

## FEATURES

- Low Dropout, 430mV at 10A Output Current
- Fast Transient Response
- Remote Sense
- 1mV Load Regulation
- Fixed 2.5V Output and Adjustable Output
- No Supply Sequencing Problems in Dual Supply Mode

## APPLICATIONS

- Microprocessor Supplies
- Post Regulators for Switching Supplies
- High Current Regulators
- 5V to 3.XXV for Pentium® Processors Operating at 90MHz to 166MHz and Beyond
- 3.3V to 2.9V for Portable Pentium Processor
- PowerPC™ Series Power Supplies

## DESCRIPTION

The LT<sup>®</sup>1581 is a 10A low dropout regulator designed to power the new generation of microprocessors. The dropout voltage of this device is 100mV at light loads rising to just 430mV at 10A. To achieve this dropout a second low current input voltage 1V greater than the output voltage is required. The device can also be used as a single supply device where dropout is comparable to an LT1584.

Several other new features have been added to the LT1581. A remote SENSE pin is brought out. This feature virtually eliminates output voltage variations due to load changes. Typical load regulation for a load current step of 100mA to 10A, measured at the SENSE pin, is less than 1mV.

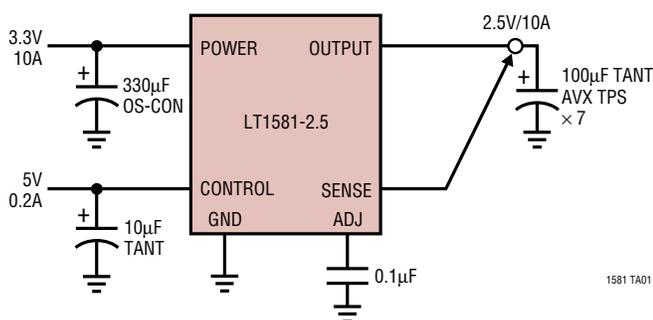
The LT1581 has fast transient response, equal to the LT1584. On fixed voltage devices, the ADJUST pin is brought out. A small capacitor on the ADJUST pin further improves transient response.

This device is ideal for generating processor supplies of 2V to 3V on motherboards where both 5V and 3.3V supplies are available.

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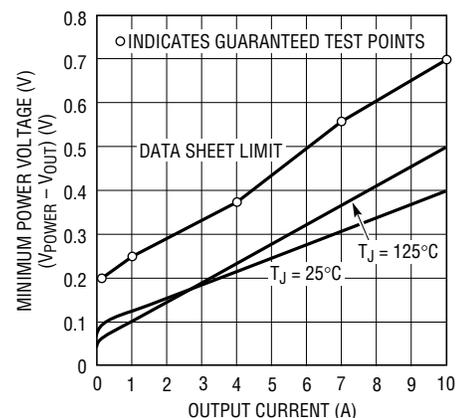
## TYPICAL APPLICATION

2.5V Microprocessor Supply



1581 TA01

Dropout Voltage –  
 Minimum Power Voltage



1581 G03

# LT1581/LT1581-2.5

## ABSOLUTE MAXIMUM RATINGS

(Note 1)

V <sub>POWER</sub> Input Voltage .....	6V
V <sub>CONTROL</sub> Input Voltage .....	13V
Operating Junction Temperature Range	
Control Section .....	0°C to 125°C
Power Transistor .....	0°C to 150°C
Storage Temperature .....	-65°C to 150°C
Lead Temperature (Soldering, 10 sec).....	300°C

## PRECONDITIONING

100% Thermal Limit Functional Test

## PACKAGE/ORDER INFORMATION

<p>FRONT VIEW</p> <p>TAB IS OUTPUT</p> <p>T7 PACKAGE 7-LEAD PLASTIC TO-220 θ<sub>JA</sub> = 50°C/W</p> <p>*PIN2 = NC FOR LT1581CT7, GND FOR LT1581CT7-2.5</p>	ORDER PART NUMBER
	LT1581CT7 LT1581CT7-2.5

Consult factory for Industrial and Military grade parts.

## ELECTRICAL CHARACTERISTICS

The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C. (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Output Voltage: LT1581-2.5	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 0mA	2.485	2.500	2.515	V
	V <sub>CONTROL</sub> = 4V to 12V, V <sub>POWER</sub> = 3V to 5.5V, I <sub>LOAD</sub> = 0mA to 4A ●	2.475	2.500	2.525	V
	V <sub>CONTROL</sub> = 4V to 12V, V <sub>POWER</sub> = 3.3V to 5.5V, I <sub>LOAD</sub> = 0mA to 10A ●	2.475	2.500	2.525	V
Reference Voltage: LT1581 (V <sub>ADJ</sub> = 0V)	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2V, I <sub>LOAD</sub> = 10mA	1.243	1.250	1.257	V
	V <sub>CONTROL</sub> = 2.7V to 12V, V <sub>POWER</sub> = 1.75V to 5.5V, I <sub>LOAD</sub> = 0mA to 4A ●	1.237	1.250	1.263	V
	V <sub>CONTROL</sub> = 2.7V to 12V, V <sub>POWER</sub> = 2.05V to 5.5V, I <sub>LOAD</sub> = 0mA to 10A ●	1.237	1.250	1.263	V
Line Regulation: LT1581-2.5 LT1581	V <sub>CONTROL</sub> = 3.65V to 12V, V <sub>POWER</sub> = 3V to 5.5V, I <sub>LOAD</sub> = 10mA ●		1	3	mV
	V <sub>CONTROL</sub> = 2.5V to 12V, V <sub>POWER</sub> = 1.75V to 5.5V, I <sub>LOAD</sub> = 10mA ●		1	3	mV
Load Regulation: LT1581-2.5 LT1581 (V <sub>ADJ</sub> = 0V)	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 0mA to 10A ●		1	10	mV
	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.1V, I <sub>LOAD</sub> = 10mA to 10A ●		1	5	mV
Minimum Load Current: LT1581	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, V <sub>ADJ</sub> = 0V (Note 4) ●		3	10	mA
Control Pin Current: LT1581-2.5 (Note 5)	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 100mA ●		5	10	mA
	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 4A ●		20	50	mA
	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 7A ●		40	100	mA
	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 10A ●		70	170	mA
Control Pin Current: LT1581 (Note 5)	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, I <sub>LOAD</sub> = 100mA ●		5	10	mA
	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, I <sub>LOAD</sub> = 4A ●		20	50	mA
	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, I <sub>LOAD</sub> = 7A ●		40	100	mA
	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, I <sub>LOAD</sub> = 10A ●		70	170	mA
Ground Pin Current: LT1581-2.5	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, I <sub>LOAD</sub> = 0mA ●		6	10	mA
Adjust Pin Current: LT1581 (V <sub>ADJ</sub> = 0V)	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, I <sub>LOAD</sub> = 10mA ●		60	120	μA
Current Limit: LT1581-2.5 LT1581 (V <sub>ADJ</sub> = 0V)	V <sub>CONTROL</sub> = 5V, V <sub>POWER</sub> = 3.3V, ΔV <sub>OUT</sub> = 100mV ●	10.1	11		A
	V <sub>CONTROL</sub> = 2.75V, V <sub>POWER</sub> = 2.05V, ΔV <sub>OUT</sub> = 100mV ●	10.1	11		A
Ripple Rejection: LT1581-2.5  LT1581	V <sub>CONTROL</sub> = V <sub>POWER</sub> = 5V Avg, V <sub>RIPPLE</sub> = 1V <sub>P-P</sub> , f <sub>RIPPLE</sub> = 120Hz, I <sub>OUT</sub> = 4A, T <sub>J</sub> = 25°C	55	80		dB
	V <sub>CONTROL</sub> = V <sub>POWER</sub> = 3.75V Avg, V <sub>RIPPLE</sub> = 1V <sub>P-P</sub> , f <sub>RIPPLE</sub> = 120Hz, V <sub>ADJ</sub> = 0V, I <sub>OUT</sub> = 4A, T <sub>J</sub> = 25°C	60	80		dB
Thermal Regulation	30ms Pulse		0.004	0.020	%/W
Thermal Resistance, Junction-to-Case	Control Circuitry/Power Transistor		0.65/2.50		°C/W

