

Single-Supply, Low Power, Precision FET Input Quad Buffer

Data Sheet

FEATURES

Low power

250 µA maximum supply current per amplifier **FET input** 2 pA maximum input bias current at 25°C **Extremely high input impedance** Low noise 13 nV/√Hz voltage noise at 1 kHz 0.4 µV p-p voltage noise (0.1 Hz to 10 Hz) 0.8 fA/√Hz current noise at 1 kHz **High dc precision** 3 µV/°C maximum offset drift (B grade) 3 MHz bandwidth **Unique pinout** No leakage from inputs to supply pins **Provides guarding capability Rail-to-rail output** Single-supply operation Input range extends to ground Wide supply range Single-supply: 3 V to 36 V Dual-supply: ±1.5 V to ±18 V Available in a compact 10-lead MSOP **APPLICATIONS**

Biopotential electrodes Medical instrumentation High impedance sensor conditioning Filters Photodiode amplifiers

GENERAL DESCRIPTION

The AD8244 is a precision, low power, FET input, quad unity-gain buffer that is designed to isolate very large source impedances from the rest of the signal chain. The 2 pA maximum bias current, near zero current noise, and 10 T Ω input impedance introduce almost no error, even with source impedance well into the megaohms.

Many traditional operational amplifier pinouts have a supply pin that is next to the noninverting input. A guard trace must be routed between these pins to avoid leakage currents much larger than the bias current of a FET input op amp. Guard traces can be routed between pins for large packages, such as DIP or even SOIC; however, the board area consumed by these packages is prohibitive for many modern applications. The AD8244 solves this problem with a unique pinout that physically separates the

Rev. A

Document Feedback

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AD8244

PIN CONFIGURATION



Figure 1. Pinout Isolates Inputs from Low-Impedance Leakage Sources



Figure 2. 0.1 Hz to 10 Hz Voltage Noise

high impedance inputs from the low impedance supplies and outputs of the other buffers. This configuration simplifies guarding while reducing board space, allowing high performance and high density in the same design.

The AD8244 design is focused on solving problems specific to buffers. This includes close channel-to-channel matching which allows channels of the AD8244 to be used in differential signal chains with minimal error. With its low voltage noise, wide supply range, and high precision, the AD8244 is also flexible enough to provide high performance anywhere a unity-gain buffer is needed, even with low source resistance.

The AD8244 is specified over the industrial temperature range of -40° C to $+85^{\circ}$ C. It is available in a 10-lead MSOP package.

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REVISION HISTORY

12/14—Rev. 0 to Rev. A

| Added Figure 1 Caption and Changes to Figure 2 1 |
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| Changes to Low Output Impedance vs. Frequency Section 15 |
| Changes to Electrocardiogram (ECG) Section, Filtering Section, |
| Figure 42, and Figure 43 16 |
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SPECIFICATIONS

 $+V_S = 5 V$, $-V_S = 0 V$, $T_A = 25^{\circ}C$, $V_{IN} = 0.2 V$, $R_L = 10 k\Omega$ to ground, unless otherwise noted.

Table 1.

| | | AD8244A | | | AD8244B | | | |
|----------------------------------|--|---------|-------|------|---------|-------|-------|--------|
| Parameter | Test Conditions/Comments | Min | Тур | Max | Min | Тур | Мах | Unit |
| DC PERFORMANCE | | | | | | | | |
| Offset Voltage | | | 100 | 600 | | 100 | 350 | μV |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | | | 1.25 | | | 0.675 | mV |
| Average Temperature Coefficient | $T_{\rm A} = -40^{\circ}$ C to +85°C | | | 10 | | | 5 | μV/°C |
| Offset Voltage Matching | Channel to channel | | | 800 | | | 500 | μV |
| Input Bias Current | | | 0.5 | 10 | | 0.5 | 2 | pА |
| Over Temperature | $T_A = 85^{\circ}C$ | | | 150 | | | 50 | pА |
| Input Bias Current Matching | Channel to channel | | 0.05 | | | 0.05 | 0.2 | pА |
| Over Temperature | $T_A = 85^{\circ}C$ | | 2 | | | 2 | | pА |
| SYSTEM PERFORMANCE | | | | | | | | |
| Nominal Gain | | | 1 | | | 1 | | V/V |
| System Error ¹ | $V_{OUT} = 0.2 V \text{ to } 3 V$ | | | 0.08 | | | 0.05 | % |
| Average Temperature Coefficient | $T_{\rm A} = -40^{\circ}$ C to +85°C | | | 2 | | | 1 | ppm/°C |
| Gain Matching | Channel to channel | | | 0.10 | | | 0.08 | % |
| NOISE PERFORMANCE | | | | | | | | |
| Voltage Noise | | | | | | | | |
| Spectral Density | f = 1 kHz | | 13 | | | 13 | | nV/√Hz |
| Peak-to-Peak | f = 0.1 Hz to 10 Hz | | 0.4 | | | 0.4 | 2 | μV p-p |
| Current Noise | | | | | | | | |
| Spectral Density | f = 1 kHz | | 0.8 | | | 0.8 | | fA/√Hz |
| Peak-to-Peak | f = 0.1 Hz to 10 Hz | | 8 | | | 8 | | fA p-p |
| DYNAMIC PERFORMANCE | | | | | | | | |
| Small Signal Bandwidth | -3 dB | | 3 | | | 3 | | MHz |
| Slew Rate | | | 0.8 | | | 0.8 | | V/µs |
| Settling Time to 0.01% | $V_{OUT} = 0.2 V \text{ to } 3 V$ | | 8 | | | 8 | | μs |
| INPUT CHARACTERISTICS | | | | | | | | |
| Input Voltage Range ² | | 0 | | 4 | 0 | | 4 | V |
| Over Temperature | $T_{\rm A} = -40^{\circ}$ C to +85°C | 0 | | 3.5 | 0 | | 3.5 | V |
| Input Impedance ³ | | | 10 4 | | | 10 4 | | TΩ pF |
| OUTPUT CHARACTERISTICS | | | | | | | | |
| Output Swing | $R_{L} = 10 \text{ k}\Omega$ to ground | 0.025 | | 4.9 | 0.025 | | 4.9 | v |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | 0.03 | | 4.88 | 0.03 | | 4.88 | V |
| Output Swing | R∟ = no load | 0.025 | | 4.97 | 0.025 | | 4.97 | v |
| Over Temperature | $T_{\rm A} = -40^{\circ}$ C to +85°C | 0.03 | | 4.95 | 0.03 | | 4.95 | V |
| Short-Circuit Current | | | 8 | | | 8 | | mA |
| Capacitive Load Drive | | | 200 | | | 200 | | pF |
| POWER SUPPLY | | | | | | | | |
| Operating Range | Single supply | 3 | | 36 | 3 | | 36 | v |
| | Dual supply | ±1.5 | | ±18 | ±1.5 | | ±18 | v |
| Power Supply Rejection | $V_{IN} = 2.5 V, +V_s = 4.5 V \text{ to } 5.5 V$ | | 80 | | | 80 | | dB |
| Supply Current per Amplifier | $I_{OUT} = 0 \text{ mA}$ | | 180 | 250 | | 180 | 250 | μA |
| Over Temperature | $T_A = -40^{\circ}$ C to +85°C | | | 300 | | | 300 | μA |
| TEMPERATURE RANGE | | | | | 1 | | | † · |
| Specified Performance | | -40 | | +85 | -40 | | +85 | °C |

