interior material of the sensor. When monocrystallinesilicon material suffers force, it makes an infinitesimal change and an electronic level change of internal atom structure, which will also lead to a great change in resistivity (Factor H Mutation), so as the resistance. This physical effect is piezoresistive effect.

Based on the piezoresistive effect, a strain gauge is also a work of IC (integrated circuit) engineering technology. Its production process contains doping, diffusion and a crystal orientation of the substrate. A strain gauge makes a Wheatstone Bridge. Taking advantage of elasticity properties of special silicon material and heterosexual micro-machining the same silicon material in different directions, then a diffused silicon sensor comes into being. The sensor is force-sensitive and mechanical-electrical detective.

Equipped with an amplify circuit and other parts in need, enable the circuit to output a standard signal, the diffused silicon sensor makes a pressure transmitter.



Signal Production Process



Input (Atmosphere Pressure + Tested Pressure) (kPa)

The Local AT Pressure is about 100kPa

Tutorial

In this section, we'll show the basic sensor usage and a simple demo about pressure detector.

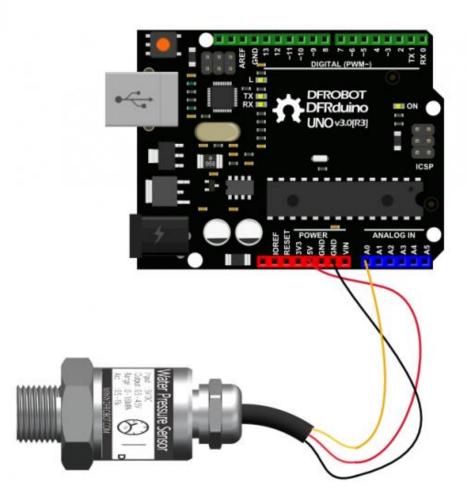
Demo: Read Water Pressure Value

Requirements

Hardware
 DFRduino UNO R3 (or similar) x 1
 Gravity: Analog Water Pressure Sensor
 Dupont wires

• Software Arduino IDE (Version requirements: V1.6.+), click to Download Arduino IDE from Arduino®

Connection Diagram(Arduino)



Analog Module Connection Diagram

Sample Code

Read Data by Serial Port.

```
/****************
  Water pressure sensor demo(Computer serial port)
  - Obtain the water pressure through the output voltage
   of the sensor.
*******************
/**********************
 Water Sensor Key Parameter
 - Parts No.: KY-3-5
 - Sensing range: 0 - 1.6 MPa
 - Input Voltage: 5VDC
 - Output Voltage: 0.5 - 4.5 VDC
   (Linearly corresponding to 0 - 1.6 MPa)
 - Accuary: 0.5% - 1% FS
*************************************
/****************
 Water Sensor Calibration
 The output voltage offset of the sensor is 0.5V (norminal).
 However, due to the zero-drifting of the internal circuit, the
 no-load output voltage is not exactly 0.5V. Calibration needs to
 be carried out as follow.
 Calibration: connect the 3 pin wire to the Arduio UNO (VCC, GND and Signal)
 without connecting the sensor to the water pipe and run the program
 for once. Mark down the LOWEST voltage value through the serial
 monitor and revise the "OffSet" value to complete the calibration.
 After the calibration the sensor is ready for measuring!
******************
```

```
const float OffSet = 0.483;
float V, P;
void setup()
 Serial.begin(9600); // open serial port, set the baud rate to 9600 b
ps
 Serial.println("/** Water pressure sensor demo **/");
void loop()
 //Connect sensor to Analog 0
 V = analogRead(0) * 5.00 / 1024;  //Sensor output voltage
 P = (V - OffSet) * 400; //Calculate water pressure
  Serial.print("Voltage:");
  Serial.print(V, 3);
  Serial.println("V");
  Serial.print(" Pressure:");
  Serial.print(P, 1);
  Serial.println(" KPa");
  Serial.println();
 delay(500);
}
```

