Flat Area Sensor With Plastic Case

Features

- 13mm slim body with fresnel lens
- Adoption of plastic (PC/ABS) injection case
- Various functions: stop transmission, interference prevention, lightening/flashing JOB indicator, Light ON/Dark ON operation by switch
- Easy to recognize at side, front, and long-distance by high brightness LED of Emitter and Receiver
- Fast response time up to 7ms
- 4 models with various optical axis (8 to 20) and sensing height (140 to 380mm)

CE

Protection structure IP40 (IEC standard)

Please read "Safety Considerations" in the instruction manual before using



SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

Spe	cifi	cati	ons	
 Ope		outr		

Madal	NPN open collector output	BWP20-08	BWP20-12	BWP20-16	BWP20-20	(B) Fiber Optic Sensors			
Vodel	PNP open collector output	BWP20-08P	BWP20-12P	BWP20-16P	BWP20-20P	(C) LiDAR			
Sensing type		Through-beam	hrough-beam						
Sensing distar	nce	0.1 to 5m				(D) Door/Area			
Sensing targe	.t	Opaque materials of min. Ø30mm							
Optical axis pi	itch	20mm							
Number of opt	tical axis	8	12	16	20	(E) Vision Sensors			
Sensing heigh	ıt	140mm	220mm	300mm	380mm	00110010			
Response time	e	Max. 6ms (frequency B s	election is max. 7ms)	U		(F) Proximity			
Power supply		12-24VDC== ±10% (ripple	e P-P: max. 10%)			Sensors			
Current consu	Imption	Emitter: max. 80mA, rece	viver: max. 80mA			(G) Pressure			
Light source		Infrared LED (850nm mo	Infrared LED (850nm modulated)						
Operation mod	de	Light ON/Dark ON by swi	itch			(H)			
Control output		NPN or PNP open collector output • Load voltage: Max. 30VDC= • Load current: Max. 150mA • Residual voltage - NPN: Max. 1VDC=-, PNP: Max. 2.5VDC							
Protection circuit		Reverse power polarity, output short over current protection circuit							
Insulation resistance		Over 20MΩ (at 500VDC megger)							
Synchronizatio	on type	Synchronized by synchronous line							
Interference p	rotection	Interference protection by transmission frequency selection							
Noise immunit	ty	±240V the square wave noise (pulse width: 1µs) by the noise simulation							
Dielectric strei	ngth	1,000VAC 50/60Hz for 1 min							
Vibration		1.5mm amplitude or 300m/s ² at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours							
Shock		500m/s ² (approx. 50G) in each X, Y, Z direction for 3 times							
Ambient illumination Environment Ambient temperature		Ambient light: max. 10,0001x (received light side illumination)							
		-10 to 55°C, storage: -20 to 60°C							
Ambient humidity		35 to 85%RH, storage: 35 to 85%RH							
Protection structure		IP40 (IEC standard)							
Material		Case: Polycarbonate/Acrylonitrile butadiene styrene, Sensing part: Polymethyl methacrylate							
Cable		Ø3.5mm, 4-wire, 3m (AWG 24, core diameter: 0.08mm, number of cores: 40, insulator out diameter: Ø1mm)							
Approval		CE							
Weight ^{**1}		Approx. 480g (approx. 280g)	Approx. 520g (approx. 320g)	Approx. 620g (approx. 360g)	Approx. 680g (approx. 430g)				

%1: The weight includes packaging. The weight in parenthesis is for unit only.

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation.



Dimensions



BK-BWP-P08

BK-BWP-P12

BK-BWP-P16

BK-BWP-P20

194

274

354

434

35

13.5

17.5

Feature Data



Input/Output Circuit and Connection Diagram



※If the receiver OUT (black) line and the emitter JOB (black) line are not connected each other, the JOB indicator of the emitter is not operated and maintain the light status.

Operation Timing Diagram



%The waveforms of operation indicator, job indicator, and control output are the state of operation for Light ON, but in case of Dark ON, it is opposite operation against Light ON mode.

• PNP open collector output

(blue) 0V 12-24VDC (brown) +V (black) JOB (white) SYNC (white) SYNC (brown) +V (black) OUT Load (blue) 0V

Sensors (B) Fiber Optic Sensors

(C) LiDAR (D) Door/Area

(E) Vision Sensors

(F) (r) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

BWP Series

Structure Emitter Receiver r Job indicator (red) Job indicator (red) Operation indicator (red) Frequency B indicator (yellow) Stability indicator (green) Frequency A indicator (green) Operation mode switch 4 0 3 2 White Black Ν Ō

O Mounting of bracket

No	Function	Switch OFF	Switch ON
1	Transmission frequency selection	Frequency A	Frequency B
2	Light ON/Dark ON selection	Light ON operation	Dark ON operation
3	Steady/flashing light of Job indicator selection	Job indicator with Steady light	Job indicator with Flashing light
4	Job/TEST selection	Normal mode	TEST mode

Functions

◎ TEST (stop transmission)

When selecting TEST mode, emit is stopped and green &yellow LED of emitter flashes. It is available to check whether sensor operates properly with stopping the transmission in TEST mode. It is changed to light OFF status when emit the transmission is stopped, control output is OFF in Light ON mode and ON in Dark ON mode.