¹ Error as a percentage of the measurement. This includes the effects of open-loop gain and common-mode rejection ratio.
 ² The inputs of the AD8244 can go up to the positive supply; however, the input range is derated because error increases near the positive supply as the input transistors start to saturate. The inputs also maintain high impedance when driven slightly below ground.
 ³ For more information on the input impedance, see Figure 24 and Figure 37.

$V_{\text{S}}=\pm5$ V, $T_{\text{A}}=25^{\text{o}}\text{C}$, $V_{\text{IN}}=0$ V, $R_{\text{L}}=10$ kΩ, unless otherwise noted.

Table 2.

| | | | AD8244 | 4 | / | D8244 | 3 | |
|----------------------------------|---|--------|--------|-------|--------|-------|-------|--------|
| Parameter | Test Conditions/Comments | Min | Тур | Мах | Min | Тур | Max | Unit |
| DC PERFORMANCE | | | | | | | | |
| Offset Voltage | | | 100 | 600 | | 100 | 350 | μV |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | | | 1.25 | | | 0.675 | mV |
| Average Temperature Coefficient | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | | | 10 | | | 5 | μV/°C |
| Offset Voltage Matching | Channel to channel | | | 800 | | | 500 | μV |
| Input Bias Current | | | 0.5 | 10 | | 0.5 | 2 | рΑ |
| Over Temperature | $T_A = 85^{\circ}C$ | | | 150 | | | 50 | pА |
| Input Bias Current Matching | Channel to channel | | 0.05 | | | 0.05 | 0.2 | рА |
| Over Temperature | $T_A = 85^{\circ}C$ | | 2 | | | 2 | | pА |
| SYSTEM PERFORMANCE | | | | | | | | |
| Nominal Gain | | | 1 | | | 1 | | V/V |
| System Error ¹ | $V_{OUT} = -3 V \text{ to } +3 V$ | | | 0.05 | | | 0.03 | % |
| Average Temperature Coefficient | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | | | 2 | | | 1 | ppm/°C |
| Gain Matching | Channel to channel | | | 0.08 | | | 0.05 | % |
| Nonlinearity | $V_{OUT} = -3 V \text{ to } +3 V$ | | 20 | | | 20 | | ppm |
| NOISE PERFORMANCE | | | | | | | | |
| Voltage Noise | | | | | | | | |
| Spectral Density | f = 1 kHz | | 13 | | | 13 | | nV/√Hz |
| Peak-to-Peak | f = 0.1 Hz to 10 Hz | | 0.4 | | | 0.4 | 2 | μV р-р |
| Current Noise | | | | | | | | |
| Spectral Density | f = 1 kHz | | 0.8 | | | 0.8 | | fA/√Hz |
| Peak-to-Peak | f = 0.1 Hz to 10 Hz | | 8 | | | 8 | | fA p-p |
| DYNAMIC PERFORMANCE | | | | | | | | |
| Small Signal Bandwidth | -3 dB | | 3.3 | | | 3.3 | | MHz |
| Slew Rate | | | 0.8 | | | 0.8 | | V/µs |
| Settling Time to 0.01% | $V_{OUT} = -3 V \text{ to } +3 V$ | | 14 | | | 14 | | μs |
| INPUT CHARACTERISTICS | | | | | | | | |
| Input Voltage Range ² | | -5 | | +4 | -5 | | +4 | V |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | -5 | | +3.5 | -5 | | +3.5 | V |
| Input Impedance ³ | | | 10 4 | | | 10 4 | | TΩ∥pF |
| OUTPUT CHARACTERISTICS | | | | | | | | |
| Output Swing | $R_L = 10 \ k\Omega$ | -4.9 | | +4.9 | -4.9 | | +4.9 | V |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | -4.88 | | +4.88 | -4.88 | | +4.88 | V |
| Output Swing | $R_L = no load$ | -4.975 | | +4.97 | -4.975 | | +4.97 | V |
| Over Temperature | $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ | -4.95 | | +4.95 | -4.95 | | +4.95 | V |
| Short-Circuit Current | | | 10 | | | 10 | | mA |
| Capacitive Load Drive | | | 200 | | | 200 | | рF |
| POWER SUPPLY | | | | | | | | |
| Operating Range | Single supply | 3 | | 36 | 3 | | 36 | v |
| | Dual supply | ±1.5 | | ±18 | ±1.5 | | ±18 | V |
| Power Supply Rejection | $V_s = \pm 3 V \text{ to } \pm 18 V$ | | 90 | | 80 | 90 | | dB |
| Supply Current per Amplifier | $I_{OUT} = 0 \text{ mA}$ | | 180 | 250 | | 180 | 250 | μA |
| Over Temperature | $T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ | | - | 300 | | - | 300 | μA |
| TEMPERATURE RANGE | | | | | | | | |
| Specified Performance | T _A | -40 | | +85 | -40 | | +85 | °C |

¹ Error as a percentage of the measurement. This includes the effects of open-loop gain and common-mode rejection ratio.

² The inputs of the AD8244 can go up to the positive supply; however, the input range is derated because error increases near the positive supply as the input transistors start to saturate.

³ For more information on the input impedance, see Figure 24 and Figure 37.

Data Sheet

 $V_{\text{S}}=\pm 15$ V, $T_{\text{A}}=25^{\circ}\text{C},$ V_{IN} = 0 V, R_{L} = 10 k $\Omega,$ unless otherwise noted.

