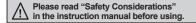
# Shaft Type Ø30mm Incremental Rotary Encoder

### Features

- Ø30mm of miniature shaft type rotary encoder
- Easy installation at narrow space
- Low moment of inertia
- Power supply: 5VDC, 12-24VDC ±5%
- Various output types



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SENSORS

MOTION DEVICES

SOFTWARE

# Ordering Information

E30S	4 -	<b>3000</b> –	- 3 -	- <b>N</b> -	<b>- 24 -</b>	-
Series	Shaft diameter	Pulses/revolution	Output phase	Control output	Power supply	Cable
Ø30mm, shaft type	Ø4mm	100, 200, 360, 500, 1000, 1024, 3000	3: A, B, Z 6: A, Ā, B, B̄, Z, Z̄	T: Totem pole output N: NPN open collector output V: Voltage output L: Line driver output (※)		No mark : axial cable type C: axial cable connector type

XThe power of Line driver is only for 5VDC.

# Specifications

Item			Shaft type Ø30mm Incremental Rotary Encoder			
Resolution (PPR) <sup>*1</sup>			100, 200, 360, 500, 1000, 1024, 3000			
	Output phase		A, B, Z phase (line driver: A, $\overline{A}$ , B, $\overline{B}$ , Z, $\overline{Z}$ phase)			
ctrical specification	Phase difference of output		Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)			
	Control	Totem pole output	[Low] - Load current: max. 30mA, residual voltage: max. 0.4VDC::     [High] - Load current: max. 10mA,			
		NPN open collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC==			
		Voltage output	Load current: max. 10mA, residual voltage: max. 0.4VDC==			
		Line driver output	• [Low] - Load current: max. 20mA, residual voltage: max. 0.5VDC== • [High] - Load current: max20mA, output voltage: min. 2.5VDC==			
		Totem pole output	Max. 1μs (cable length: 2m, I sink = 20mA)			
	time	NPN open collector output				
		Voltage output	Max. 1μs (5VDC: output resistance 820Ω), Max. 2μs (12-24VDC: output resistance 4.7kΩ) (cable length: 2m, I sink = 20mA)			
		Line driver output	Max. 0.5μs (cable length: 2m, I sink = 20mA)			
	Max. response frequency		300kHz			
	Power supply		• 5VDC== ±5% (ripple P-P: max. 5%) • 12-24VDC== ±5% (ripple P-P: max. 5%)			
	Current consumption		Max. 80mA (disconnection of the load), Line driver output: max. 50mA (disconnection of the load)			
	Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)			
	Dielectric s	trength	750VAC 50/60Hz for 1 minute (between all terminals and case)			
	Connection		Axial cable type, axial cable connector type			
ion	Starting tor	que	Max. 20gf·cm (0.002N·m)			
ani	Starting torque  Moment of inertia  Shaft loading		Max. 20g·cm² (2×10 <sup>-6</sup> kg·m²)			
ਤੂੰ ਤੂੰ Shaft loading		ng	Radial: max. 2kgf, Thrust: max. 1kgf			
Max. allowable revolution *2		able revolution <sup>×2</sup>	5,000rpm			
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock			Approx. max. 50G			
Env	ironment	Ambient temperature	-10 to 70°C, storage: -25 to 85°C			
LIIV		Ambient humidity	35 to 85%RH, storage: 35 to 90%RH			
Protection structure		ture	IP50 (IEC standard)			
Cable			Ø5mm, 5-wire (line driver: 8-wire), 2m, Shield cable (AWG24, core diameter: Ø.08mm, number of cores: 40, insulator out diameter: Ø1mm)			
Accessory			Ø4mm coupling			
Approval			C € (except line driver output)			
Unit	Unit weight		Approx. 80g			
V-Z 4 -	N. C. P. C	d recolutions are quetemiz	able WEnvironment registered is reted at no freezing or condensation			

<sup>X1: Not indicated resolutions are customizable.</sup> 

[Max. response revolution (rpm)=  $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}]$ 