**ELECTRICAL CHARACTERISTICS** The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ . (Note 2)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>Dropout Voltage (Note 3)</b>					
Minimum $V_{\text{CONTROL}}$ : LT1581-2.5 ( $V_{\text{CONTROL}} - V_{\text{OUT}}$ )	$V_{\text{POWER}} = 3.3\text{V}$ , $I_{\text{LOAD}} = 100\text{mA}$	●	1.02	1.25	V
	$V_{\text{POWER}} = 3.3\text{V}$ , $I_{\text{LOAD}} = 1\text{A}$	●	1.04	1.27	V
	$V_{\text{POWER}} = 3.3\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$	●	1.06	1.30	V
	$V_{\text{POWER}} = 3.3\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$	●	1.10	1.33	V
	$V_{\text{POWER}} = 3.3\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$	●	1.12	1.35	V
Minimum $V_{\text{CONTROL}}$ : LT1581 ( $V_{\text{CONTROL}} - V_{\text{OUT}}$ ) ( $V_{\text{ADJ}} = 0\text{V}$ )	$V_{\text{POWER}} = 2.05\text{V}$ , $I_{\text{LOAD}} = 100\text{mA}$	●	1.02	1.25	V
	$V_{\text{POWER}} = 2.05\text{V}$ , $I_{\text{LOAD}} = 1\text{A}$	●	1.04	1.27	V
	$V_{\text{POWER}} = 2.05\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$	●	1.06	1.30	V
	$V_{\text{POWER}} = 2.05\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$	●	1.10	1.33	V
	$V_{\text{POWER}} = 2.05\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$	●	1.12	1.35	V
Minimum $V_{\text{POWER}}$ : LT1581-2.5 ( $V_{\text{POWER}} - V_{\text{OUT}}$ )	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 100\text{mA}$	●	0.10	0.20	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 1\text{A}$	●	0.13	0.25	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.22	0.33	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$	●		0.37	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.31	0.45	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$	●		0.55	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.43	0.63	V
	$V_{\text{CONTROL}} = 5\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$	●		0.70	V
Minimum $V_{\text{POWER}}$ : LT1581 ( $V_{\text{POWER}} - V_{\text{OUT}}$ ) ( $V_{\text{ADJ}} = 0\text{V}$ )	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 100\text{mA}$	●	0.10	0.20	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 1\text{A}$	●	0.13	0.25	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.22	0.33	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 4\text{A}$	●		0.37	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.31	0.45	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 7\text{A}$	●		0.55	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$ , $T_J = 25^\circ\text{C}$	●	0.43	0.63	V
	$V_{\text{CONTROL}} = 2.75\text{V}$ , $I_{\text{LOAD}} = 10\text{A}$	●		0.70	V