Table 3.

| ParameterTest Conditions/CommentsMinDC PERFORMANCE $T_{A} = -40^{\circ}C$ to $+85^{\circ}C$ I_{A} Offset Voltage $T_{A} = -40^{\circ}C$ to $+85^{\circ}C$ I_{A} Over Temperature Coefficient $T_{A} = -40^{\circ}C$ to $+85^{\circ}C$ I_{A} Offset Voltage MatchingChannel to channel I_{A} Input Bias Current $T_{A} = 85^{\circ}C$ I_{A} Over Temperature $T_{A} = 85^{\circ}C$ $I_{A} = 85^{\circ}C$ Input Bias Current MatchingChannel to channel $I_{A} = 85^{\circ}C$ Over Temperature $T_{A} = -40^{\circ}C$ to $+85^{\circ}C$ $I_{A} = 85^{\circ}C$ SYSTEM PERFORMANCE $I_{A} = -40^{\circ}C$ to $+85^{\circ}C$ $I_{A} = 40^{\circ}C$ to $+85^{\circ}C$ Nominal Gain $I_{A} = -40^{\circ}C$ to $+85^{\circ}C$ $I_{A} = 40^{\circ}C$ to $+85^{\circ}C$ System Error ¹ $V_{OUT} = -10$ V to $+10$ V $I_{A} = 40^{\circ}C$ to $+85^{\circ}C$ Nolise PERFORMANCE $I_{A} = -40^{\circ}C$ to $+85^{\circ}C$ $I_{A} = 40^{\circ}C$ to $+85^{\circ}C$ Voltage Noise $I_{A} = 1$ kHz $I_{A} = 40^{\circ}C$ to $+10$ VNOISE PERFORMANCE $I_{A} = 1$ kHz $I_{A} = 1$ kHzVoltage Noise $I_{A} = 1$ kHz $I_{A} = 1$ kHzSpectral Density $I_{A} = 1$ kHz $I_{A} = 1$ kHzPeak-to-Peak $I_{A} = 1$ kHz $I_{A} = 1$ kHzPeak-to-Peak $I_{A} = 1$ kHz $I_{A} = 1$ kHzSmall Signal Bandwidth -3 dB $I_{A} = 1$ kHzShew Rate $I_{A} = -40^{\circ}C$ to $+85^{\circ}C$ -15 NPUT CHARACTERISTICS $I_{A} = -40^{\circ}C$ to $+85^{\circ}C$ -15 Input Voltage Range ² | Typ 100 0.9 0.05 2 1 1 5 13 | Max 600 1.25 10 800 10 150 0.03 2 0.05 | Min | Typ 100 0.9 0.05 2 1 | Max 350 0.545 3 500 3 100 0.2 0.008 1 | Unit μV mV μV/°C μV pA pA pA pA v/v |
|---|------------------------------------|---|--------|--|--|---|
| Offset Voltage $T_A = -40^{\circ}$ C to $+85^{\circ}$ COver Temperature $T_A = -40^{\circ}$ C to $+85^{\circ}$ CAverage Temperature Coefficient $T_A = -40^{\circ}$ C to $+85^{\circ}$ COffset Voltage MatchingChannel to channelInput Bias Current $T_A = 85^{\circ}$ COver Temperature $T_A = 85^{\circ}$ CInput Bias Current MatchingChannel to channelOver Temperature $T_A = 85^{\circ}$ CSYSTEM PERFORMANCE $T_A = -40^{\circ}$ C to $+85^{\circ}$ CNominal Gain $T_A = -40^{\circ}$ C to $+85^{\circ}$ CSystem Error ¹ Vout = -10 V to $+10$ VAverage Temperature Coefficient $T_A = -40^{\circ}$ C to $+85^{\circ}$ CGain MatchingChannel to channelNonlinearityVout = -10 V to $+10$ VNOISE PERFORMANCE $F = 1$ kHzVoltage Noise $F = 1$ kHzSpectral Density $f = 1$ kHzPeak-to-Peak $f = 0.1$ Hz to 10 HzCurrent Noise $F = 1$ kHzSpectral Density $f = 1$ kHzPeak-to-Peak $f = 0.1$ Hz to 10 HzDYNAMIC PERFORMANCE $F = 1$ kHzSmall Signal Bandwidth -3 dBSlew Rate $Settling Time to 0.01\%$ NPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}$ C to $+85^{\circ}$ CInput Impedance ³ -15 | 0.9 0.05 2 1 5 13 | 1.25 10 800 10 150 0.03 2 | | 0.9 0.05 2 | 0.545 3 500 3 100 0.2 | mV μV/°C μV pA pA pA pA V/V |
| Over Temperature $T_A = -40^\circ$ C to $+85^\circ$ CAverage Temperature Coefficient $T_A = -40^\circ$ C to $+85^\circ$ COffset Voltage MatchingChannel to channelInput Bias Current $T_A = 85^\circ$ CInput Bias Current MatchingChannel to channelOver Temperature $T_A = 85^\circ$ CSYSTEM PERFORMANCE $V_{OUT} = -10 V to +10 V$ Nominal Gain $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^\circ$ C to $+85^\circ$ CGain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ Current Noise $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ DYNAMIC PERFORMANCE $Spectral Density$ System Rate -3 dB Slew Rate $Settling Time to 0.01\%$ NPUT CHARACTERISTICS -15 Input Voltage Range2 -15 Over Temperature $T_A = -40^\circ$ C to $+85^\circ$ C | 0.9 0.05 2 1 5 13 | 1.25 10 800 10 150 0.03 2 | | 0.9 0.05 2 | 0.545 3 500 3 100 0.2 | mV μV/°C μV pA pA pA pA V/V |
| Average Temperature Coefficient Offset Voltage Matching Input Bias Current Over Temperature $T_A = -40^\circ$ C to $+85^\circ$ C Channel to channelInput Bias Current Matching Over Temperature $T_A = 85^\circ$ CInput Bias Current Matching Over TemperatureChannel to channelOver Temperature $T_A = 85^\circ$ CSYSTEM PERFORMANCE Nominal Gain $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient Gain Matching $T_A = -40^\circ$ C to $+85^\circ$ CGain Matching NonlinearityChannel to channel Vour = $-10 V to +10 V$ NOISE PERFORMANCE Voltage Noise $F = 1 \text{ kHz}$ $F = 0.1 \text{ Hz} to 10 \text{ Hz}$ Spectral Density Peak-to-Peak $f = 1 \text{ kHz}$ $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ DYNAMIC PERFORMANCE Small Signal Bandwidth Slew Rate Settling Time to 0.01% -3 dB Slew Rate Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS Input Voltage Range2 Over Temperature -15 -15 Input Impedance3 $T_A = -40^\circ$ C to $+85^\circ$ C | 0.05 2 1 5 | 10 800 10 150 0.03 2 | | 0.05 2 | 3 500 3 100 0.2 | μV/°C μV pA pA pA pA V/V |
| Offset Voltage Matching Input Bias CurrentChannel to channelOver Temperature $T_A = 85^{\circ}C$ Input Bias Current Matching Over TemperatureChannel to channelOver Temperature $T_A = 85^{\circ}C$ SYSTEM PERFORMANCE $V_{OUT} = -10 V to +10 V$ Nominal Gain $T_A = -40^{\circ}C to +85^{\circ}C$ System Error ¹ $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Current Noise $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Shew Rate -15 Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ Over Temperature $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ | 0.05 2 1 5 | 800 10 150 0.03 2 | | 0.05 2 | 500 3 100 0.2 | μV pA pA pA pA V/V |
