

# NTS0102

Dual supply translating transceiver; open-drain; auto direction sensing

Rev. 4.4 — 6 October 2022

Product data sheet

## 1 General description

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The NTS0102 is a 2-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 2-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.65 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 2.3 V and 5.5 V, making the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V, and 5.0 V). Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

## 2 Features and benefits

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- Wide supply voltage range:
  - $V_{CC(A)}$ : 1.65 V to 3.6 V and  $V_{CC(B)}$ : 2.3 V to 5.5 V
- Maximum data rates:
  - Push-pull: 50 Mbit/s
- $I_{OFF}$  circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - HBM JESD22-A114E Class 3B exceeds 8000 V for B port
  - CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from  $-40\text{ }^{\circ}\text{C}$  to  $+85\text{ }^{\circ}\text{C}$  and  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$

## 3 Applications

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- I<sup>2</sup>C/SMBus
- UART
- GPIO



## 4 Ordering information

Table 1. Ordering information

Type number	Topside marking	Package		
		Name	Description	Version
NTS0102DP	s02	TSSOP8	plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm	SOT505-2
NTS0102GT	s02	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 1 × 1.95 × 0.5 mm	SOT833-1
NTS0102GD	s02	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 3 × 2 × 0.5 mm	SOT996-2
NTS0102GF	s2	XSON8	extremely thin small outline package; no leads; 8 terminals; body 1.35 × 1 × 0.5 mm	SOT1089
NTS0102TL	tS2	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 3 × 2 × 0.5 mm	SOT1052-2

### 4.1 Ordering options

Table 2. Ordering options

Type number	Orderable part number	Package	Packing method <sup>[1]</sup>	Minimum order quantity	Temperature
NTS0102DP	NTS0102DP,125	TSSOP8	Reel 7" Q3 NDP	3000	-40 °C to +125 °C
NTS0102GT	NTS0102GT,115	XSON8	Reel 7" Q1 NDP	5000	-40 °C to +125 °C
NTS0102GD <sup>[2]</sup>	NTS0102GD,125	XSON8	Reel 7" Q3 NDP	3000	-40 °C to +125 °C
NTS0102GF	NTS0102GF,115	XSON8	Reel 7" Q1 NDP	5000	-40 °C to +125 °C
NTS0102TL	NTS0102TLH	XSON8	Reel 7" Q3 NDP	4000	-40 °C to +125 °C

[1] Standard packing quantities and other packaging data are available at [www.nxp.com/packages/](http://www.nxp.com/packages/).

[2] Discontinuation Notice 202111012DN - drop in replacement is NTS0102TLH.

The TL package has a center pad vs no center pad for the GD package. The TL package pad is not electrically connected to the silicon and is not required to connect to the PCB so it can drop onto the GD package PCB layout. If the existing GD package has a trace underneath the risk is low since the TL package center pad is not connected to the silicon. If there are multiple traces there could be EMI and cross talk. In both cases the customer needs to evaluate risk.

Note: The length and width are reversed between the "GD" and "TL" package drawings but the shorter edge contains the pins and is 2.0 mm in both cases.

### 5 Functional diagram

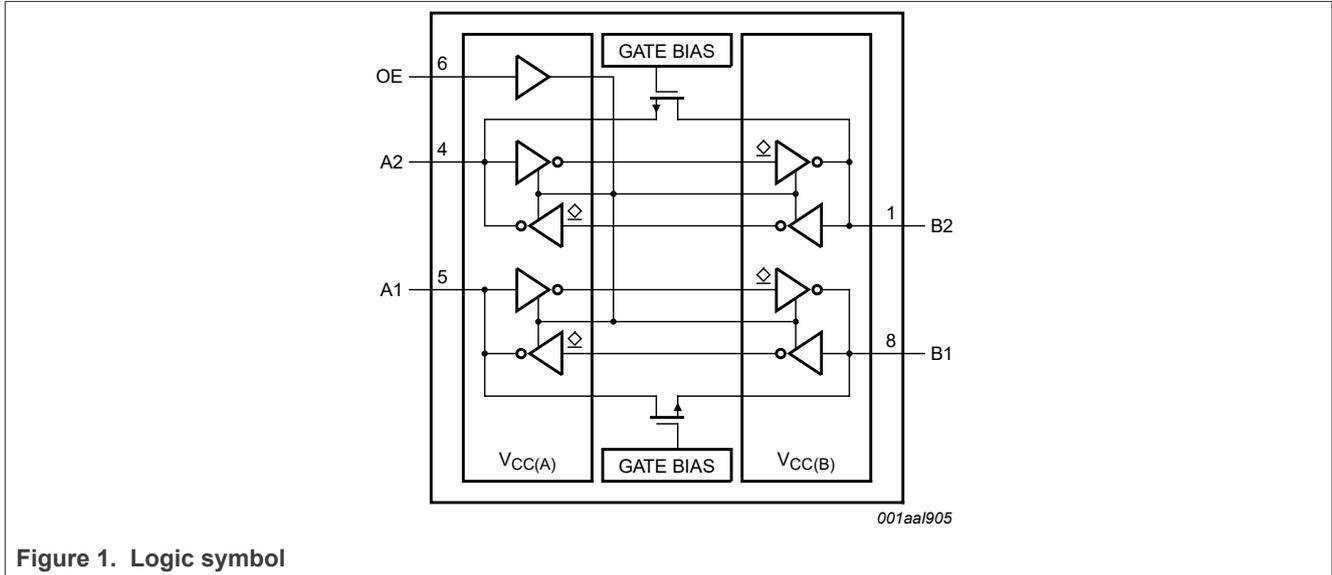


Figure 1. Logic symbol

### 6 Pinning information

#### 6.1 Pinning

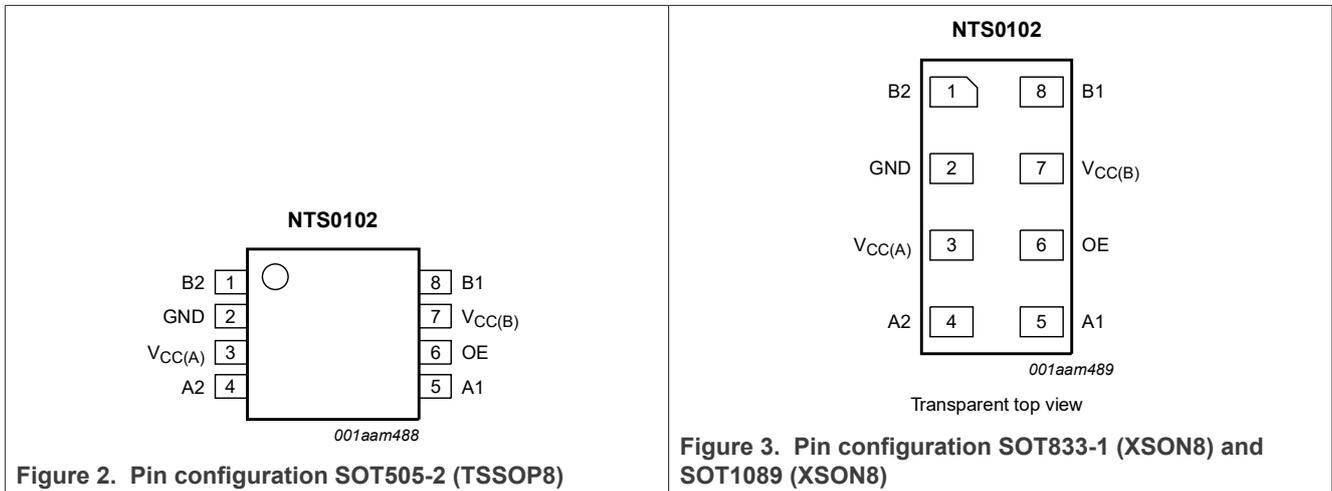
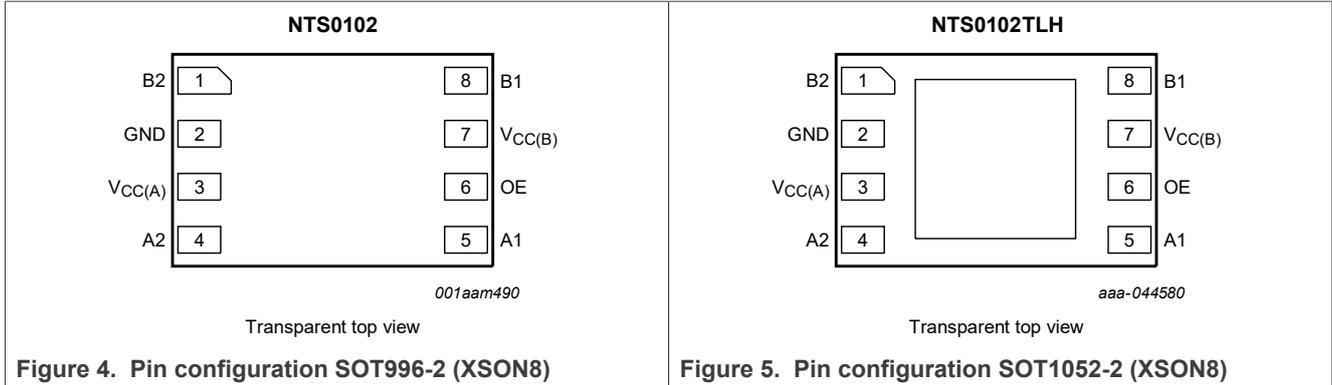


Figure 2. Pin configuration SOT505-2 (TSSOP8)

Figure 3. Pin configuration SOT833-1 (XSON8) and SOT1089 (XSON8)