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

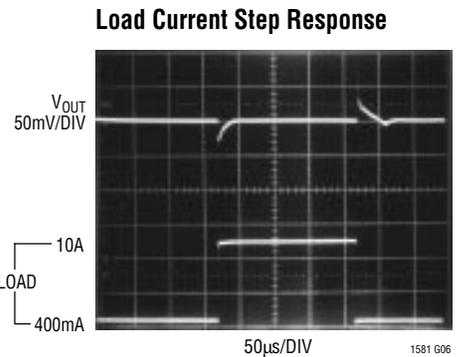
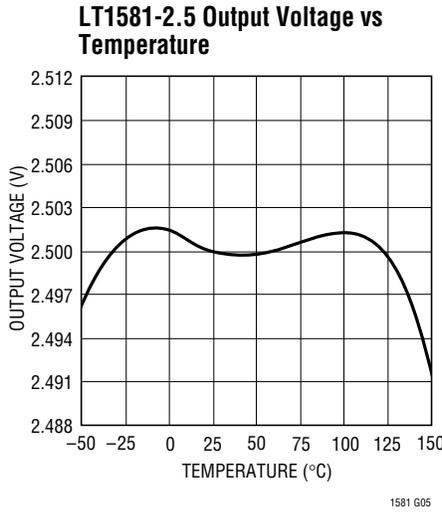
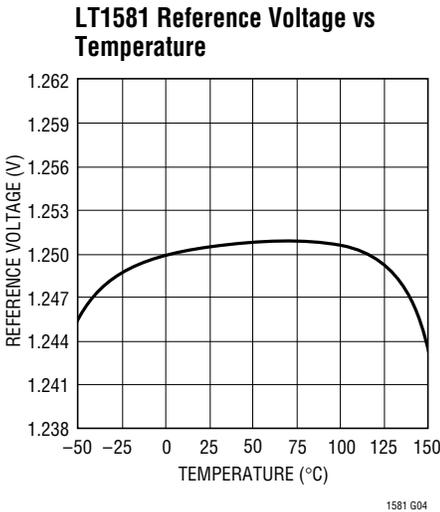
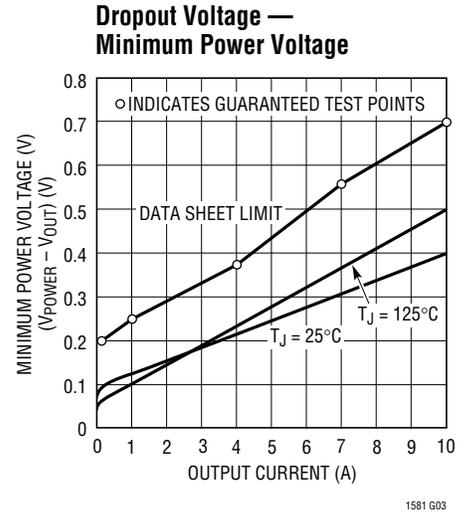
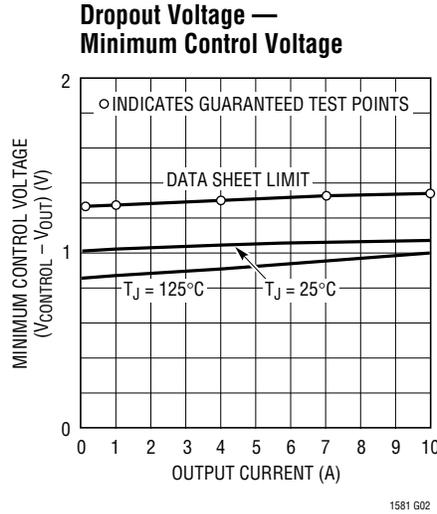
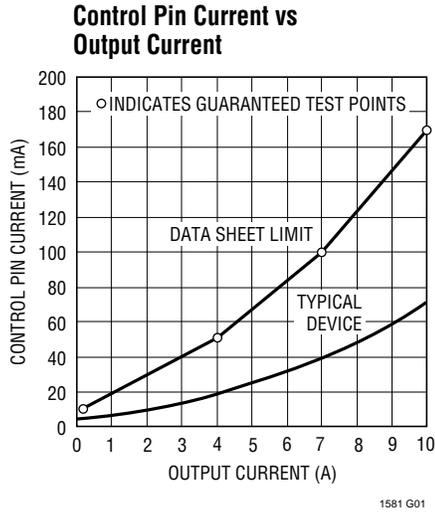
**Note 2:** Unless otherwise specified,  $V_{\text{OUT}} = V_{\text{SENSE}}$ . For the LT1581 adjustable device,  $V_{\text{ADJ}} = 0\text{V}$ .

**Note 3:** For the LT1581, dropout is caused by either minimum control voltage ( $V_{\text{CONTROL}}$ ) or minimum power voltage ( $V_{\text{POWER}}$ ). Both parameters are specified with respect to the output voltage. The specifications represent the minimum input-to-output voltage required to maintain 1% regulation.

**Note 4:** For the LT1581 adjustable device the minimum load current is the minimum current required to maintain regulation. Normally, the current in the resistor divider used to set the output voltage is selected to meet the minimum load current requirement.

**Note 5:** The CONTROL pin current is the drive current required for the output transistor. This current will track output current with roughly a 1:100 ratio. The minimum value is equal to the quiescent current of the device.

## TYPICAL PERFORMANCE CHARACTERISTICS



## PIN FUNCTIONS

**ADJUST (Pin 1):** This pin is the negative side of the reference voltage for the device. Transient response can be improved by adding a small bypass capacitor from the ADJUST pin to ground. For fixed voltage devices the ADJUST pin is also brought out to allow the user to add a bypass capacitor.

**GND (Pin 2, Fixed Voltage Devices Only):** For fixed voltage devices this is the bottom of the resistor divider that sets the output voltage.

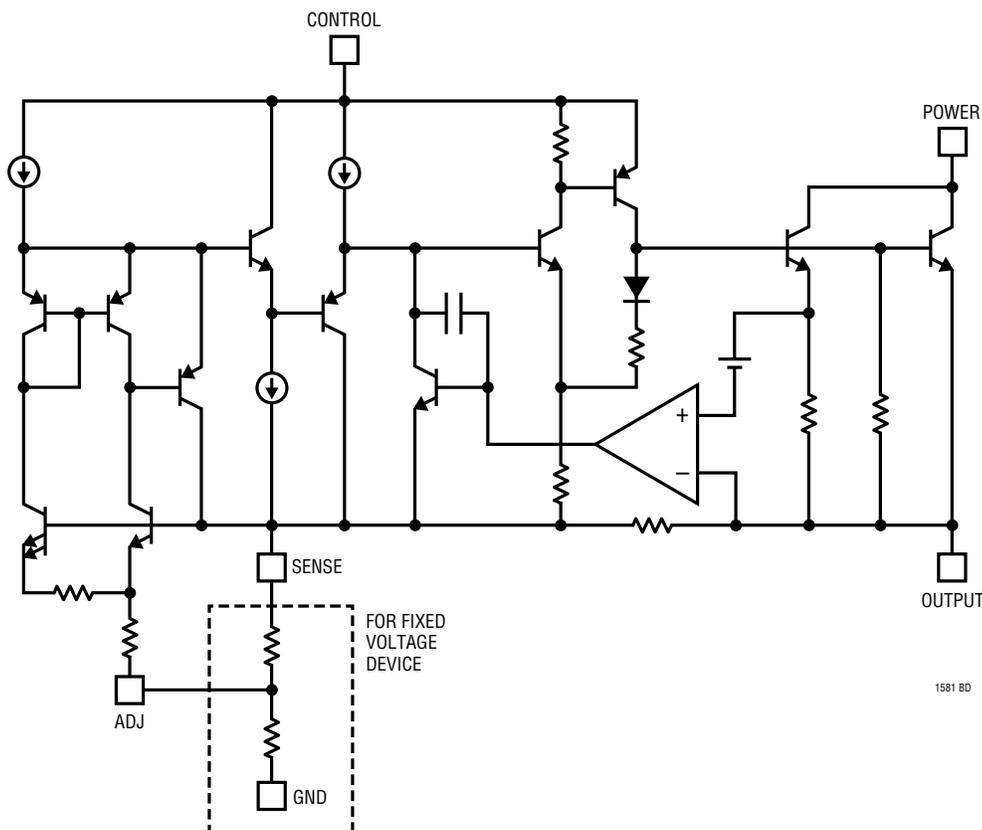
**SENSE (Pin 3):** This pin is the positive side of the reference voltage for the device. With this pin it is possible to Kelvin sense the output voltage at the load.