| Input Bias Current $T_A = 85^{\circ}C$ Input Bias Current Matching $T_A = 85^{\circ}C$ Input Bias Current Matching $T_A = 85^{\circ}C$ Input Bias Current MatchingInput Bias Current MatchingOver Temperature $T_A = 85^{\circ}C$ Input Bias Current MatchingInput Bias Current MatchingSystem Error1 $V_{OUT} = -10 V to +10 V$ Input Bias Current PersonAverage Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Input Bias Current Not PersonGain MatchingChannel to channelVout = -10 V to +10 VNOISE PERFORMANCEVout = -10 V to +10 VInput Spectral DensityVoltage Noisef = 1 kHzFeak-to-PeakSpectral Densityf = 1 kHzFeak-to -10 V to +10 VDYNAMIC PERFORMANCEFeak-to -PeakFe 0.1 Hz to 10 HzDYNAMIC PERFORMANCESmall Signal Bandwidth $-3 dB$ Slew RateSettling Time to 0.01%Vout = -10 V to +10 VINPUT CHARACTERISTICS -15 -15 Input Voltage Range2 -15 Over Temperature $T_A = -40^{\circ}C$ to $+85^{\circ}C$ Input Impedance3Ta = -40^{\circ}C to $+85^{\circ}C$ | 0.05 2 1 5 | 10 150 0.03 2 | | 0.05 2 | 3 100 0.2 0.008 | pA pA pA pA V/V |
| Over Temperature $T_A = 85^{\circ}C$ Input Bias Current MatchingChannel to channelOver Temperature $T_A = 85^{\circ}C$ SYSTEM PERFORMANCE $V_{OUT} = -10 V to +10 V$ Nominal Gain $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 kHz$ Spectral Density $f = 0.1 Hz to 10 Hz$ Current Noise $f = 0.1 Hz to 10 Hz$ Spectral Density $f = 0.1 Hz to 10 Hz$ DYNAMIC PERFORMANCE $-3 dB$ Silew Rate $-3 dB$ Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}C to +85^{\circ}C$ Input Impedance ³ -15 | 0.05 2 1 5 | 150 0.03 2 | | 0.05 2 | 100 0.2 0.008 | pA pA pA V/V |
| Input Bias Current Matching Over TemperatureChannel to channel $T_A = 85^{\circ}C$ SYSTEM PERFORMANCE Nominal Gain System Error1VOUT = -10 V to +10 V T_A = -40^{\circ}C to +85^{\circ}CGain Matching NonlinearityChannel to channel Channel to channel VOUT = -10 V to +10 VNOISE PERFORMANCE Voltage NoiseF = 1 kHz F = 0.1 Hz to 10 HzSpectral Density Peak-to-Peakf = 1 kHz f = 0.1 Hz to 10 HzDYNAMIC PERFORMANCE Spectral Densityf = 1 kHz f = 0.1 Hz to 10 HzDYNAMIC PERFORMANCE Steur and DensityJ = 1 kHz f = 0.1 Hz to 10 HzDYNAMIC PERFORMANCE Small Signal Bandwidth Slew Rate Settling Time to 0.01%-3 dBSteuting Time to 0.01%VOUT = -10 V to +10 VINPUT CHARACTERISTICS Input Voltage Range2-15 -15 -15Input Impedance3T_A = -40^{\circ}C to +85^{\circ}C | 2 1 5 13 | 0.03 2 | | 2 | 0.2 | pA pA V/V |
| Over Temperature $T_A = 85^{\circ}C$ SYSTEM PERFORMANCE $Nominal Gain$ Nominal Gain $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ Current Noise $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ DYNAMIC PERFORMANCE $F = 1 \text{ kHz}$ Small Signal Bandwidth -3 dB Slew Rate $Settling Time to 0.01\%$ INPUT CHARACTERISTICS $V_{OUT} = -10 V to +10 V$ Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}C to +85^{\circ}C$ Input Impedance ³ -15 | 2 1 5 13 | 2 | | 2 | 0.008 | pA V/V |
| SYSTEM PERFORMANCE Nominal Gain $V_{OUT} = -10 V to +10 V$ Nominal Gain $V_{OUT} = -10 V to +10 V$ System Error1 $V_{OUT} = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ VOISE PERFORMANCE $f = 1 \text{ kHz}$ Voltage Noise $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ Current Noise $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ DYNAMIC PERFORMANCE $f = 0.1 \text{ Hz} to 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Slew Rate $Settling Time to 0.01\%$ Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS Input Voltage Range2 -15 Over Temperature $T_A = -40^{\circ}C to +85^{\circ}C$ Input Impedance3 -15 | 1 5 13 | 2 | | | | V/V |
| Nominal Gain $V_{OUT} = -10 V to +10 V$ System Error1 $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 kHz$ Spectral Density $f = 0.1 Hz to 10 Hz$ Current Noise $f = 1 kHz$ Spectral Density $f = 1 kHz$ Peak-to-Peak $f = 0.1 Hz to 10 Hz$ Current Noise $-3 dB$ Spectral Density $-3 dB$ Slew Rate $-3 dB$ Slew Rate -15 NPUT CHARACTERISTICS -15 Input Voltage Range2 -15 Over Temperature $T_A = -40^{\circ}C to +85^{\circ}C$ Input Impedance3 -15 | 5 | 2 | | 1 | | - |
| System Error1 $V_{OUT} = -10 V to +10 V$ Average Temperature Coefficient $T_A = -40^{\circ}C to +85^{\circ}C$ Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 \text{ kHz}$ Spectral Density $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Current Noise $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Slew Rate -3 dB Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS -15 Input Voltage Range2 -15 Over Temperature $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ Input Impedance3 -15 | 5 | 2 | | 1 | | - |
| Average Temperature Coefficient Gain Matching $T_A = -40^\circ$ C to $+85^\circ$ C Channel to channelNonlinearity $V_{OUT} = -10 V$ to $+10 V$ NOISE PERFORMANCE Voltage Noise $F = 1 kHz$ f $= 0.1 Hz$ to $10 Hz$ Spectral Density $f = 1 kHz$ f $= 0.1 Hz$ to $10 Hz$ Current Noise Spectral Density $f = 1 kHz$ f $= 0.1 Hz$ to $10 Hz$ DYNAMIC PERFORMANCE Small Signal Bandwidth Slew Rate Settling Time to 0.01% $-3 dB$ Stelling Time to 0.01% $V_{OUT} = -10 V$ to $+10 V$ INPUT CHARACTERISTICS Input Voltage Range2 -15 -15 Input Impedance3 $T_A = -40^\circ$ C to $+85^\circ$ C | 13 | 2 | | | | % |
| Gain MatchingChannel to channelNonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 kHz$ Spectral Density $f = 1 kHz$ Peak-to-Peak $f = 0.1 Hz to 10 Hz$ Current Noise $f = 0.1 Hz to 10 Hz$ Spectral Density $f = 1 kHz$ Peak-to-Peak $f = 0.1 Hz to 10 Hz$ DYNAMIC PERFORMANCE $f = 0.1 Hz to 10 Hz$ Small Signal Bandwidth $-3 dB$ Slew Rate $-3 dB$ Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}$ C to $+85^{\circ}$ CInput Impedance ³ -15 | 13 | | | | 1 | |