### 6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
B2, B1	1, 8	data input or output (referenced to $V_{CC(B)}$ )
GND	2	ground (0 V)
$V_{CC(A)}$	3	supply voltage A
A2, A1	4, 5	data input or output (referenced to $V_{CC(A)}$ )
OE	6	output enable input (active HIGH; referenced to $V_{CC(A)}$ )
$V_{CC(B)}$	7	supply voltage B

## 7 Functional description

Table 4. Function table<sup>[1]</sup>

Supply voltage		Input	Input/output	
$V_{CC(A)}$	$V_{CC(B)}$	OE	An	Bn
1.65 V to $V_{CC(B)}$	2.3 V to 5.5 V	L	Z	Z
1.65 V to $V_{CC(B)}$	2.3 V to 5.5 V	H	input or output	output or input
GND <sup>[2]</sup>	GND <sup>[2]</sup>	X	Z	Z

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

## 8 Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
$V_{CC(B)}$	supply voltage B		-0.5	+6.5	V
$V_I$	input voltage	A port and OE input <sup>[1] [2]</sup>	-0.5	+6.5	V
		B port <sup>[1] [2]</sup>	-0.5	+6.5	V

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Table 5. Limiting values...continued

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>O</sub>	output voltage	Active mode [1] [2]			
		A or B port	-0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode [1]			
		A port	-0.5	+4.6	V
		B port	-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V	-50	—	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	—	mA
I <sub>O</sub>	output current	V <sub>O</sub> = 0 V to V <sub>CCO</sub> [2]	—	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>	—	100	mA
I <sub>GND</sub>	ground current		-100	—	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +125 °C [3]	—	250	mW

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V<sub>CCO</sub> is the supply voltage associated with the output.

[3] For TSSOP8 package: above 55 °C, the value of P<sub>tot</sub> derates linearly with 2.5 mW/K.  
For XSON8 packages: above 118 °C, the value of P<sub>tot</sub> derates linearly with 7.8 mW/K.

## 9 Recommended operating conditions

Table 6. Recommended operating conditions<sup>[1][2]</sup>

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.65	3.6	V
V <sub>CC(B)</sub>	supply voltage B		2.3	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	A or B port; push-pull driving			
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	10	ns/V
		OE input			
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	10	ns/V

[1] The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CC1</sub> or both at GND.

[2] V<sub>CC(A)</sub> must be less than or equal to V<sub>CC(B)</sub>.

## 10 Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I <sub>I</sub>	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	—	±1	μA

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**Table 7. Typical static characteristics...continued**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V);  $T_{amb} = 25\text{ }^{\circ}\text{C}$ .

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{OZ}$	OFF-state output current	A or B port; $V_O = 0\text{ V}$ or $V_{CCO}$ ; $V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$ ; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ <sup>[1]</sup>	—	—	$\pm 1$	$\mu\text{A}$
$I_{OFF}$	power-off leakage current	A port; $V_I$ or $V_O = 0\text{ V to }3.6\text{ V}$ ; $V_{CC(A)} = 0\text{ V}$ ; $V_{CC(B)} = 0\text{ V to }5.5\text{ V}$	—	—	$\pm 1$	$\mu\text{A}$
		B port; $V_I$ or $V_O = 0\text{ V to }5.5\text{ V}$ ; $V_{CC(B)} = 0\text{ V}$ ; $V_{CC(A)} = 0\text{ V to }3.6\text{ V}$	—	—	$\pm 1$	$\mu\text{A}$
$C_I$	input capacitance	OE input; $V_{CC(A)} = 3.3\text{ V}$ ; $V_{CC(B)} = 3.3\text{ V}$	—	1	—	pF
$C_{I/O}$	input/output capacitance	A port	—	5	—	pF
		B port	—	8.5	—	pF
		A or B port; $V_{CC(A)} = 3.3\text{ V}$ ; $V_{CC(B)} = 3.3\text{ V}$	—	11	—	pF

[1]  $V_{CCO}$  is the supply voltage associated with the output.

**Table 8. Typical supply current**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V);  $T_{amb} = 25\text{ }^{\circ}\text{C}$ .

$V_{CC(A)}$	$V_{CC(B)}$						Unit
	2.5 V		3.3 V		5.0 V		
	$I_{CC(A)}$	$I_{CC(B)}$	$I_{CC(A)}$	$I_{CC(B)}$	$I_{CC(A)}$	$I_{CC(B)}$	
1.8 V	0.1	0.5	0.1	1.5	0.1	4.6	$\mu\text{A}$
2.5 V	0.1	0.1	0.1	0.8	0.1	3.8	$\mu\text{A}$
3.3 V	—	—	0.1	0.1	0.1	2.8	$\mu\text{A}$

**Table 9. Static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	A port					
		$V_{CC(A)} = 1.65\text{ V to }1.95\text{ V}$ ; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ <sup>[1]</sup>	$V_{CCI} - 0.2$	—	$V_{CCI} - 0.2$	—	V
		$V_{CC(A)} = 2.3\text{ V to }3.6\text{ V}$ ; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ <sup>[1]</sup>	$V_{CCI} - 0.4$	—	$V_{CCI} - 0.4$	—	V
		B port					
		$V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$ ; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$ <sup>[1]</sup>	$V_{CCI} - 0.4$	—	$V_{CCI} - 0.4$	—	V
		OE input					
	$V_{CC(A)} = 1.65\text{ V to }3.6\text{ V}$ ; $V_{CC(B)} = 2.3\text{ V to }5.5\text{ V}$	$0.65V_{CC(A)}$	—	$0.65V_{CC(A)}$	—	V	

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Table 9. Static characteristics...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
V <sub>IL</sub>	LOW-level input voltage	A or B port					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	0.15	—	0.15	V
		OE input					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	0.35V <sub>CC(A)</sub>	—	0.35V <sub>CC(A)</sub>	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub> = -20 μA					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V [2]	0.67V <sub>CCO</sub>	—	0.67V <sub>CCO</sub>	—	V
V <sub>OL</sub>	LOW-level output voltage	A or B port; I <sub>O</sub> = 1 mA [2]					
		V <sub>I</sub> ≤ 0.15 V; V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	0.4	—	0.4	V
I <sub>I</sub>	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	±2	—	±12	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; V <sub>O</sub> = 0 V or V <sub>CCO</sub> ; V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V [2]	—	±2	—	±12	μA
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V	—	±2	—	±12	μA
		B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	—	±2	—	±12	μA
I <sub>CC</sub>	supply current	V <sub>I</sub> = 0 V or V <sub>CCI</sub> ; I <sub>O</sub> = 0 A [1]					
		I <sub>CC(A)</sub>					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	2.4	—	15	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	—	2.2	—	15	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	—	-1	—	-8	μA
		I <sub>CC(B)</sub>					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	12	—	30	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V	—	-1	—	-5	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	—	1	—	6	μA
		I <sub>CC(A)</sub> + I <sub>CC(B)</sub>					
V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	—	14.4	—	30	μA		

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

[2] V<sub>CCO</sub> is the supply voltage associated with the output.

11 Dynamic characteristics

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit, see [Figure 8](#); for wave forms see [Figure 6](#) and [Figure 7](#).

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	
<b>V<sub>CC(A)</sub> = 1.8 V ± 0.15 V</b>									
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	—	4.6	—	4.7	—	5.8	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	—	6.8	—	6.8	—	7.0	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	—	4.4	—	4.5	—	4.7	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	—	5.3	—	4.5	—	0.5	ns
t <sub>en</sub>	enable time	OE to A; B	—	200	—	200	—	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load <sup>[2]</sup>	—	25	—	25	—	25	ns
		OE to B; no external load <sup>[2]</sup>	—	25	—	25	—	25	ns
		OE to A	—	230	—	230	—	230	ns
		OE to B	—	200	—	200	—	200	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	A port	3.2	9.5	2.3	9.3	1.8	7.6	ns
		B port	3.3	10.8	2.7	9.1	2.7	7.6	ns
t <sub>THL</sub>	HIGH to LOW output transition time	A port	2.0	5.9	1.9	6.0	1.7	13.3	ns
		B port	2.9	7.6	2.8	7.5	2.8	10.0	ns
t <sub>sk(o)</sub>	output skew time	between channels <sup>[3]</sup>	—	0.7	—	0.7	—	0.7	ns
t <sub>W</sub>	pulse width	data inputs	20	—	20	—	20	—	ns
f <sub>data</sub>	data rate		—	50	—	50	—	50	Mbit/s
<b>V<sub>CC(A)</sub> = 2.5 V ± 0.2 V</b>									
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	—	3.2	—	3.3	—	3.4	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	—	3.5	—	4.1	—	4.4	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	—	3.0	—	3.6	—	4.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	—	2.5	—	1.6	—	0.7	ns
t <sub>en</sub>	enable time	OE to A; B	—	200	—	200	—	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load <sup>[2]</sup>	—	20	—	20	—	20	ns
		OE to B; no external load <sup>[2]</sup>	—	20	—	20	—	20	ns
		OE to A	—	200	—	200	—	200	ns

Dual supply translating transceiver; open-drain; auto direction sensing

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C<sup>[1]</sup>...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	
		OE to B	—	200	—	200	—	200	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	A port	2.8	7.4	2.6	6.6	1.8	6.2	ns
		B port	3.2	8.3	2.9	7.9	2.4	6.8	ns
t <sub>THL</sub>	HIGH to LOW output transition time	A port	1.9	5.7	1.9	5.5	1.8	5.3	ns
		B port	2.2	7.8	2.4	6.7	2.6	6.6	ns
t <sub>sk(o)</sub>	output skew time	between channels <sup>[3]</sup>	—	0.7	—	0.7	—	0.7	ns
t <sub>W</sub>	pulse width	data inputs	20	—	20	—	20	—	ns
f <sub>data</sub>	data rate		—	50	—	50	—	50	Mbit/s
<b>V<sub>CC(A)</sub> = 3.3 V ± 0.3 V</b>									
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	—	—	—	2.4	—	3.1	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	—	—	—	4.2	—	4.4	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	—	—	—	2.5	—	3.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	—	—	—	2.5	—	2.6	ns
t <sub>en</sub>	enable time	OE to A; B	—	—	—	200	—	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load <sup>[2]</sup>	—	—	—	15	—	15	ns
		OE to B; no external load <sup>[2]</sup>	—	—	—	15	—	15	ns
		OE to A	—	—	—	260	—	260	ns
		OE to B	—	—	—	200	—	200	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	A port	—	—	2.3	5.6	1.9	5.9	ns
		B port	—	—	2.5	6.4	2.1	7.4	ns
t <sub>THL</sub>	HIGH to LOW output transition time	A port	—	—	2.0	5.4	1.9	5.0	ns
		B port	—	—	2.3	7.4	2.4	7.6	ns
t <sub>sk(o)</sub>	output skew time	between channels <sup>[3]</sup>	—	—	—	0.7	—	0.7	ns
t <sub>W</sub>	pulse width	data inputs	—	—	20	—	20	—	ns
f <sub>data</sub>	data rate		—	—	—	50	—	50	Mbit/s

[1] t<sub>en</sub> is the same as t<sub>PZL</sub> and t<sub>PZH</sub>.

t<sub>dis</sub> is the same as t<sub>PLZ</sub> and t<sub>PHZ</sub>.