**OUTPUT (Pin 4):** This is the power output of the device.

**$V_{POWER}$  (Pin 5):** This is the collector to the power device of the LT1581. The output load current is supplied through this pin. For the device to regulate, the voltage at this pin must be between 0.1V and 0.7V greater than the output voltage (see Dropout specifications).

**$V_{CONTROL}$  (Pin 6):** This pin is the supply pin for the control circuitry of the device. The current flow into this pin will be about 1% of the output current. For the device to regulate, the voltage at this pin must be between 1.0V and 1.35V greater than the output voltage (see Dropout specifications).

## BLOCK DIAGRAM



## APPLICATIONS INFORMATION

The LT1581 is a low dropout regulator designed to power the new generation of microprocessors. Low dropout regulators have become more common in desktop computer systems as microprocessor manufacturers have moved away from 5V only CPUs. A wide range of supply requirements exists today with new voltages just over the horizon. In many cases the input/output differential is very small, effectively disqualifying many of the low dropout regulators on the market today. The LT1581 is designed to make use of multiple power supplies present in most systems to reduce the dropout voltage. This 2-supply approach maximizes efficiency.

The second supply, at least 1V greater than the output voltage, is used to provide power for the control circuitry and supply the drive current to the NPN output transistor. This allows the NPN to be driven into saturation, thereby reducing the dropout voltage by a  $V_{BE}$  compared to conventional designs. The current requirement for the

control voltage is relatively small, equal to approximately 1% of the output current or about 100mA for a 10A load. The bulk of this current is drive current for the NPN output transistor. This drive current becomes part of the output current.

The control voltage must be at least 1V greater than the output voltage to obtain optimum performance. The maximum voltage on the  $V_{CONTROL}$  pin is 13V. The maximum voltage at the  $V_{POWER}$  pin is limited to 7V. GND pin current for fixed voltage devices is 6mA (typ) and is constant as a function of load. ADJUST pin current for adjustable devices is 60 $\mu$ A at 25°C and varies proportional to absolute temperature.

The LT1581 has improved frequency compensation which permits the use of capacitors with very low ESR. This is critical in addressing the needs of modern, low voltage, high speed microprocessors. Current generation micro-

## APPLICATIONS INFORMATION

processors cycle load current from several hundred milliamperes to several amperes in tens of nanoseconds. Output voltage tolerances are tighter and include transient response as part of the specification. The LT1581 is designed to meet the fast current load step requirements of these microprocessors and saves total cost by needing less output capacitance to maintain regulation.

Careful design has eliminated any supply sequencing issues associated with a dual supply system. The output voltage will not turn on until both supplies are operating. If the control voltage comes up first, the output current will be limited to a few milliamperes until the power input voltage comes up. If the power input comes up first the output will not turn on at all until the control voltage comes up. The output can never come up unregulated. The LT1581 can also be operated as a single supply device by tying the control and power inputs together. Dropout in single supply operation will be determined by the minimum control voltage.

The LT1581 includes several innovative features that require additional pins over the traditional 3-terminal regulator. Both the fixed and adjustable devices have remote sense pins, permitting very accurate regulation of output voltage at the load, where it counts, rather than at the regulator. As a result the typical load regulation over an output current range of 100mA to 10A with a 2.5V output is typically less than 1mV. For the fixed voltage devices the ADJUST pin is also brought out. This allows the user to improve transient response by bypassing the internal resistor divider. In the past, fixed output voltage devices did not provide this capability. Bypassing the ADJUST pin with a capacitor in the range of 0.1 $\mu$ F to 1 $\mu$ F will provide optimum transient response. The value chosen will depend on the amount of output capacitance in the system.

In addition to the enhancements mentioned above, the reference accuracy has been improved by a factor of two with a guaranteed initial tolerance of  $\pm 0.6\%$  at 25°C. Temperature drift is also very well controlled. When combined with ratiometrically accurate internal divider resistors the part can easily hold 1% output accuracy over the full temperature range and load current range, guaran-

teed, while operating with an input/output differential of well under 1V.

Typical applications for the LT1581 include 3.3V to 2.5V conversion with a 5V control supply, 5V to 4.2V conversion with a 12V control supply or 5V to 3.6V conversion with a 12V control supply. It is easy to obtain dropout voltages of less than 0.4V at 4A along with excellent static and dynamic specifications. The LT1581 is capable of 10A of output current with a maximum dropout of 0.7V. The LT1581 has fast transient response that allows it to handle the large current changes associated with today's microprocessors. The device is fully protected against overcurrent and overtemperature conditions. Both fixed voltage (2.5V) and adjustable output versions are available. The device is available in a 7-lead TO-220 package.