| Nonlinearity $V_{OUT} = -10 V to +10 V$ NOISE PERFORMANCE $V_{OUT} = -10 V to +10 V$ Voltage Noise $f = 1 kHz$ Spectral Density $f = 1 kHz$ Peak-to-Peak $f = 0.1 Hz to 10 Hz$ Current Noise $f = 1 kHz$ Spectral Density $f = 1 kHz$ Peak-to-Peak $f = 0.1 Hz to 10 Hz$ DYNAMIC PERFORMANCE $f = 0.1 Hz to 10 Hz$ Small Signal Bandwidth $-3 dB$ Slew Rate $-3 dB$ Settling Time to 0.01% $V_{OUT} = -10 V to +10 V$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}C to +85^{\circ}C$ Input Impedance ³ $-10 V to +10 V$ | 13 | 0.05 | | | • | ppm/°C |
| NOISE PERFORMANCE Voltage Noisef = 1 kHzSpectral Densityf = 1 kHzPeak-to-Peakf = 0.1 Hz to 10 HzCurrent Noise Spectral Densityf = 1 kHzPeak-to-Peakf = 0.1 Hz to 10 HzDYNAMIC PERFORMANCEf = 0.1 Hz to 10 HzSmall Signal Bandwidth Slew Rate Settling Time to 0.01% $-3 dB$ INPUT CHARACTERISTICS Input Voltage Range2 -15 Over Temperature Input Impedance3TA = -40°C to +85°C | 13 | | | | 0.01 | % |
| Voltage Noise $f = 1 \text{ kHz}$ $f = 0.1 \text{ Hz}$ Spectral Density $f = 0.1 \text{ Hz}$ to 10 Hz I Peak-to-Peak $f = 0.1 \text{ Hz}$ to 10 Hz I Spectral Density $f = 1 \text{ kHz}$ I Peak-to-Peak $f = 0.1 \text{ Hz}$ to 10 Hz I DYNAMIC PERFORMANCE -3 dB I Signal Bandwidth -3 dB I Slew Rate I I Settling Time to 0.01% $V_{OUT} = -10 \text{ V to } +10 \text{ V}$ I INPUT CHARACTERISTICS -15 -15 Input Voltage Range ² $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ -15 Input Impedance ³ I I | | | | 5 | | ppm |
| Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Current Noise $F = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE $F = 0.1 \text{ Hz to } 10 \text{ Hz}$ Small Signal Bandwidth -3 dB Slew Rate -3 dB Settling Time to 0.01% $V_{0UT} = -10 \text{ V to } +10 \text{ V}$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$ Input Impedance ³ -15 | | | | | | |
| Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Current Noise $f = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Small Signal Bandwidth -3 dB Slew Rate -3 dB Settling Time to 0.01% $V_{out} = -10 \text{ V to } +10 \text{ V}$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$ Input Impedance ³ -15 | | | | | | |
| Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ Current Noise $f = 1 \text{ kHz}$ Spectral Density $f = 1 \text{ kHz}$ Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Small Signal Bandwidth -3 dB Slew Rate -3 dB Settling Time to 0.01% $V_{OUT} = -10 \text{ V to } +10 \text{ V}$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$ Input Impedance ³ -15 | <u> </u> | | | 13 | | nV/√Hz |
| Spectral Density Peak-to-Peak $f = 1 \text{ kHz}$ $f = 0.1 \text{ Hz to 10 Hz}$ Image: form of the state of the sta | 0.4 | | | 0.4 | | μV р-р |
| Peak-to-Peak $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ DYNAMIC PERFORMANCE -3 dB Small Signal Bandwidth -3 dB Slew Rate -3 dB Settling Time to 0.01% $V_{OUT} = -10 \text{ V to } +10 \text{ V}$ INPUT CHARACTERISTICS -15 Input Voltage Range ² -15 Over Temperature $T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$ Input Impedance ³ -15 | | | | | | |
| $\begin{array}{c c} DYNAMIC PERFORMANCE & & & \\ Small Signal Bandwidth & -3 dB & & \\ Slew Rate & & & \\ Settling Time to 0.01\% & V_{OUT} = -10 V to +10 V & & \\ \hline INPUT CHARACTERISTICS & & & \\ Input Voltage Range^2 & & -15 & \\ Over Temperature & T_A = -40^\circ C to +85^\circ C & -15 & \\ Input Impedance^3 & & & \\ \end{array}$ | 0.8 | | | 0.8 | | fA/√Hz |
| $ \begin{array}{c} \mbox{Small Signal Bandwidth} & -3 \ dB & & \\ \mbox{Slew Rate} & & & \\ \mbox{Settling Time to 0.01\%} & & V_{OUT} = -10 \ V \ to + 10 \ V & \\ \mbox{INPUT CHARACTERISTICS} & & & \\ \mbox{Input Voltage Range}^2 & & -15 & \\ \mbox{Over Temperature} & & T_A = -40^\circ \ C \ to + 85^\circ \ C & -15 & \\ \mbox{Input Impedance}^3 & & & \\ \end{array} $ | 8 | | | 8 | | fA p-p |
| $\begin{tabular}{ c c c c c } Slew Rate & & & & & & & & & & & & & & & & & & &$ | | | | | | |
| $\begin{tabular}{ c c c c c } Slew Rate & & & & & & & & & & & & & & & & & & &$ | 3.6 | | | 3.6 | | MHz |
| INPUT CHARACTERISTICS Input Voltage Range2 -15 Over Temperature Input Impedance3 $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ | 0.8 | | | 0.8 | | V/µs |
| Input Voltage Range2 -15 Over Temperature $T_A = -40^{\circ}C$ to $+85^{\circ}C$ -15 Input Impedance3 -15 | 18 | | | 18 | | μs |
| Over Temperature $T_A = -40^{\circ}C$ to $+85^{\circ}C$ -15 Input Impedance ³ -15 | | | | | | |
| Over Temperature $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ -15 Input Impedance ³ -15 | | +14 | -15 | | +14 | V |
| | | +13.5 | -15 | | +13.5 | V |
| | 10 4 | | | 10 4 | | TΩ pF |
| OUTPUT CHARACTERISTICS | | | | | | |
| Output Swing $R_L = 10 k\Omega$ -14.87 | | +14.87 | -14.87 | | +14.87 | V |
| Over Temperature $T_A = -40^{\circ}C \text{ to } +85^{\circ}C -14.84$ | | +14.84 | -14.84 | | +14.84 | V |
| Output Swing $R_L = no load$ -14.95 | | +14.95 | -14.95 | | +14.95 | V |
| Over Temperature $T_A = -40^{\circ}C$ to $+85^{\circ}C$ -14.93 | | +14.93 | -14.93 | | +14.93 | v |
| Short-Circuit Current | 20 | | | 20 | | mA |
| Capacitive Load Drive | 200 | | | 200 | | рF |
| POWER SUPPLY | | | 1 | | | 1 ²² |
| Operating Range Single supply 3 | | 36 | 3 | | 36 | v |
| Dual supply ±1.5 | | ±18 | ±1.5 | | ±18 | v |
| Power Supply Rejection $V_s = \pm 3 V \text{ to } \pm 18 V$ | 90 | | 80 | 90 | | dB |
| Supply Current per Amplifier $I_{OUT} = 0 \text{ mA}$ | 180 | 250 | | 180 | 250 | μA |
| Supply current per Ampliner $1001 - 0$ mixOver Temperature $T_A = -40^{\circ}C$ to $+85^{\circ}C$ | 100 | 300 | | 100 | 300 | μΑ |
| TEMPERATURE RANGE | | 500 | | | 500 | μ |
| Specified Performance T_A -40 | | +85 | -40 | | +85 | °C |