Demo: DIY a Simple Water Pressure Detector

Requirements

Hardware

DFRduino UNO R3 (or similar) x 1 DFRobot Gravity IO Expansion Shield x1

Gravity: I2C 16x2 Arduino LCD with RGB Backlight Display

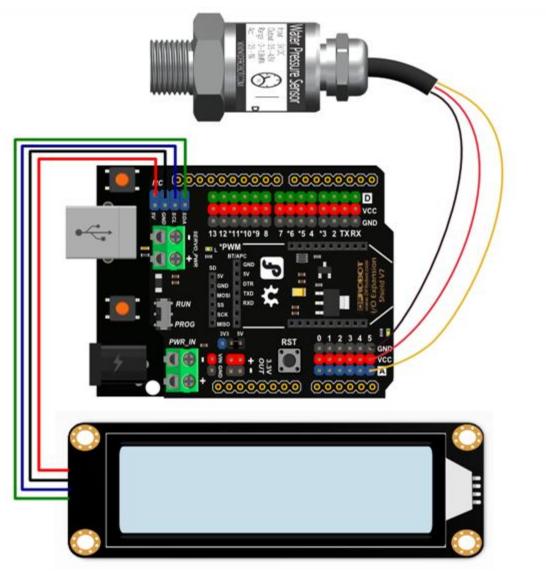
7.4V 2500MA Lithium Battery x1

Dupont wires

Software

Arduino IDE (Version requirements: V1.6.+), click to Download Arduino IDE from Arduino®

Connection Diagram



Water Pressure Detector

Sample Code

Please download the LCD library: DFRobot RGB LCD. How to install Libraries in Arduino IDE Read Data by LCD1602 Display.

/***********
Water pressure sensor demoB(LCD1602)
- Obtain the water pressure through the output voltage
of the sensor.

/**********
Water Sensor Key Parameter
- Parts No.:KY-3-5
- Sensing range: 0 - 1.6 MPa
- Input Voltage: 5VDC
- Output Voltage: 0.5 - 4.5 VDC
(Linearly corresponding to 0 - 1.6 MPa)
- Accuary: 0.5% - 1% FS

/**********
/*************************************
Water Sensor Calibration
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```
#include <Wire.h>
#include <DFRobot_RGBLCD.h>
                                                     //LCD header file
const float OffSet = 0.483;
float V;
int P;
unsigned int lcd r = 0, lcd g = 0, lcd b = 0;
unsigned long delaytime = 0, lighttime = 0;
DFRobot_RGBLCD lcd(16, 2);
void setup()
{lcd.init();
 delay(5000);
 Serial.begin(115200);
  Serial.println("hello start");
 lighttime = millis();
 lcd.setCursor(0, 0);
 lcd.print("Water Pressure:");
 lcd.setRGB(255, 255, 000);
void loop() {
1cd r = random(256);
 delayMicroseconds(10);
 lcd g = random(256);
 delayMicroseconds(10);
 lcd b = random(256);
 if (millis() - lighttime > 3000)
   lcd.setRGB(lcd_r, lcd_g, lcd_b);
   lighttime = millis();
  //delay(100);
   V = analogRead(0) * 5.00 / 1024;
                                                         //Sensor output volta
ge
```

Expected Results



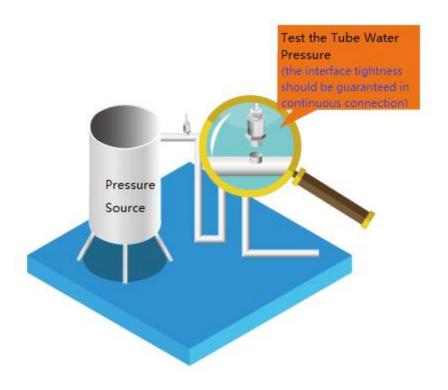
Water Pressure Display

Installation

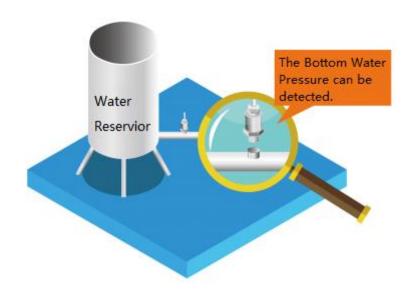


Installation Scenes

Installation Scenes



Tube Water Pressure Detection



Bottom Water Pressure Detection



NOTE:

- 1.To guarantee the interface tightness, you need to install a waterproof nut and bind PTFE tape.
- 2. Please take necessary measures to avoid large pressure involved during usage.

FAQ

Q1. Some general Arduino Problems/FAQ/Tips

A. Click the topic link on DFRobot Forum.

For any questions, advice or cool ideas to share, please visit the DFRobot Forum.

More Documents