### Grounding and Output Sensing

The LT1581 allows true Kelvin sensing for both the high and low side of the load. This means that the voltage regulation at the load can be easily optimized. Voltage drops due to parasitic resistances between the regulator and the load which would normally degrade regulation can be placed inside the regulation loop of the LT1581. Figures 1 through 3 illustrate the advantages of remote sensing. Figure 1 shows the LT1581 connected as a conventional 3-terminal regulator with the SENSE lead connected directly to the output of the device.  $R_P$  represents the parasitic resistance of the connections between the LT1581 and the load. The load is typically a microprocessor and  $R_P$  is made up of the PC traces and/or connector resistances, in the case of a modular regulator, between the regulator and the processor. The effect of  $R_P$  can be seen in trace A of Figure 3. Very small resistances cause significant load regulation steps. For example, at 10A output current the output voltage will shift by 10mV for every 0.001 $\Omega$  of resistance. In Figure 2 the LT1581 is connected to take advantage of the remote sense feature. The SENSE pin and the top of the resistor divider are connected to the top of the load. The bottom of the resistor divider is connected to the bottom of the load.  $R_P$  is now effectively connected inside the regulating loop of the LT1581 and the load regulation at the load will be negligible for reasonable values of  $R_P$ . Trace B of Figure 3

## APPLICATIONS INFORMATION

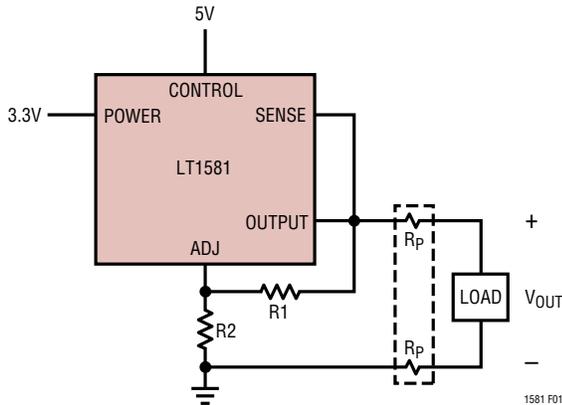


Figure 1. Conventional Load Sensing

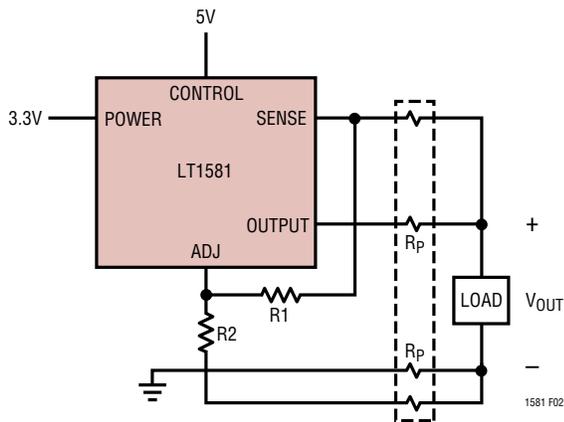


Figure 2. Remote Load Sensing

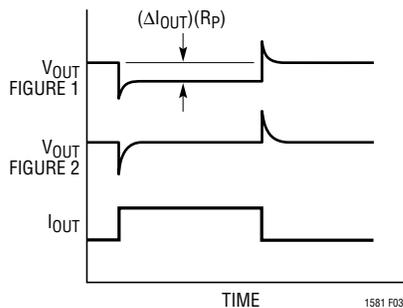


Figure 3. Remote Sensing Improves Load Regulation

illustrates the effect on output regulation. It is important to note that the voltage drops due to  $R_p$  are not eliminated. They will add to the dropout voltage of the regulator regardless of whether they are inside the loop as in Figure 2 or outside the loop as in Figure 1. This means that the

LT1581 can control the voltage at the load as long as the input/output voltage is greater than the total of the dropout voltage of the LT1581 plus the voltage drop across  $R_p$ .

### Stability

The LT1581 requires the use of an output capacitor as part of the device frequency compensation. The device requires a minimum of  $22\mu\text{F}$  tantalum or  $150\mu\text{F}$  of aluminum electrolytic to ensure stability. Larger capacitor values increase stability and improve transient performance.

Many different types of capacitors are available and have widely varying characteristics. These capacitors differ in capacitor tolerance (sometimes up to  $\pm 100\%$ ), equivalent series resistance, equivalent series inductance and capacitance temperature coefficient. The LT1581 frequency compensation optimizes frequency response with low ESR capacitors. In general, use capacitors with an ESR of less than  $1\Omega$ .

For microprocessor applications larger value capacitors will be needed to meet the transient requirements of the processor. Processor manufacturers require tight voltage tolerances on the power supply. High quality bypass capacitors must be used to limit the high frequency noise generated by the processor. Multiple small ceramic capacitors in addition to high quality bulk tantalum capacitors are typically required to limit parasitic inductance (ESL) and resistance (ESR) in the capacitors to acceptable levels. The LT1581 is stable with the type of capacitors recommended by processor manufacturers.

Bypassing the adjust terminal on the LT1581 improves ripple rejection and transient response. The ADJUST pin is brought out on the fixed voltage device specifically to allow this capability.

Capacitor values on the order of several hundred microfarads are used to ensure good transient response with heavy load current changes. Output capacitance can increase without limit and larger values of output capacitance further improve the stability and transient response of the LT1581.

Modern microprocessors generate large high frequency current transients. The load current step contains higher order frequency components that the output coupling

## APPLICATIONS INFORMATION

network must handle until the regulator throttles to the load current level. Capacitors are not ideal elements and contain parasitic resistance and inductance. These parasitic elements dominate the change in output voltage at the beginning of a transient load step change. The ESR of the output capacitors produces an instantaneous step in output voltage ( $\Delta V = \Delta I)(ESR)$ . The ESL of the output capacitors produces a droop proportional to the rate of change of the output current ( $V = L)(\Delta I/\Delta t)$ . The output capacitance produces a change in output voltage proportional to the time until the regulator can respond ( $\Delta V = \Delta t)(\Delta I/C)$ . These transient effects are illustrated in Figure 4.

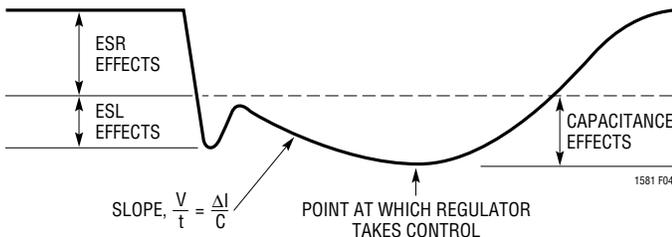


Figure 4

The use of capacitors with low ESR, low ESL and good high frequency characteristics is critical in meeting the output voltage tolerances of these high speed microprocessors. These requirements dictate a combination of high quality, surface mount, tantalum and ceramic capacitors. The location of the decoupling network is critical to transient performance. Place the decoupling network as close to the processor pins as possible because trace runs from the decoupling capacitors to the processor pins are inductive. The ideal location for the decoupling network is actually inside the microprocessor socket cavity. In addition, use large power and ground plane areas to minimize distribution drops.