[2] Delay between OE going LOW and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

Dual supply translating transceiver; open-drain; auto direction sensing

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit	
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V			
			Min	Max	Min	Max	Min	Max		
<b>V<sub>CC(A)</sub> = 1.8 V ± 0.15 V</b>										
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	—	5.8	—	5.9	—	7.3	ns	
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	—	8.5	—	8.5	—	8.8	ns	
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A	—	5.5	—	5.7	—	5.9	ns	
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A	—	6.7	—	5.7	—	0.7	ns	
t <sub>en</sub>	enable time	OE to A; B	—	200	—	200	—	200	ns	
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	—	30	—	30	—	30	ns
		OE to B; no external load	[2]	—	30	—	30	—	30	ns
		OE to A		—	250	—	250	—	250	ns
		OE to B		—	220	—	220	—	220	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	A port		3.2	11.9	2.3	11.7	1.8	9.5	ns
		B port		3.3	13.5	2.7	11.4	2.7	9.5	ns
t <sub>THL</sub>	HIGH to LOW output transition time	A port		2.0	7.4	1.9	7.5	1.7	16.7	ns
		B port		2.9	9.5	2.8	9.4	2.8	12.5	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	—	0.8	—	0.8	—	0.8	ns
t <sub>w</sub>	pulse width	data inputs		20	—	20	—	20	—	ns
f <sub>data</sub>	data rate			—	50	—	50	—	50	Mbit/s
<b>V<sub>CC(A)</sub> = 2.5 V ± 0.2 V</b>										
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B		—	4.0	—	4.2	—	4.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B		—	4.4	—	5.2	—	5.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		—	3.8	—	4.5	—	5.4	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		—	3.2	—	2.0	—	0.9	ns
t <sub>en</sub>	enable time	OE to A; B		—	200	—	200	—	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	—	25	—	25	—	25	ns
		OE to B; no external load	[2]	—	25	—	25	—	25	ns
		OE to A		—	220	—	220	—	220	ns
		OE to B		—	220	—	220	—	220	ns

Dual supply translating transceiver; open-drain; auto direction sensing

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C<sup>[1]</sup>...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit	
			2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V			
			Min	Max	Min	Max	Min	Max		
t <sub>TLH</sub>	LOW to HIGH output transition time	A port	2.8	9.3	2.6	8.3	1.8	7.8	ns	
		B port	3.2	10.4	2.9	9.7	2.4	8.3	ns	
t <sub>THL</sub>	HIGH to LOW output transition time	A port	1.9	7.2	1.9	6.9	1.8	6.7	ns	
		B port	2.2	9.8	2.4	8.4	2.6	8.3	ns	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	—	0.8	—	0.8	—	0.8	ns
t <sub>W</sub>	pulse width	data inputs		20	—	20	—	20	—	ns
f <sub>data</sub>	data rate			—	50	—	50	—	50	Mbit/s
<b>V<sub>CC(A)</sub> = 3.3 V ± 0.3 V</b>										
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B		—	—	—	3.0	—	3.9	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B		—	—	—	5.3	—	5.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		—	—	—	3.2	—	4.2	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		—	—	—	3.2	—	3.3	ns
t <sub>en</sub>	enable time	OE to A; B		—	—	—	200	—	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	—	—	—	20	—	20	ns
		OE to B; no external load	[2]	—	—	—	20	—	20	ns
		OE to A		—	—	—	280	—	280	ns
		OE to B		—	—	—	220	—	220	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	A port		—	—	2.3	7.0	1.9	7.4	ns
		B port		—	—	2.5	8.0	2.1	9.3	ns
t <sub>THL</sub>	HIGH to LOW output transition time	A port		—	—	2.0	6.8	1.9	6.3	ns
		B port		—	—	2.3	9.3	2.4	9.5	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	—	—	—	0.8	—	0.8	ns
t <sub>W</sub>	pulse width	data inputs		—	—	20	—	20	—	ns
f <sub>data</sub>	data rate			—	—	—	50	—	50	Mbit/s

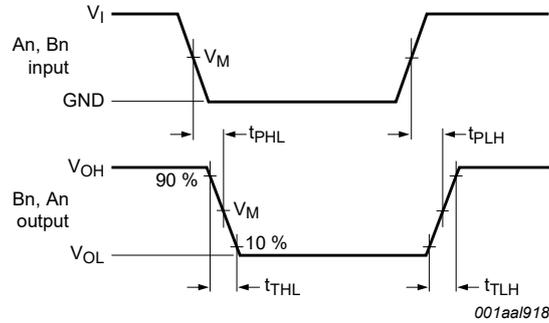
[1] t<sub>en</sub> is the same as t<sub>PZL</sub> and t<sub>PZH</sub>.

t<sub>dis</sub> is the same as t<sub>PLZ</sub> and t<sub>PHZ</sub>.

[2] Delay between OE going LOW and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

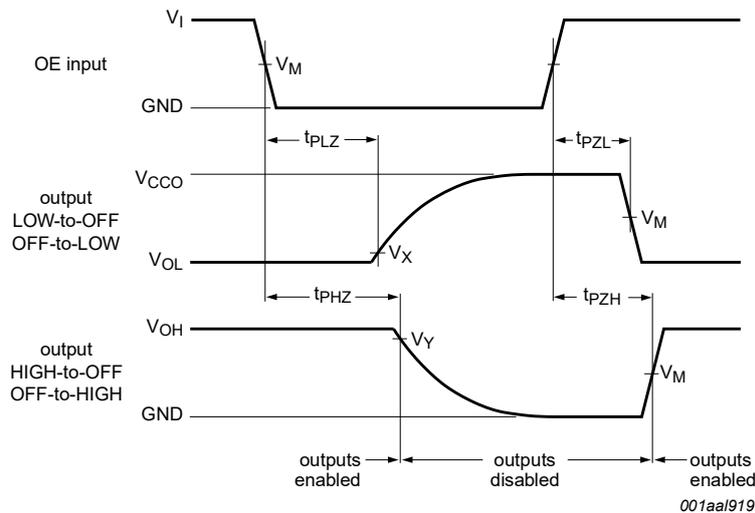
12 Waveforms



Measurement points are given in [Table 12](#).

$V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Figure 6. The data input (An, Bn) to data output (Bn, An) propagation delay times



Measurement points are given in [Table 12](#).

$V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Figure 7. Enable and disable times

Table 12. Measurement points<sup>[1][2]</sup>

Supply voltage	Input	Output		
$V_{CCO}$	$V_M$	$V_M$	$V_X$	$V_Y$
1.8 V ± 0.15 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.15 V$	$V_{OH} - 0.15 V$
2.5 V ± 0.2 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.15 V$	$V_{OH} - 0.15 V$
3.3 V ± 0.3 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$
5.0 V ± 0.5 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

[1]  $V_{CCI}$  is the supply voltage associated with the input.

[2]  $V_{CCO}$  is the supply voltage associated with the output.