Autonics H-21

(A) Photoelectric Sensors (B) Fiber Optic Sensors

Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

ressure

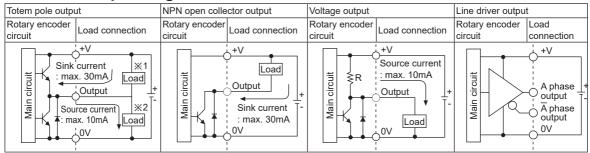
H) totary

Connectors/ Connector Cables. Sensor Distributio Boxes/ Sockets

<sup>\*</sup>Environment resistance is rated at no freezing or condensation.

<sup>\*2:</sup> Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

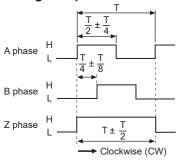
# **■** Control Output Diagram



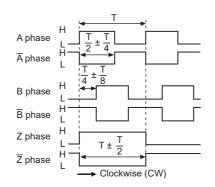
- The output circuit of A, B, Z phase are same. (line driver output is A, A, B, B, Z, Z)
- Totem pole output type can be used for NPN open collector output type (×1) or Voltage output type (×2).

## Output Waveform

Totem pole output / NPN open collector output / Voltage output



# Line driver output

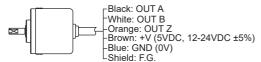




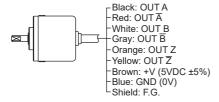
## Connections

#### Axial cable type

 Totem pole output / NPN open collector output / Voltage output



• Line driver output



#### Axial cable connector type





	en collector	output	Line driver output		
Voltage of		output	Line anver eacher		
Pin No.	Function	Cable color	Pin No.	Function	Cable color
1	OUT A	Black	1	OUT A	Black
2	OUT B	White	2	OUT Ā	Red
3	OUT Z	Orange	3	+V	Brown
4	+V	Brown	4	GND	Blue
(5)	GND	Blue	(5)	OUT B	White
6	F.G.	Shield	6	OUT B	Gray
			7	OUT Z	Orange
—			8	OUT Z	Yellow
			9	F.G.	Shield

XF.G. (field ground): It should be grounded separately.

XUnused wires must be insulated.

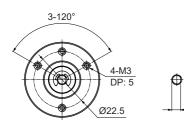
<sup>\*\*</sup>The metal case and shield wire of encoder should be grounded (F.G.).

<sup>%</sup>Do not apply tensile strength over 30N to the cable.

# Incremental Ø30mm Shaft type

## Dimensions

## Axial cable type



 CONTROLLERS

MOTION DEVICES

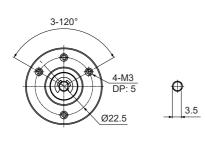
SOFTWARE

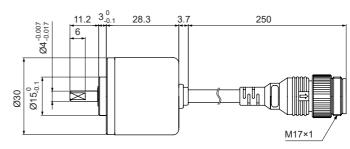
(unit: mm)

Cable for axial cable type

Ø5, 5-wire (line driver output: 8-wire), 2m, Shield cable

# O Axial cable connector type



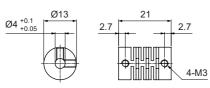


Cable for axial cable connector type

Ø5, 5-wire (line driver output: 8-wire), 250mm, Shield cable

\*\*Connector cable is sold separately and refer to the 'Connectors, Connector Cables, Sensor Distribution Boxes, Sockets' section.

# © Coupling (E30S)



- Parallel misalignment: max. 0.25mm
- Angular misalignment: max. 5°
- End-play: max. 0.5mm

XIt must not use larger shaft loading than specification.

XDo not put strong impact when insert a coupling into shaft.

Failure to follow this instruction may result in product damage.

※Fix the unit or a coupling by a wrench under 0.15N·m of torque.

\*When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.

\*\*For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.

\*For flexible coupling (ERB series) information, refer to the ERB series section.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

> Proximity Sensors

> > G) Pressure Sensors

H) totary incoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

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