### Output Voltage

The adjustable version of the LT1581 develops a 1.25V reference voltage between the SENSE pin and the ADJUST pin (see Figure 5). Placing a resistor R1 between these two terminals causes a constant current to flow through R1 and down through R2 to set the overall output voltage. Normally, R1 is chosen so that this current is the specified

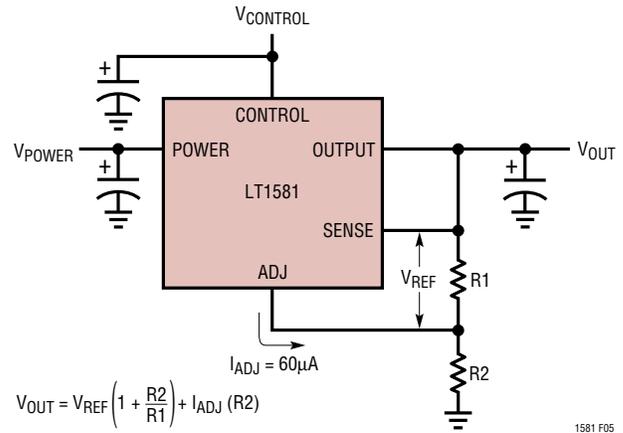


Figure 5. Setting Output Voltage

minimum load current of 10mA. The current out of the ADJUST pin adds to the current from R1. The ADJUST pin current is small, typically 60μA. The output voltage contribution of the ADJUST pin current is small and only needs to be considered when very precise output voltage setting is required. Note that the top of the resistor divider should be connected directly to the SENSE pin for best regulation. See the section on grounding and Kelvin sensing above.

### Protection Diodes

In normal operation the LT1581 does not require protection diodes. Older 3-terminal regulators require protection diodes between the OUTPUT pin and the INPUT pin or between the ADJUST pin and the OUTPUT pin to prevent die overstress.

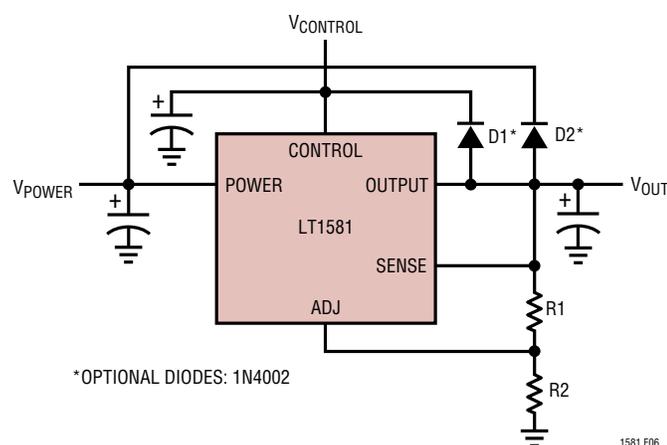
On the LT1581, internal resistors limit internal current paths on the ADJUST pin. Therefore even with bypass capacitors on the ADJUST pin, no protection diode is needed to ensure device safety under short-circuit conditions. The ADJUST pin can be driven on a transient basis  $\pm 7V$  with respect to the output without any device degradation.

A protection diode between the OUTPUT pin and the VPOWER pin is usually not needed. An internal diode between the OUTPUT pin and the VPOWER pin on the LT1581 can handle microsecond surge currents of 50A to 100A. Even with large value output capacitors it is difficult to obtain those values of surge currents in normal operation. Only with large values of output capacitance, such as

## APPLICATIONS INFORMATION

1000 $\mu$ F to 5000 $\mu$ F, and with the  $V_{POWER}$  pin instantaneously shorted to ground can damage occur. A crowbar circuit at the power input can generate those levels of current and a diode from output to power input is then recommended. This is shown in Figure 6. Normal power supply cycling or system “hot-plugging and unplugging” will not do any damage.

A protection diode between the OUTPUT pin and the  $V_{CONTROL}$  pin is usually not needed. An internal diode between the OUTPUT pin and the  $V_{CONTROL}$  pin on the LT1581 can handle microsecond surge currents of 1A to 10A. This can only occur if the  $V_{CONTROL}$  pin is instantaneously shorted to ground with a crowbar circuit with large value output capacitors. Since the  $V_{CONTROL}$  pin is usually a low current supply, this condition is unlikely. A protection diode from the OUTPUT pin to the  $V_{CONTROL}$  pin is recommended if the  $V_{CONTROL}$  pin can be instantaneously shorted to ground. This is shown in Figure 6. Normal power supply cycling or system “hot-plugging and unplugging” will not do any damage.



**Figure 6. Optional Clamp Diodes Protect Against Input Crowbar Circuits**

If the LT1581 is connected as a single supply device with the control and power input pins shorted together, the internal diode between the output and the power input pins will protect the control input pin.

Like any other regulator exceeding the maximum input-to-output differential can cause the internal transistors to break down and none of the internal protection circuitry is then functional.

### Thermal Considerations

The LT1581 has internal current and thermal limiting designed to protect the device under overload conditions. For continuous normal load conditions maximum junction temperature ratings must not be exceeded. It is important to give careful consideration to all sources of thermal resistance from junction to ambient. This includes junction-to-case, case-to-heat sink interface and heat sink resistance itself. Thermal resistance specifications are given in the electrical characteristics for both the Control section and the Power section of the device. The thermal resistance of the Control section is given as 0.65°C/W and junction temperature of the Control section is allowed to run at up to 125°C. The thermal resistance of the Power section is given as 2.5°C/W and the junction temperature of the Power section is allowed to run at up to 150°C. The difference in thermal resistances between Control and Power sections is due to thermal gradients between the power transistor and the control circuitry.