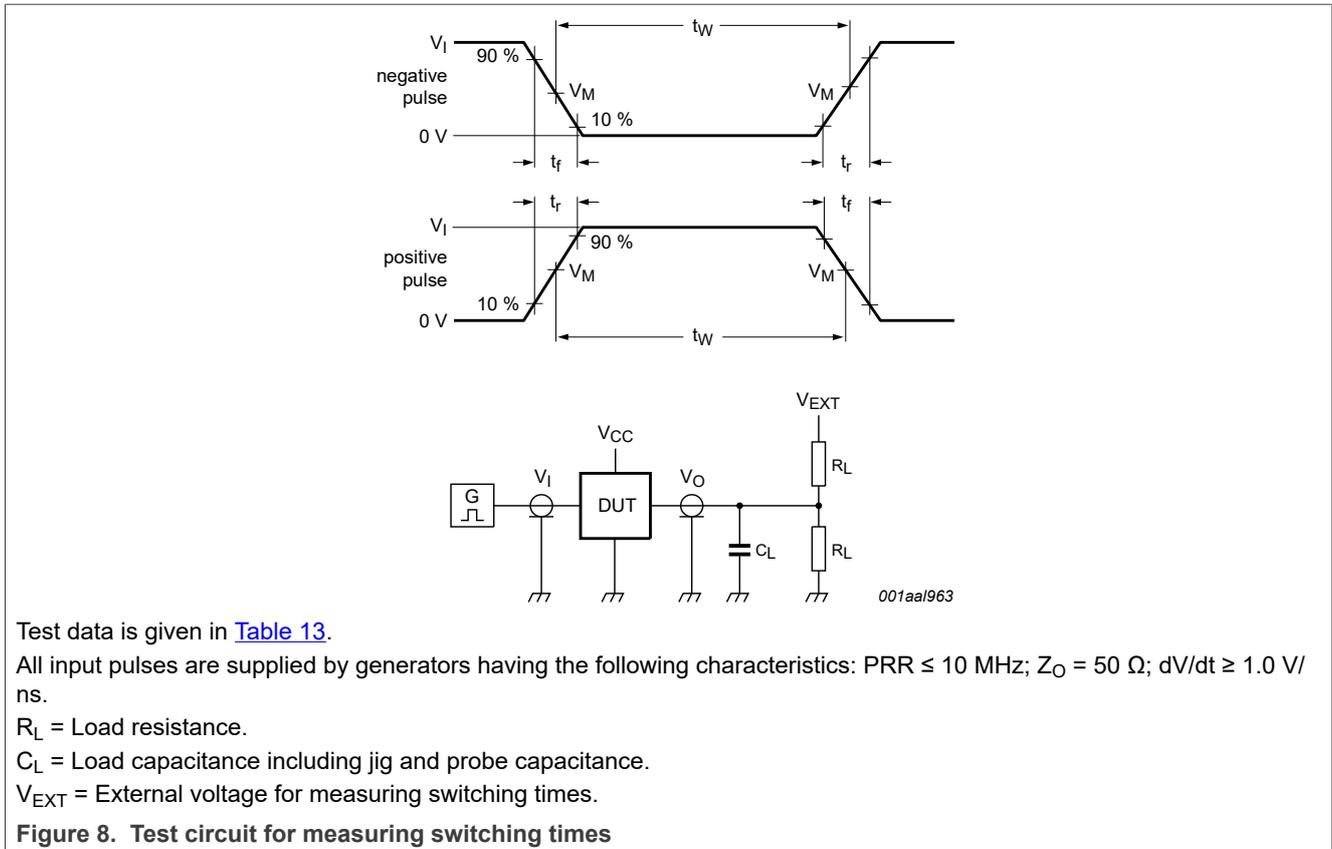


Table 13. Test data

Supply voltage		Input		Load		V <sub>EXT</sub>		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>I</sub> <sup>[1]</sup>	Δt/ΔV	C <sub>L</sub>	R <sub>L</sub> <sup>[2]</sup>	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> <sup>[3]</sup>
1.65 V to 3.6 V	2.3 V to 5.5 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

[2] For measuring data rate, pulse width, propagation delay, and output rise and fall measurements, R<sub>L</sub> = 1 MΩ; for measuring enable and disable times, R<sub>L</sub> = 50 kΩ.

[3] V<sub>CCO</sub> is the supply voltage associated with the output.

## 13 Application information

### 13.1 Applications

Voltage level-translation applications. The NTS0102 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I<sup>2</sup>C or 1-wire which use open-drain drivers, it may also be used in applications where push-pull drivers are connected to the ports, however the NTB0102 may be more suitable.

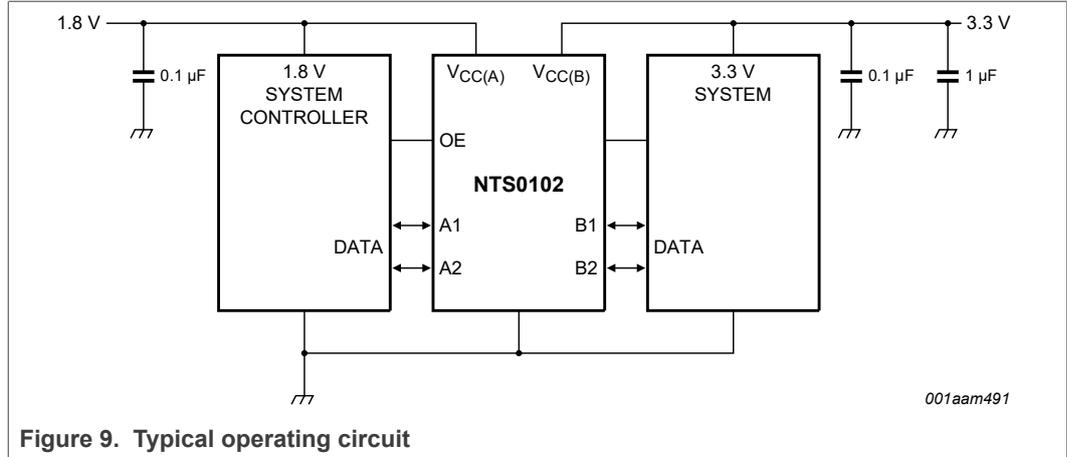


Figure 9. Typical operating circuit

13.2 Architecture

The architecture of the NTS0102 is shown in Figure 10. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.

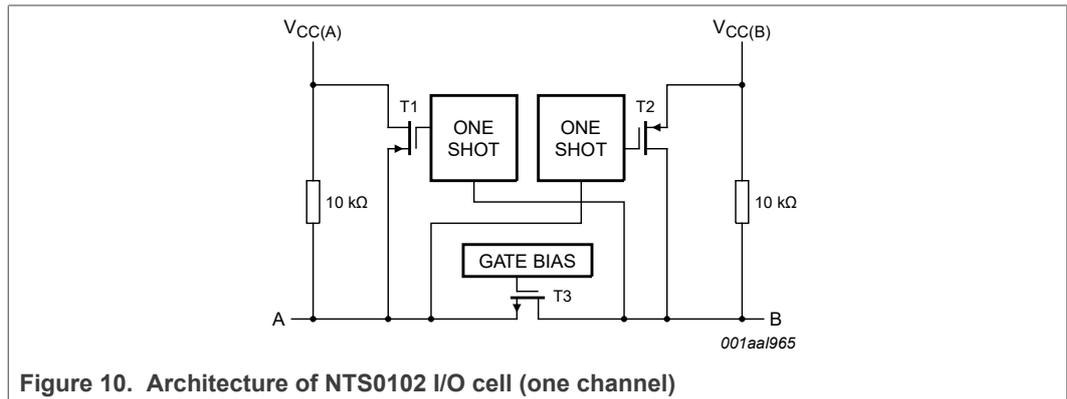


Figure 10. Architecture of NTS0102 I/O cell (one channel)

The NTS0102 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

1. A pass-gate transistor (N-channel) that ties the ports together.
2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the  $V_{CC}$  level of the low-voltage side. During a LOW-to-HIGH transition, the output one-shot accelerates the output transition by switching on the PMOS transistors (T1, T2) bypassing the 10 kΩ pull-up resistors and increasing current drive capability. The one-shot is activated once the input transition reaches approximately  $V_{CC}/2$ ; it is de-activated approximately 50 ns after the output reaches  $V_{CC}/2$ . During the acceleration time, the driver output resistance is between approximately 50 Ω and 70 Ω. To avoid signal contention and minimize dynamic  $I_{CC}$ , the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

### 13.3 Input driver requirements

As the NTS0102 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system; the max data rate, HIGH-to-LOW output transition time ( $t_{THL}$ ), and propagation delay ( $t_{PHL}$ ) are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the data sheet assume a driver with output impedance below 50  $\Omega$  is used.

### 13.4 Output load considerations

The maximum lumped capacitive load that can be driven is dependent upon the one-shot pulse duration. In cases with very heavy capacitive loading, there is a risk that the output will not reach the positive rail within the one-shot pulse duration.

To avoid excessive capacitive loading, and to ensure correct triggering of the one-shot, it's recommended to use short trace lengths and low capacitance connectors on NTS0102 PCB layouts. To ensure low impedance termination and avoid output signal oscillations and one-shot re-triggering, the length of the PCB trace should be such that the round trip delay of any reflection is within the one-shot pulse duration (approximately 50 ns).

### 13.5 Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \geq V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTS0102 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

### 13.6 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

### 13.7 Pull-up or pull-down resistors on I/Os lines

Each A port I/O has an internal 10 k $\Omega$  pull-up resistor to  $V_{CC(A)}$ , and each B port I/O has an internal 10 k $\Omega$  pull-up resistor to  $V_{CC(B)}$ . If a smaller value of pull-up resistor is required, an external resistor must be added parallel to the internal 10 k $\Omega$ , this effects the  $V_{OL}$  level. When OE goes LOW the internal pull-ups of the NTS0102 are disabled.