¹ Error as a percentage of the measurement. This includes the effects of open-loop gain and common-mode rejection ratio.

² The inputs of the AD8244 can go up to the positive supply; however, the input range is derated because error increases near the positive supply as the input transistors start to saturate.

³ For more information on the input impedance, see Figure 24 and Figure 37.

ABSOLUTE MAXIMUM RATINGS

Table 4.

| Parameter | Rating |
|---|------------------|
| Supply Voltage | ±18 V |
| Output Short-Circuit Current Duration | Indefinite |
| Maximum Voltage at IN x or OUT x ¹ | +Vs + 0.3 V |
| Minimum Voltage at IN x or OUT x ¹ | $-V_{s} - 0.3 V$ |
| Storage Temperature Range | -65°C to +150°C |
| Operating Temperature Range | -40°C to + 85°C |
| Maximum Junction Temperature | 150°C |
| ESD | |
| Human Body Model (HBM) | 3 kV |
| Charged Device Model (CDM) | 1.25 kV |
| Machine Model (MM) | 100 V |

¹ For voltages beyond these limits, use input protection resistors. See the Input Protection section for more information.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL RESISTANCE

 θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 5. Thermal Resistance

| Package Type | θ _{JA} | Unit |
|--------------|-----------------|------|
| 10-Lead MSOP | 152 | °C/W |

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



| Table 6. Pin Function Description | Table 6. | Pin | Function | Description |
|-----------------------------------|----------|-----|----------|-------------|
|-----------------------------------|----------|-----|----------|-------------|

| Pin Number | Mnemonic | Description |
|------------|----------|-------------------------|
| 1 | IN A | Channel A Input |
| 2 | OUT A | Channel A Output |
| 3 | +Vs | Positive Supply Voltage |
| 4 | OUT B | Channel B Output |
| 5 | IN B | Channel B Input |
| 6 | IN C | Channel C Input |
| 7 | OUT C | Channel C Output |
| 8 | $-V_S$ | Negative Supply Voltage |
| 9 | OUT D | Channel D Output |
| 10 | IN D | Channel D Input |

TYPICAL PERFORMANCE CHARACTERISTICS

 $V_{\text{S}}=\pm5$ V, $T_{\text{A}}=25^{\circ}\text{C},$ V_{IN} = 0 V, R_{L} = 10 k\Omega, unless otherwise noted.



Figure 6. Typical Distribution of Input Bias Current



Figure 7. Typical Distribution of Offset Voltage Matching





Figure 9. Typical Distribution of Power Supply Rejection Ratio (PSRR)

Data Sheet

AD8244





Data Sheet





Figure 28. 0.1 Hz to 10 Hz Voltage Noise





Figure 30. No Phase Reversal







Figure 32. Large Signal Pulse Response and Settling Time, $R_L = 10 \ k\Omega$, $C_L = 100 \ pF$





Figure 34. Small Signal Pulse Response, $R_L = 10 \ k\Omega$, $C_L = 100 \ pF$



Figure 35. Small Signal Pulse Response with Various Capacitive Loads, $R_L = No Load$





Figure 37. Input Capacitance vs. Input Voltage (V_{IN}) Referred to $+V_S$



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OVERVIEW

The AD8244 is a precision, quad, FET input, unity-gain buffer that is designed to isolate very large source impedances from the rest of the signal chain. N-channel JFETs are used as the input transistors to provide a low offset (350 µV maximum), low noise (13 nV/ $\sqrt{\text{Hz}}$ typical), high impedance (more than 10 T Ω) input stage that operates right down to the negative supply voltage. Using a new drift trimming method, the B grade AD8244 is able to achieve very low offset voltage over temperature (0.545 mV maximum), and it introduces minimal system error over temperature. The AD8244 design is optimized for high precision applications, such as buffers for biopotential electrodes, where it is important that buffers have very high impedance inputs and channels that match closely. Because the AD8244 fits into a 10-lead package, whereas a quad op amp requires a minimum of 14 leads, routing space is reduced and parasitics from the feedback traces are eliminated. Furthermore, the flexible design and the high channel density of the AD8244 allow it to be used in the signal chain anywhere a unity-gain buffer is needed.