Virtually all of the power dissipated by the device is dissipated in the power transistor. The temperature rise in the power transistor will be greater than the temperature rise in the Control section so the effective thermal resistance, temperature rise per watt dissipated, will be lower in the Control section. At power levels below 12W the temperature gradient will be less than 25°C and the maximum ambient temperature will be determined by the junction temperature of the Control section. This is due to the lower maximum junction temperature in the Control section. At power levels greater than 12W the temperature gradient will be greater than 25°C and the maximum ambient temperature will be determined by the Power section. For both cases the junction temperature is determined by the total power dissipated in the device. For most low dropout applications the power dissipation will be less than 12W.

The power in the device is made up of two main components: the power in the output transistor and the power in the drive circuit. The additional power in the control circuit is negligible.

The power in the drive circuit will be equal to:

$$P_{DRIVE} = (V_{CONTROL} - V_{OUT})(I_{CONTROL})$$

## APPLICATIONS INFORMATION

where  $I_{\text{CONTROL}}$  is equal to between  $I_{\text{OUT}}/100$  (typ) and  $I_{\text{OUT}}/58$  (max).

$I_{\text{CONTROL}}$  is a function of output current. A curve of  $I_{\text{CONTROL}}$  vs  $I_{\text{OUT}}$  can be found in the Typical Performance Characteristics curves.

The power in the output transistor is equal to:

$$P_{\text{OUTPUT}} = (V_{\text{POWER}} - V_{\text{OUT}})(I_{\text{OUT}})$$

The total power is equal to:

$$P_{\text{TOTAL}} = P_{\text{DRIVE}} + P_{\text{OUTPUT}}$$

Junction-to-case thermal resistance is specified from the IC junction to the bottom of the case directly below the die. This is the lowest resistance path for heat flow. Proper mounting is required to ensure the best possible thermal flow from this area of the package to the heat sink. Thermal compound at the case-to-heat sink interface is strongly recommended. If the case of the device must be electronically isolated, a thermally conductive spacer can be used as long as the added contribution to thermal resistance is considered. Please consult Linear Technology's "Mounting Considerations for Power Semiconductors," 1990 *Linear Applications Handbook, Volume 1*, Pages RR3-1 to RR3-20. Note that the case of the LT1581 is electrically connected to the output.

The following example illustrates how to calculate maximum junction temperature. Using an LT1581 and assuming:

$$\begin{aligned} V_{\text{CONTROL}} \text{ (max continuous)} &= 5.25\text{V} \text{ (5V + 5\%)}, \\ V_{\text{POWER}} \text{ (max continuous)} &= 3.465\text{V} \text{ (3.3V + 5\%)}, \\ V_{\text{OUT}} &= 2.5\text{V}, I_{\text{OUT}} = 4\text{A}, \\ T_{\text{A}} &= 70^{\circ}\text{C}, \theta_{\text{HEATSINK}} = 4^{\circ}\text{C/W}, \\ \theta_{\text{CASE-HEATSINK}} &= 1^{\circ}\text{C/W} \text{ (with thermal compound)} \end{aligned}$$

Power dissipation under these conditions is equal to:

$$\text{Total Power Dissipation} = P_{\text{DRIVE}} + P_{\text{OUTPUT}}$$

$$P_{\text{DRIVE}} = (V_{\text{CONTROL}} - V_{\text{OUT}})(I_{\text{CONTROL}})$$

$$I_{\text{CONTROL}} = I_{\text{OUT}}/58 = 4\text{A}/58 = 69\text{mA}$$

$$P_{\text{DRIVE}} = (5.25\text{V} - 2.5\text{V})(69\text{mA}) = 190\text{mW}$$

$$P_{\text{OUTPUT}} = (V_{\text{POWER}} - V_{\text{OUT}})(I_{\text{OUT}})$$

$$= (3.465\text{V} - 2.5\text{V})(4\text{A}) = 3.9\text{W}$$

$$\text{Total Power Dissipation} = 4.09\text{W}$$

Junction temperature will be equal to:

$$T_{\text{J}} = T_{\text{A}} + P_{\text{TOTAL}} (\theta_{\text{HEATSINK}} + \theta_{\text{CASE-HEATSINK}} + \theta_{\text{JC}})$$

For the Control section:

$$T_{\text{J}} = 70^{\circ}\text{C} + 4.09\text{W}(4^{\circ}\text{C/W} + 1^{\circ}\text{C/W} + 0.65^{\circ}\text{C/W}) = 93^{\circ}\text{C}$$

$$93^{\circ}\text{C} < 125^{\circ}\text{C} = T_{\text{JMAX}} \text{ for Control Section}$$

For the Power section:

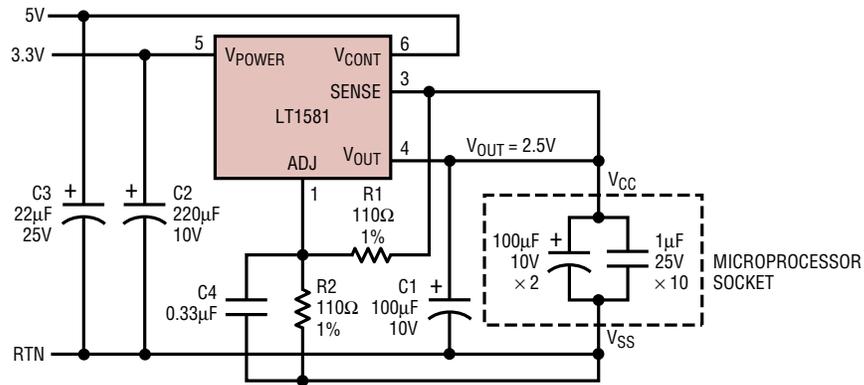
$$T_{\text{J}} = 70^{\circ}\text{C} + 4.09\text{W}(4^{\circ}\text{C/W} + 1^{\circ}\text{C/W} + 2.5^{\circ}\text{C/W}) = 101^{\circ}\text{C}$$

$$101^{\circ}\text{C} < 150^{\circ}\text{C} = T_{\text{JMAX}} \text{ for Power Section}$$

In both cases the junction temperature is below the maximum rating for the respective sections, ensuring reliable operation.