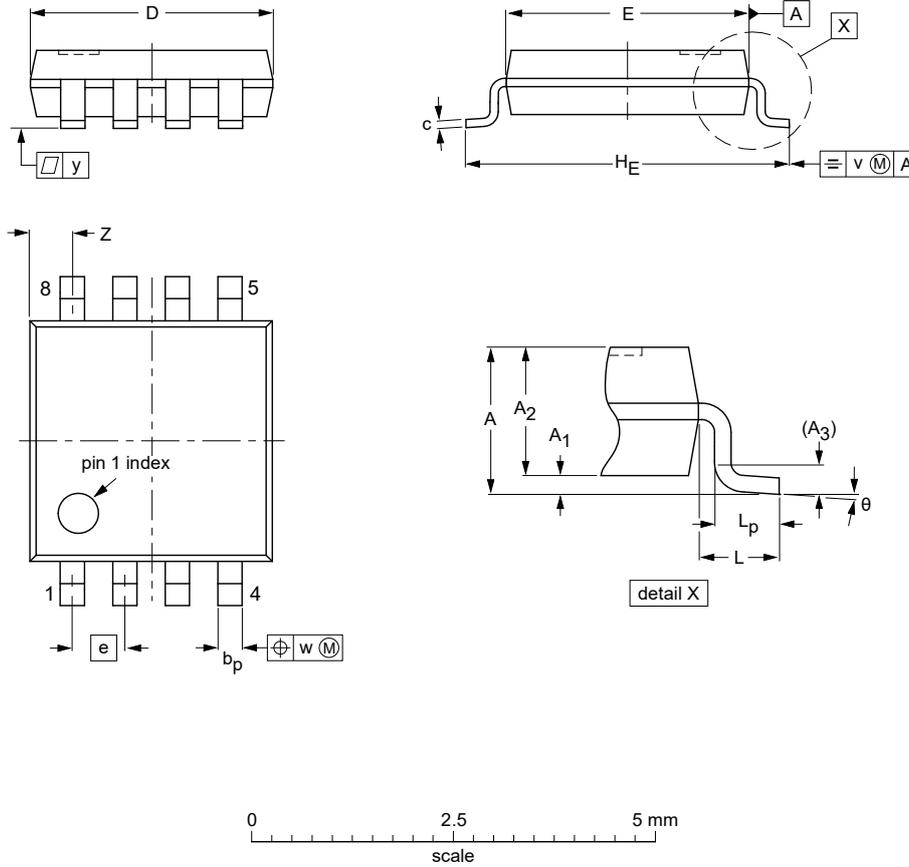
### 13.8 GD package vs TL package

Due to differences in package construction the TL package has a center pad vs no center pad for the GD package. The following section provides guidance in replacement vs new applications.

- **No trace under GD package**
  1. Replacement of GD package: The pad is not electrically connected to the silicon (no wire bond and epoxy is not conductive) and can be left floating. It is not required to be connected to the PCB. Simply place the TL package on the same PCB traces as the existing GD package.
  2. New use of the TL package: Place PCB trace for soldering of the center pad based on PCB layout recommendations for better mechanical connection and thermal conductivity. The PCB center pad can be connect to GND or left floating.
- **Trace under the GD package**
  1. Replacement of GD package: It is not best practice to have center pad over the trace but since the TL package center pad is not connected to the silicon the risk is low. If there are multiple traces there could be EMI and cross talk. In both cases the customer needs to evaluate risk.
  2. New use of the TL package: Do not route traces under the package

14 Package outline

TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm SOT505-2



DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	v	w	y	z <sup>(1)</sup>	θ
mm	1.1	0.15 0.00	0.95 0.75	0.25	0.38 0.22	0.18 0.08	3.1 2.9	3.1 2.9	0.65	4.1 3.9	0.5	0.47 0.33	0.2	0.13	0.1	0.70 0.35	8° 0°

Note

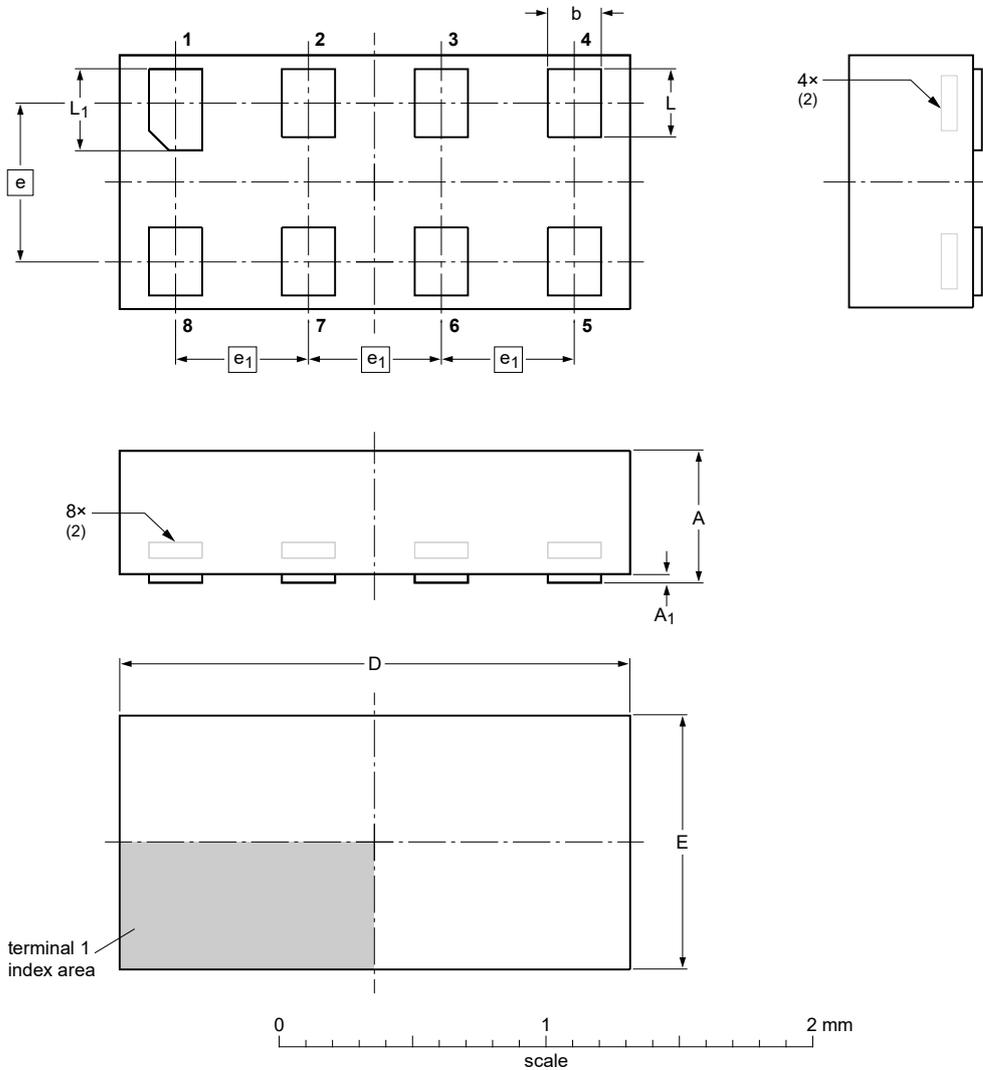
1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES			EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA		
SOT505-2		---			02-01-16

Figure 11. Package outline SOT505-2 (TSSOP8)

XSON8: plastic extremely thin small outline package; no leads; 8 terminals; body 1 x 1.95 x 0.5 mm

SOT833-1



**DIMENSIONS (mm are the original dimensions)**

UNIT	A <sup>(1)</sup> max	A <sub>1</sub> max	b	D	E	e	e <sub>1</sub>	L	L <sub>1</sub>
mm	0.5	0.04	0.25 0.17	2.0 1.9	1.05 0.95	0.6	0.5	0.35 0.27	0.40 0.32

**Notes**

1. Including plating thickness.
2. Can be visible in some manufacturing processes.

OUTLINE VERSION	REFERENCES			EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA		
SOT833-1	---	MO-252	---		07-11-14 07-12-07

Figure 12. Package outline SOT833-1 (XSON8)

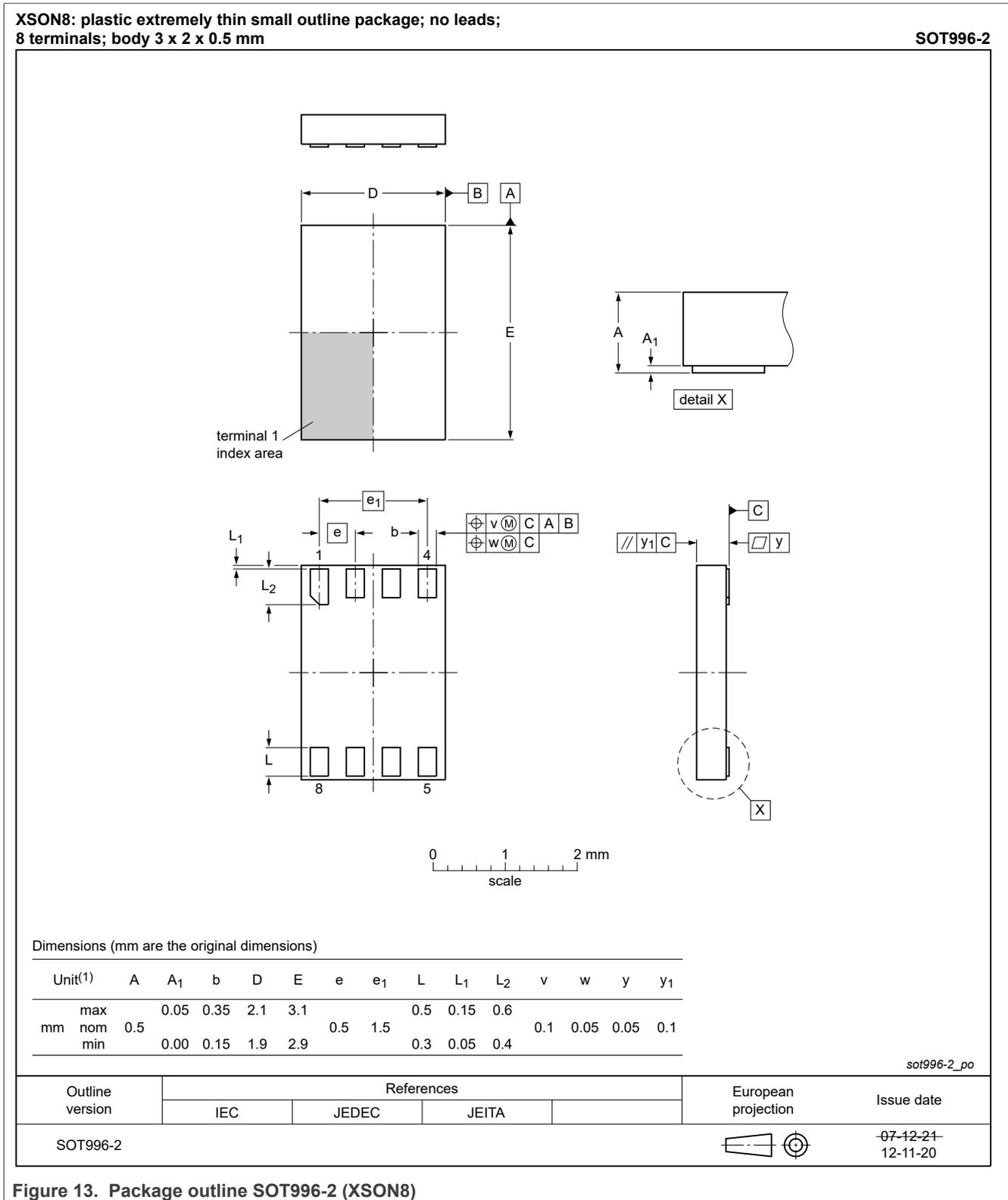


Figure 13. Package outline SOT996-2 (XSON8)