Control output pulse for TEST input



◎ Interference prevention

In case of using 2 of sensor in serial or parallel in order to extend sensing width, it may cause sensing error because of light interference.

This function is operating a sensor in transmission frequency A and another sensor in transmission frequency B to avoid these sensing errors by the light interference.



© Light-ON / Dark-ON operation mode

The control output is ON when it is light ON in Light ON and the control output is ON when it is light OFF in Dark ON. It is available to select with user's preference.

	Operation mode switch	Control output operation		
Light ON	ON ← ④ □ □ ③ □ □ Light ON	It is ON when \ it is light ON.		
Dark ON	ON ← ④ □ □ ③ □ □ Dark ON ① □ □	It is ON when it is light OFF.		

© Lightening/Flashing JOB indicator

JOB indicator will be lighted and flashed to make out work sensing operation more easily.

Operation mode switch	JOB indicator operation	
ON ← ④ □ □ ↓ ④ □ □ ↓ ↓ Lighting	Lighting indicator	
ON ← Flashing ③	Flashing indicator	

Installation

O For direction of installation

Emitter and receiver should be installed as same up/down position.



O For reflection from the surface of wall and flat

When installing it as below the light reflected from the surface of wall and flat will not be shaded. Please, check whether it operates normally or not with a sensing target before using. (interval distance: min. 0.3m)



O For prevention of interference

Bottom

It may cause interference when installing more than 2 sets of the sensor. In order to avoid the interference of the sensor, please install as following figures and use the interference protection function.

• Transmission direction should be opposite between 2 sets





It should be installed out of the interference distance



XAvoid using the unit in the place where the sensor is exposed directly to the fluorescent light with high speed start or high frequency.

Operation Indicator

Receiver

Wall

6

				-				
_	Emitte	r		Receiv	er			
Item	Indicator		Indicator			Control		
licin	Green	Yellow	JOB Indicator	Green	Red	JOB Indicator	output	
Power on	\		—	—	—	_	—	
FREQ. A operation	ф.		—	—	—	_	—	
FREQ. B operation	ф.	-¢-	—	_	—	_	—	(A)
TEST		۲	- ¢	-¢-		- ¢-	OFF	Photoelecti Sensors
Stable light ON	—	—		- ¢	Ø		ON	
Unstable light ON	-	—			Ø		ON	(B) Fiber Optic
Unstable light OFF	_	—	- ¢			- ¢	OFF	Sensors
Stable light OFF	-	—	- ¢	-¢-		- ¢-	OFF	
Flashing function ON	—	—		-¢			OFF	(C) LIDAR
Synchronous line malfunction	-	_	¢	۲	۲	¢	OFF	
Overcurrent	-	—	- ¢			- ¢	OFF	(D) Door/Area
Display classification list				Sensors				
C Light ON				(E) Vision Sensors				
Light OFF								
Flashing by 0.3 sec				(F)				
Flashing simultaneously by 0.3 sec								
Cross-Flashing by 0.3 sec			Proximity Sensors					

*The operation of 'Operation indicator (red)', 'Job indicator (red)', 'Control output' is for Light ON, in case of Dark ON, it is opposite operation against Light ON. (In case, malfunction of synchronous line and over current, control output is OFF regardless of the mode.)

Troubleshootina

Malfunction	Cause	Troubleshooting	
Non-operation	Power supply Cable incorrect connection or disconnection	Supply rated power. Check the wiring.	
	Rated connection failure	Use it within rated sensing distance.	
Non-operation	Pollution by dirt of sensor cover	Remove dirt by soft brush or cloth.	
in sometimes	Connector connection failure	Check the assembled part of the connector.	
	Out of rated sensing distance	Use within rated sensing distance.	
Control output is OFF	There is an obstacle to cut off the light emitted between emitter and	Remove the obstacle.	
even though there is not a target object.	receiver There is a strong electric wave or noise generated by motor, electric generator, high voltage line etc.	Put away the strong electric wave or noise generator.	
LED displays for synchronous line	Synchronous line incorrect connection or disconnection	Check the wiring.	
malfunction	Break of synchronous circuit of emitter or receiver	Contact our company.	
LED displays for over	Control output line is shorten	Check the wiring.	
current	Over load	Check the rated load capacity.	

) DAR

otoelectric

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(G)

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(1) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Proper Usage

- 1. Follow instructions in 'Proper Usage'. Otherwise, It may cause unexpected accidents.
- 2. 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Use the product, 1 sec after supplying power.
- When using separate power supply for the sensor and load, supply power to sensor first.
- 4. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
- 5. When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise.
- 7. This unit may be used in the following environments.
- ①Indoors (in the environment condition rated in 'Specifications')
 ②Altitude max. 2,000m
 ③Pollution degree 2
 ④Installation category II