# TYPICAL APPLICATION

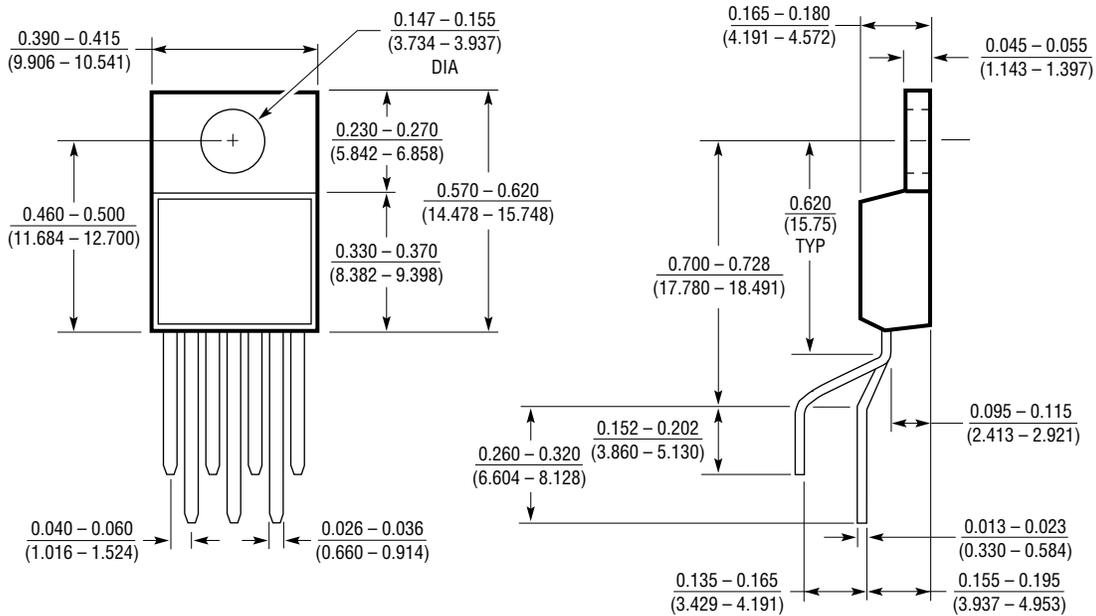
## 2.5V/10A Regulator



1581 TA03

# PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

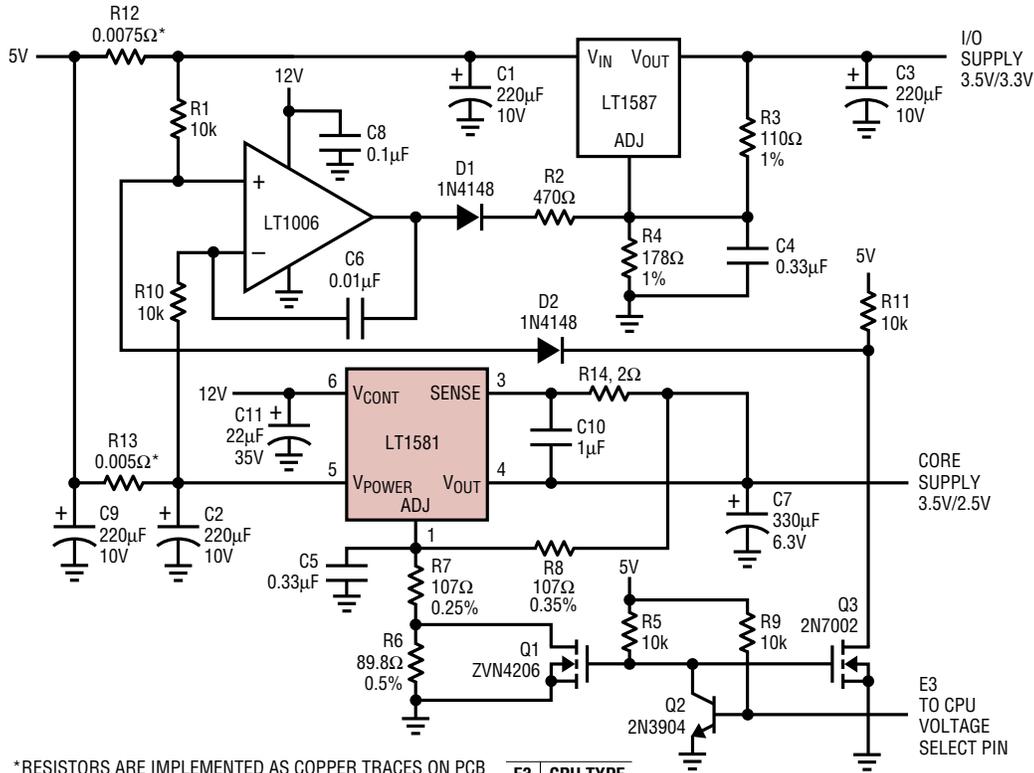
## T7 Package 7-Lead Plastic TO-220 (Standard) (LTC DWG # 05-08-1422)



T7 (TO-220) (FORMED) 1197

## TYPICAL APPLICATION

### Dual Regulators Power Pentium Processor or Upgrade CPU



\*RESISTORS ARE IMPLEMENTED AS COPPER TRACES ON PCB  
 IF 1 OZ COPPER, TRACE WIDTHS ARE 0.05 INCH  
 IF 2 OZ COPPER, TRACE WIDTHS ARE 0.025 INCH  
 R13 IS 0.83 INCHES LONG, R12 IS 1.24 INCHES LONG

E3	CPU TYPE
0	P55C
1	P54C

1581 TA04

## RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC <sup>®</sup> 1430	High Power Synchronous Step-Down Switching Regulator	>90% Efficiency High Current Microprocessor Supply
LTC1435	High Current Synchronous Step-Down Controller	>90% Efficiency in 12V to 3.3V Applications
LT1575/LT1577	Single and Dual Low Dropout Regulator Controllers	Fast Transient Response, No Bulk Capacitors Needed
LT1580	7A Fast Transient Response Regulator with 0.7V Dropout	For 3.3V to 2.XXV Applications
LT1584	7A Low Dropout Fast Transient Response Regulator	For High Performance Microprocessors
LT1585	4.6A Low Dropout Fast Transient Response Regulator	For High Performance Microprocessors