GUARDING

When using low input bias current FET input amplifiers, designers must pay careful attention to voltage gradients from the input node to adjacent conductors on the board. These gradients can create leakage currents that overwhelm the input impedance and bias current performance of the FET input. These leakage currents get much worse with contamination, humidity, and temperature. Guarding techniques can be used to protect against parasitic leakage currents by greatly reducing the voltage gradient seen by the input node. Physically, a guard is a low impedance conductor that surrounds a high impedance node and is raised to the voltage of that node. It serves to buffer leakage by diverting it away from the sensitive node and into the low impedance guard. A complication results from the fact that many traditional op amp pinouts place a supply pin next to the noninverting input. The only way to guard the input of one of these op amps is to route the guard trace between the input pin and the supply pin. Traces can be routed between pins for large packages, such as DIP or even SOIC; however, the board area consumed by these packages is prohibitive for many modern applications.



The AD8244 solves this problem with a unique pinout that naturally isolates the high impedance inputs from the low impedance nodes, such as the supplies and outputs of the other buffers. Additionally, the buffers of the AD8244 can be used to guard their own inputs, reducing the voltage gradient seen by the input to only the low offset voltage of the buffer. The AD8244 facilitates this by making guard traces easy to route without the need for traces to go between pins.



Figure 40. Guarding with the AD8244

INPUT PROTECTION

All terminals of the AD8244 are protected against ESD. In addition, the input structure allows for dc overload conditions up to a diode drop above the positive supply and a diode drop below the negative supply. Voltages more than a diode drop beyond the supplies cause the ESD diodes to conduct and enable current to flow through the diode. Therefore, use an external resistor in series with each of the inputs to limit current for voltages beyond the supplies. In either scenario, the AD8244 input safely handles a continuous 6 mA current at room temperature.

For applications where the AD8244 encounters extreme overload voltages, as in cardiac defibrillators, use external series resistors and low leakage diode clamps, such as FJH1100 or BAV199L.

LAYOUT CONSIDERATIONS

The inputs of the AD8244 buffers are extremely high impedance. Shunt impedances from leakage resistance and parasitic capacitance in the printed circuit board (PCB) layout can severely degrade the performance of the JFET input. If a buffer output is used to surround the corresponding input node, leakage resistance and parasitic capacitance from the layout can be kept extremely low. Remove solder mask from the guard traces to guard against surface leakage due to contamination. In addition to the guard traces on the primary side, route a guard trace around any vias in the input net on the other side of the board as well. Keep the parasitic capacitance seen by the output small to maintain the optimum step response. Amplifiers used in the same signal path, such as buffering the voltage for two inputs of an inamp or difference amplifier, must have matched impedance in the input traces. This includes matched length and symmetrical traces. Place any input resistors close to the AD8244 inputs to avoid interaction with trace parasitics. If one of the channels is not in use, connect the input to a voltage that is within its linear range to avoid overdrive conditions that can interfere with other channels. Leave the output unconnected. Place decoupling capacitors, such as 0.1 µF, near the AD8244. Larger capacitors, such as 10 μ F, can be used farther away from the device.

DIFFERENTIAL SIGNAL CHAINS

The AD8244 can be used to buffer the inputs of difference amplifiers and instrumentation amplifiers to take advantage of qualities of the JFET input. In applications such as these, which use two channels of the AD8244 to buffer the positive and negative of a differential signal path, it is the mismatch between the channels, rather than the absolute error, that introduces error into the system. The AD8244 is designed so that the channels closely match and can be used in differential circuits with excellent results. Channel-to-channel matching errors are specified to aid in the design process. When driving the inputs of an instrumentation amplifier, difference amplifier, or other differential input circuit, the gain matching from channel to channel defines the common-mode rejection ratio (CMRR) error introduced to the system by the AD8244. The unit conversion is as follows:

CMRR (dB) = 20 × log₁₀(100/Gain Matching (%))

The JFET pinch-off voltage can vary from channel to channel and cause additional mismatch when the JFET begins to saturate near the positive rail. The CMRR error is minimized by keeping the input voltage away from the positive input range limit. Because the input impedance is very high, the CMRR achieved in differential systems stays high, even with large or mismatched source resistance. See the Typical Performance Characteristics section for more information.

LOW OUTPUT IMPEDANCE vs. FREQUENCY

The closed-loop output impedance of the AD8244 increases at higher frequencies when the loop gain is reduced, as shown in Figure 12. The AD8244 drives 200 pF directly with slight ringing, as shown in Figure 35. By placing a small resistor in series with the output, the capacitive load drive of the AD8244 can be increased. For applications that need the AD8244 input performance and very low output impedance over frequency, such as driving a cable shield, a switching load, or a large amount of capacitance at high frequencies, an op amp can be added in a configuration, such as the one in Figure 41. This configuration takes advantage of the low op amp output impedance at low frequencies, and the load capacitor reduces the output impedance at high frequencies. Typically, $R_F \times C_F$ should be less than or equal to $R_0 \times C_L$.



Figure 41. Adding an Op Amp for Low Output Impedance

APPLICATIONS INFORMATION ELECTROCARDIOGRAM (ECG)

In an ECG system, mismatches between the source impedance of different leads, working against the input impedance of the front-end amplifier, can create unbalanced voltage dividers that reduce the system CMRR. When presented to a moderately high input impedance amplifier, the combined impedance of the skin, electrolyte, electrodes, and the protection resistors can be enough to cause power line noise pickup, current noise issues, and signal division. Dry electrode systems, which are becoming increasingly common and have significantly higher source impedance, are especially sensitive to these errors. Typically, a high input impedance, low bias current, FET input op amp is used to buffer the electrode signal before it is presented to an instrumentation amplifier. This buffer solves the majority of these problems; however, when an instrument is in the field, it can be subject to dust pickup and humidity. If the op amp input is not guarded, these environmental factors can create unwanted leakage currents that bring back the aforementioned issues from insufficient input impedance. The AD8244 pinout is configured to make it simple to guard the inputs from parasitic resistance and capacitance while it also drives the instrumentation amplifier inputs, creating a more robust design, while saving power and board space. The CMRR of the AD8244 driving an instrumentation amplifier initially depends on the gain matching for the chosen supplies and voltage range, as well as the instrumentation amplifier used, but it can be improved with design techniques such as right leg drive (RLD) or digital filtering.