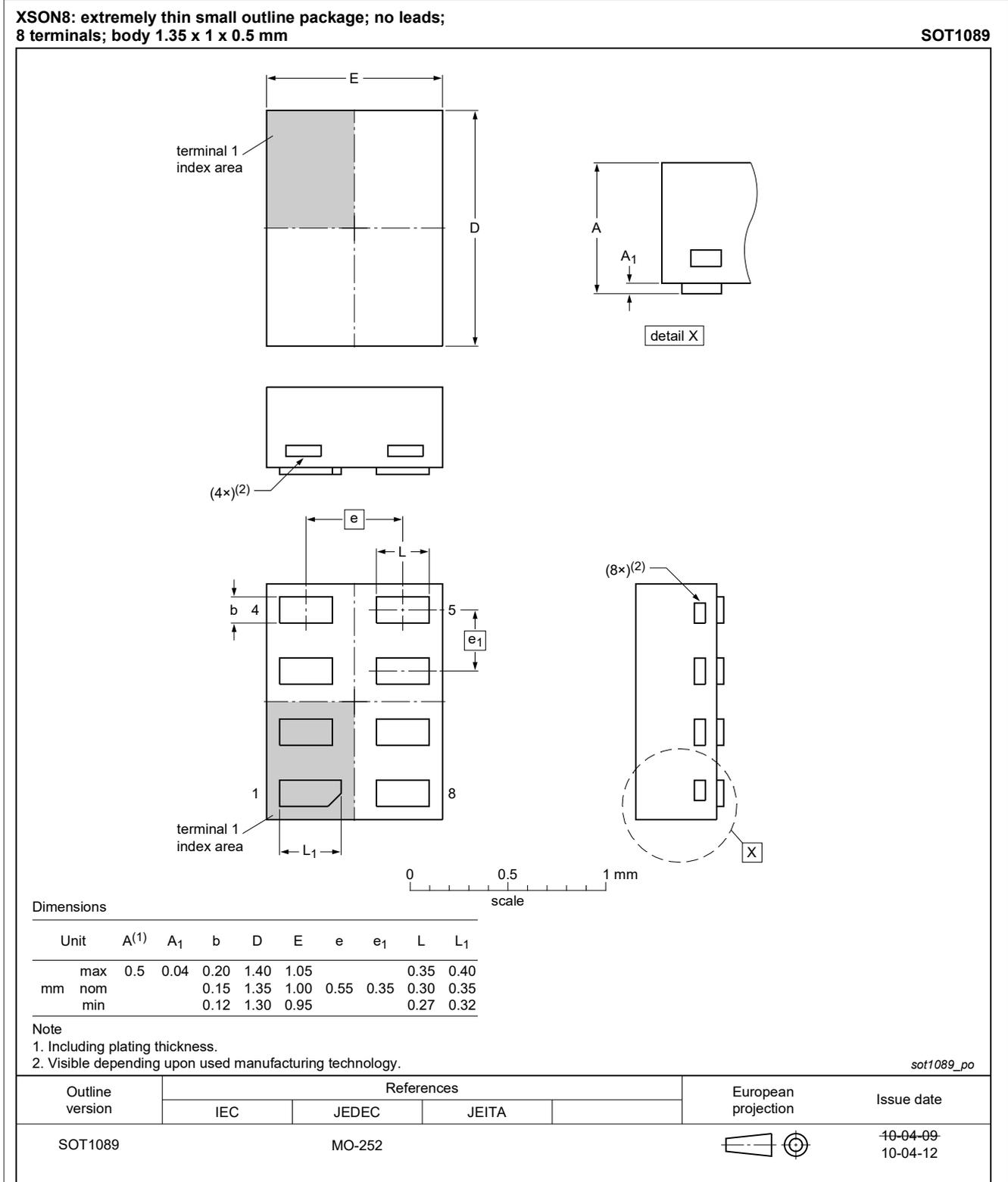
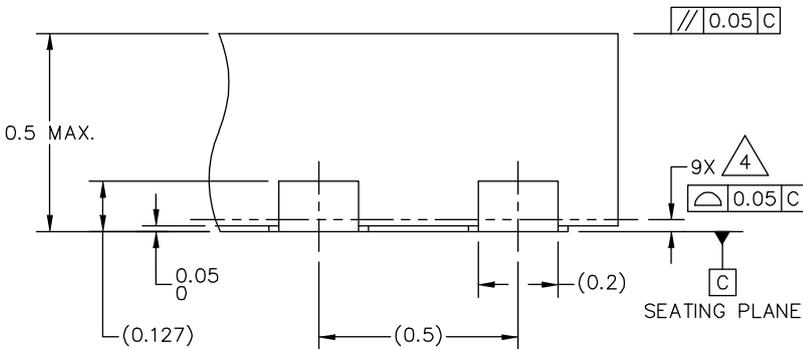


Figure 14. Package outline SOT1089 (XSON8)



H-PDFN-8 I/O  
3 X 2 X 0.5 PKG, 0.5 PITCH

SOT1052-2



DETAIL E  
VIEW ROTATED 90° CW

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DATE: 06 JAN 2022

MECHANICAL OUTLINE PRINT VERSION NOT TO SCALE	STANDARD: NON-JEDEC	DRAWING NUMBER: 98ASA01831D	REVISION: 0	
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Figure 16. Package outline SOT1052-2 (XSON8)

## 15 Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note AN10365 “Surface mount reflow soldering description”.

### 15.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### 15.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

### 15.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 15.4 Reflow soldering

Key characteristics in reflow soldering are:

Dual supply translating transceiver; open-drain; auto direction sensing

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 17](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 14](#) and [Table 15](#)

Table 14. SnPb eutectic process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm <sup>3</sup> )	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

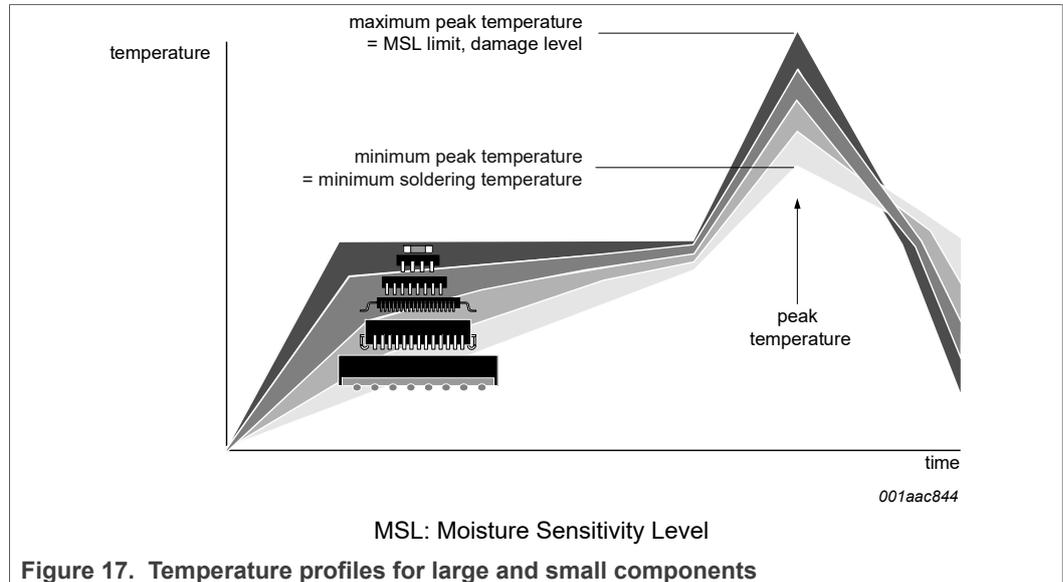
Table 15. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm <sup>3</sup> )		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 17](#).