FILTERING

In filtering applications, it is generally recommended to use capacitors such as COG or NP0 ceramics for distortion and dielectric absorption performance. These types of capacitors do not have a high volumetric efficiency and are only available in values less than a few tens of nanofarads, depending on the case size and voltage rating. For a given cutoff frequency, using smaller capacitors requires larger resistor values. At low frequencies where the resistor values become very large, the bias current of a typical op amp can introduce significant offsets and additional noise. The subpicoampere bias current of the AD8244 allows resistor values in the tens of megaohms with no additional error while providing an excellent low power, small footprint solution for filter design. Between the four channels of the AD8244, a filter with more than eight poles can be implemented while using less space than the same filter with a quad op amp.

Sallen-Key Low-Pass Filter



Figure 42. Sallen-Key Low-Pass Filter

The following equations describe the corner frequency, f_c , and quality factor, Q, for the low-pass filter case of the Sallen-Key topology, shown in Figure 42:

$$f_{C} = 1/(2\pi \sqrt{R1 \times R2 \times C1 \times C2})$$
$$Q = (\sqrt{R1 \times R2 \times C1 \times C2})/(C2 \times (R1 + R2))$$

For an example of a design with this topology, choose a filter where Q = 0.707 and R1 = R2 = R. This requires that $C1 = 2 \times C2$. The corner frequency equation can now be simplified to

$$f_C = 1/(2\pi \times R \times C2 \times \sqrt{2})$$

If an available capacitor, such as 1 nF, is chosen for C2, R can be written in terms of the desired cutoff frequency:

 $R = 1/(2\sqrt{2} \times \pi \times 1 \text{ nF} \times f_c) = 112.5 M\Omega/f_c \text{ (that is,} R = 750 \text{ k}\Omega \text{ for } f_c = 150 \text{ Hz})$

Sallen-Key High-Pass Filter





The high-pass filter case of the Sallen-Key topology has the same corner frequency equation as the low-pass filter. However, the equation for Q changes to

 $Q = (\sqrt{R1 \times R2 \times C1 \times C2})/(R1 \times (C1 + C2))$

In this case, a Q of 0.707 is achieved with C1 = C2 = C, and $2 \times R1 = R2 = R$, which is a symmetrical result to the low-pass filter case.

The corner frequency then simplifies to

$$f_C = 1/(\sqrt{2} \times \pi \times R \times C)$$

For a low corner frequency, a larger available capacitor such as 22 nF can be chosen, yielding the following expression for R:

 $R = 10.2 M\Omega/f_c$ (that is, a 0.5 Hz filter requires R1 = 10 M Ω and R2 = 20 M Ω)

Twin-T Notch Filter



The following equations describe the parameters of the Twin-T notch filter with active feedback shown in Figure 44:

$$f_0 = 1/(2\pi RC)$$

 $Q = 0.25/(1 - K)$

where K is an attenuation factor from 0 to 1, as shown in Figure 44. A K of either 0 or 1 can be achieved with only one buffer.

One of the best things about this filter is that fo and Q are independent, which allows for easy tuning of filter characteristics. However, designers use the Twin-T notch filter sparingly in production designs because of its sensitivity to component tolerances, which affect both the depth and the frequency of the notch. Reducing the Q is one way to ensure that the desired frequency has sufficient attenuation independent of component variance and drift; however, reducing the Q also linearly increases the distance between the pass bands. The notch depth can be improved and the stop-band width decreased simultaneously by cascading multiple filter stages.

To illustrate the benefit of cascading stages, Figure 45 shows the response of two filters, both designed to provide greater than 26 dB of attenuation at 60 Hz \pm 5%, which allows for component tolerance. The single stage filter requires a Q of 0.5 and results in a -3 dB notch bandwidth of 120 Hz. The two stage filter has a Q of 2.25 for each stage, and the -3 dB notch bandwidth is reduced to about 40 Hz.



PHOTODIODE AMPLIFIER

Photodiodes in precision circuits are typically measured in photovoltaic mode, in which there is no reverse bias voltage. Two benefits to this measurement mode are that there is no dark current, and the output is linearly related to the light intensity. However, in photovoltaic mode, the signal current can be very small, requiring a high gain transimpedance amplifier (TIA). There are a limited number of amplifiers suited for building TIAs for measuring photodiodes or other low current sensors, which can make it difficult to achieve high performance. Using an AD8244 as the interface to the photodiode eliminates the need for a low bias current op amp, allowing optimization of other parameters, such as precision, slew rate, output drive, board space, and cost. As with any composite amplifier, it is important to pay special attention to stability. The unity-gain crossover frequency of the op amp must be less than the AD8244 bandwidth for this configuration to be unity-gain stable. The noise gain of the op amp varies with the shunt resistance of the diode, which is temperature dependent.



LOW NOISE, JFET INPUT BUFFER

The voltage noise of the AD8244 can be reduced by placing multiple buffers in parallel. For example, two buffers in parallel reduce the voltage noise by $\sqrt{2}$, or all four buffers placed in parallel act as a buffer with $\frac{1}{2}$ the noise. The trade-offs to this method are increased bias current, current noise, and input capacitance. Place a small resistor, such as 50 Ω , between the outputs to avoid extra current flow due to the slight differences between each output. For less power sensitive applications, these 50 Ω resistors can be omitted to boost the available output current.



Figure 47. Reducing the Voltage Noise

OUTLINE DIMENSIONS



ORDERING GUIDE

| | | | Package | |
|--------------------|-------------------|---|---------|----------|
| Model ¹ | Temperature Range | Package Description | Option | Branding |
| AD8244ARMZ | -40°C to +85°C | 10-Lead Mini Small Outline Package [MSOP], Standard Grade | RM-10 | Y54 |
| AD8244ARMZ-R7 | –40°C to +85°C | 10-Lead Mini Small Outline Package [MSOP], Standard Grade, 7″Tape and Reel | RM-10 | Y54 |
| AD8244BRMZ | -40°C to +85°C | 10-Lead Mini Small Outline Package [MSOP], High Performance Grade | RM-10 | Y55 |
| AD8244BRMZ-R7 | -40°C to +85°C | 10-Lead Mini Small Outline Package [MSOP], High Performance Grade, 7″Tape and Reel | RM-10 | Y55 |
| AD8244-EVALZ | | Evaluation Board | | |

 1 Z = RoHS Compliant Part.

NOTES

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