Dual supply translating transceiver; open-drain; auto direction sensing



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

16 Soldering: PCB footprints

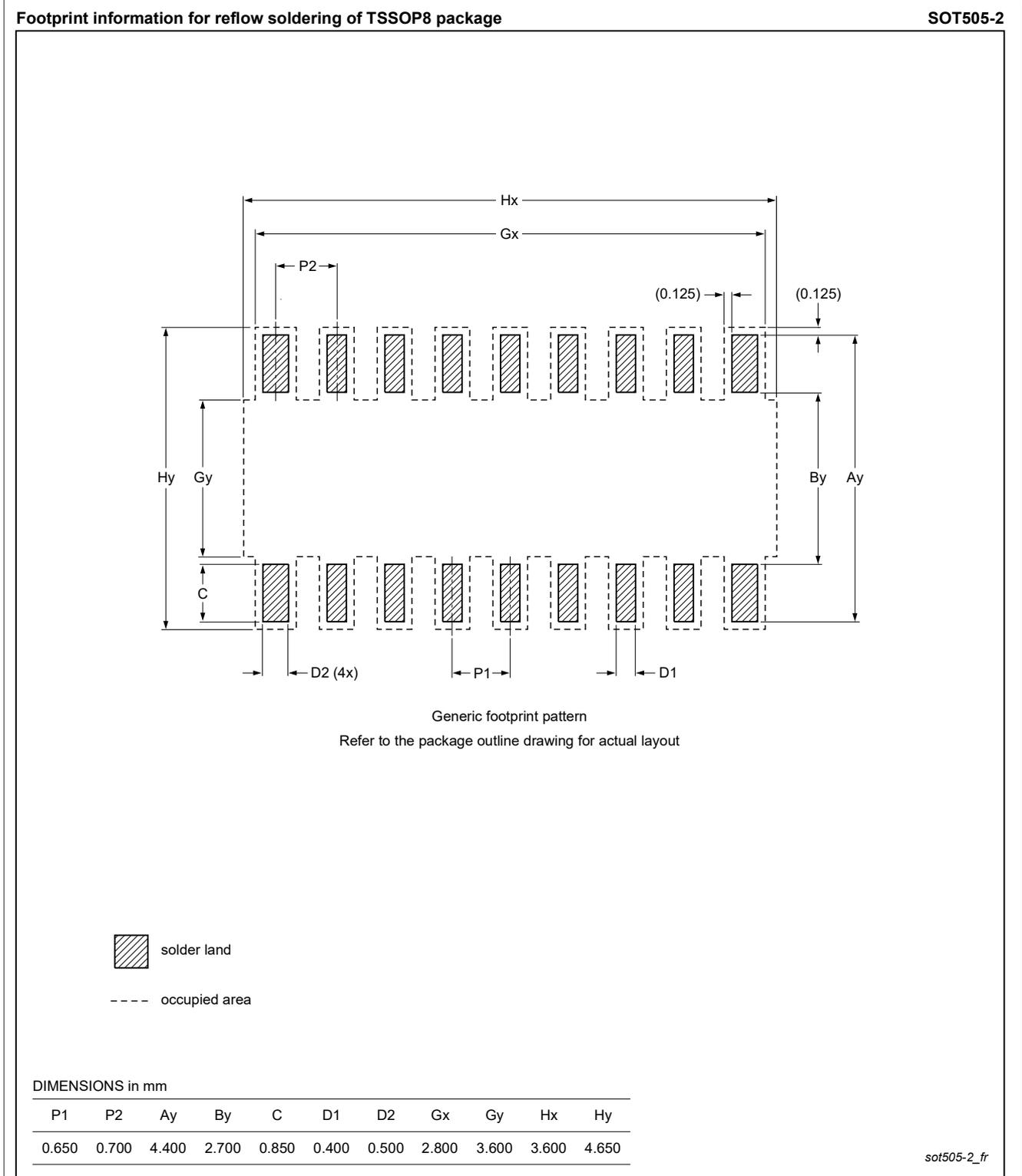


Figure 18. PCB footprint for SOT505-2 (TSSOP8); reflow soldering

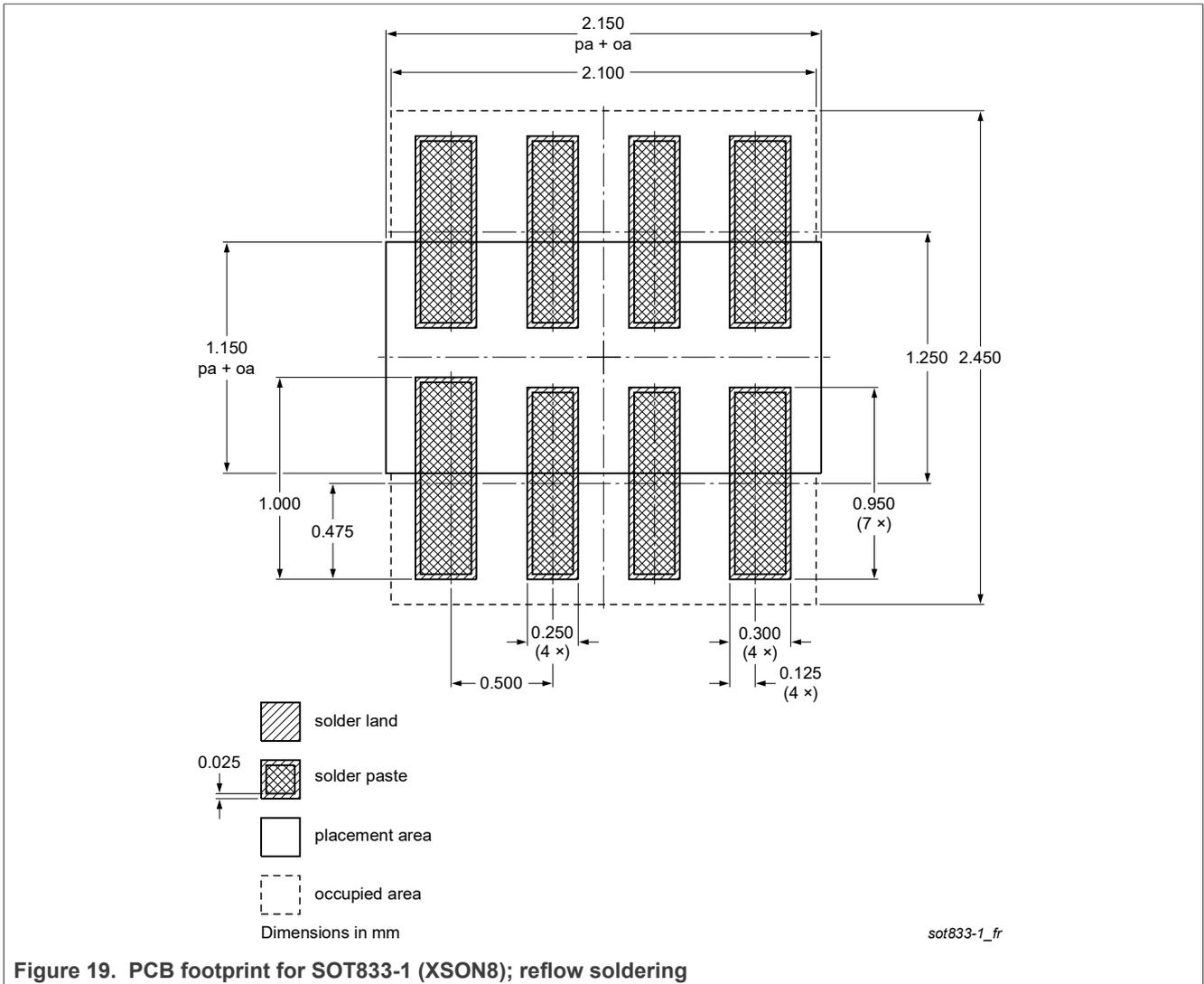


Figure 19. PCB footprint for SOT833-1 (XSON8); reflow soldering

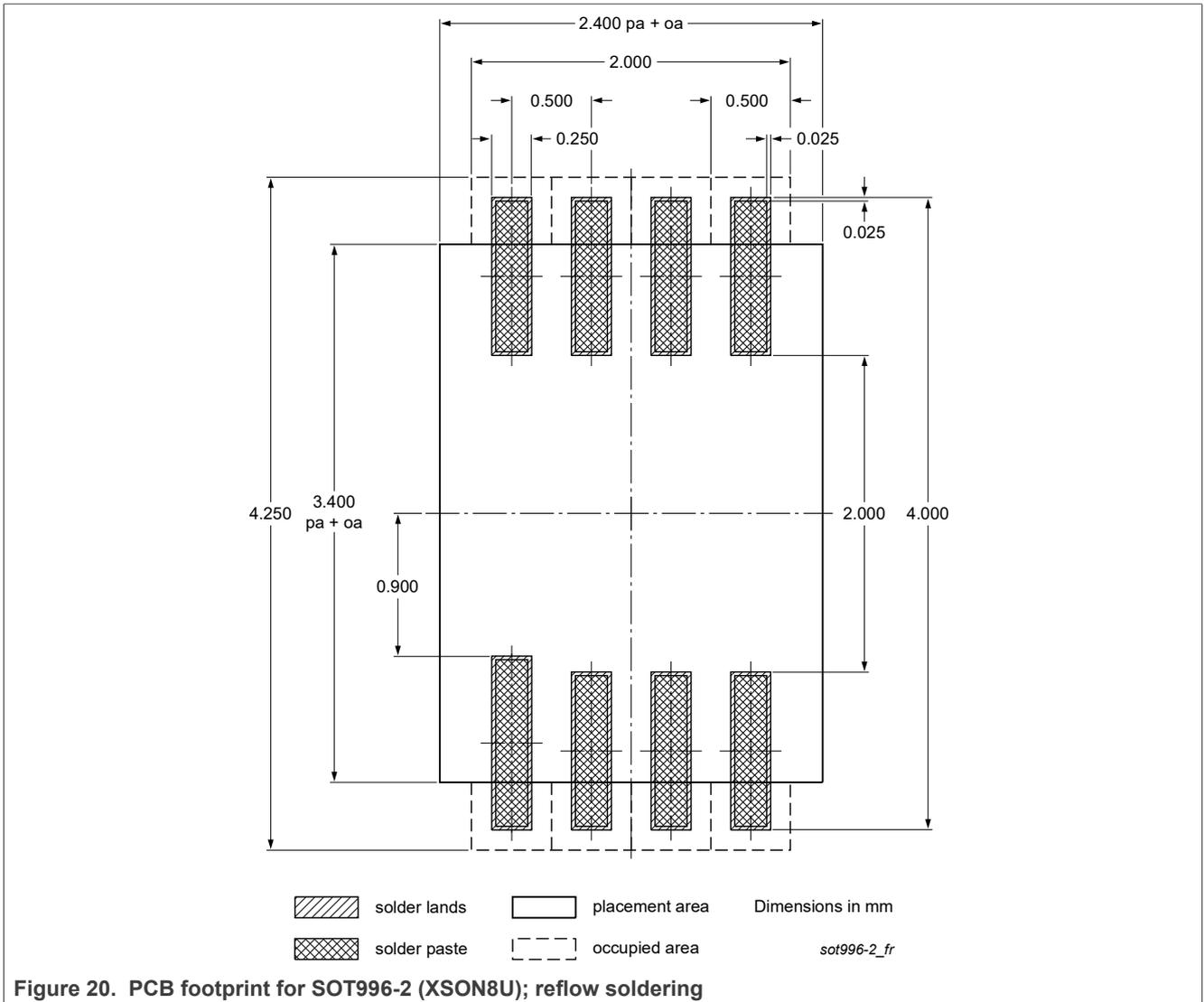


Figure 20. PCB footprint for SOT996-2 (XSON8U); reflow soldering

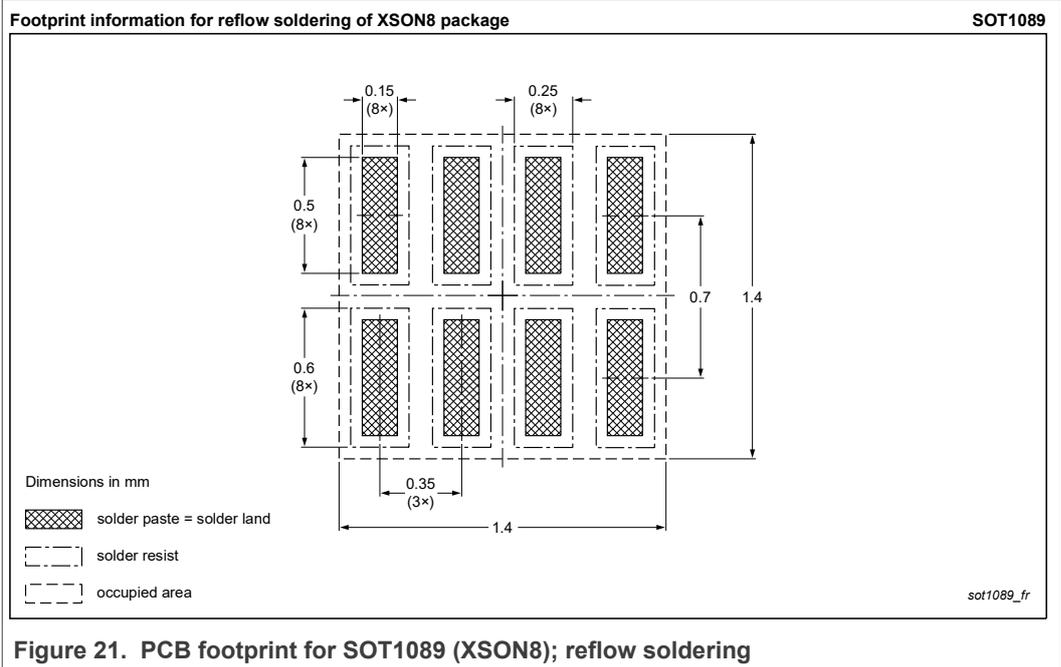
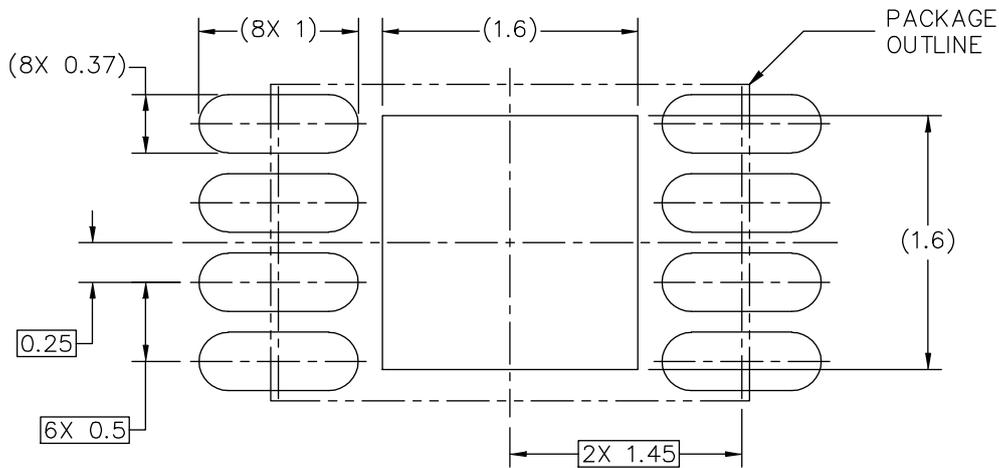


Figure 21. PCB footprint for SOT1089 (XSON8); reflow soldering

H-PDFN-8 I/O  
3 X 2 X 0.5 PKG, 0.5 PITCH

SOT1052-2



PCB DESIGN GUIDELINES  
RECOMMENDED SOLDER MASK OPENING PATTERN

THIS SHEET SERVES ONLY AS A GUIDELINE TO HELP DEVELOP A USER SPECIFIC SOLUTION. DEVELOPMENT EFFORT WILL STILL BE REQUIRED BY END USERS TO OPTIMIZE PCB MOUNTING PROCESSES AND BOARD DESIGN IN ORDER TO MEET INDIVIDUAL/SPECIFIC REQUIREMENTS.

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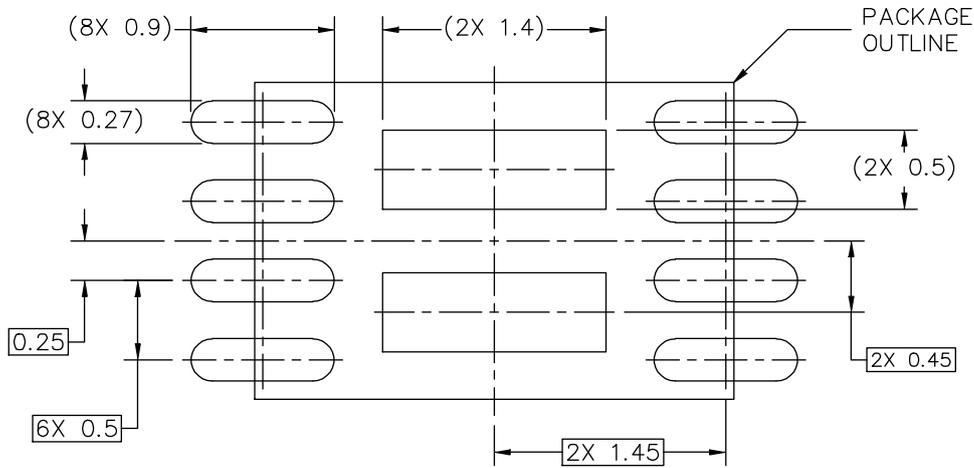
Figure 22. PCB footprint for SOT1052-2 (XSON8); recommended solder mask opening pattern



Dual supply translating transceiver; open-drain; auto direction sensing

H-PDFN-8 I/O  
3 X 2 X 0.5 PKG, 0.5 PITCH

SOT1052-2



RECOMMENDED STENCIL THICKNESS 0.125

PCB DESIGN GUIDELINES – RECOMMENDED SOLDER PASTE STENCIL

THIS SHEET SERVES ONLY AS A GUIDELINE TO HELP DEVELOP A USER SPECIFIC SOLUTION. DEVELOPMENT EFFORT WILL STILL BE REQUIRED BY END USERS TO OPTIMIZE PCB MOUNTING PROCESSES AND BOARD DESIGN IN ORDER TO MEET INDIVIDUAL/SPECIFIC REQUIREMENTS.

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Figure 24. PCB footprint for SOT1052-2 (XSON8); recommended solder paste stencil

Dual supply translating transceiver; open-drain; auto direction sensing

H-PDFN-8 I/O  
3 X 2 X 0.5 PKG, 0.5 PITCH

SOT1052-2

NOTES:

1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
3. PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY.
4. COPLANARITY APPLIES TO LEADS, DIE ATTACH FLAG.
5. MIN. METAL GAP FOR LEAD TO EXPOSED PAD SHALL BE 0.2 MM.

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Figure 25. PCB footprint for SOT1052-2 (XSON8); notes

## 17 Abbreviations

Table 16. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
GPIO	General Purpose Input Output
HBM	Human Body Model
I <sup>2</sup> C	Inter-Integrated Circuit
MM	Machine Model
PCB	Printed-circuit board
PMOS	Positive Metal Oxide Semiconductor
SMBus	System Management Bus
UART	Universal Asynchronous Receiver Transmitter
UTLP	Ultra Thin Leadless Package

## 18 Revision history

Table 17. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTS0102 v.4.4	20221006	Product data sheet	202210008I	NTS0102 v.4.3
Modifications:	<ul style="list-style-type: none"> <li><a href="#">Table 2</a>: NTS0102TL Minimum Order Quantity corrected to 4Ku per reel</li> </ul>			
NTS0102 v.4.3	20220420	Product data sheet	—	NTS0102 v.4.2
NTS0102 v.4.2	20220303	Product data sheet	—	NTS0102 v.4.1
NTS0102 v.4.1	20211112	Product data sheet	—	NTS0102 v.4
NTS0102 v.4	20130123	Product data sheet	—	NTS0102 v.3
NTS0102 v.3	20111117	Product data sheet	—	NTS0102 v.2
NTS0102 v.2	20110411	Product data sheet	—	NTS0102 v.1
NTS0102 v.1	20100921	Product data sheet	—	—

## 19 Legal information

### 19.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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## Dual supply translating transceiver; open-drain; auto direction sensing

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