

Sonoma (MAXREFDES14#) LX9 MicroBoard Quick Start Guide

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Table of Contents

1. Required Equipment	3
2. Overview	3
3. Included Files	5
4. Procedure	6
5. Code Documentation	. 18
6. Appendix A: Project Structure and Key Filenames	. 19
7. Trademarks	. 19
8. Revision History	. 20

1. Required Equipment

- PC with Windows® OS with Xilinx® ISE®/SDK version 13.4 or later and two USB ports
- License for Xilinx EDK/SDK version 13.4 or later
- 120V AC power source or wall outlet
- AC load
- Sonoma (MAXREFDES14#) board
- Avnet Spartan®-6 LX9 MicroBoard

2. Overview

Below is a high-level overview of the steps required to quickly get the Sonoma design running by downloading and running the FPGA project. Detailed instructions for each step are provided in the following pages. The Sonoma (MAXREFDES14#) subsystem reference design will be referred to as the Sonoma throughout this document.

- Connect the Sonoma board to the J5 port of a LX9 MicroBoard as shown in <u>Figure 1</u>. Ensure the connector is aligned as shown in <u>Figure 2</u>.
- 2. Connect the power supply and the load to the Sonoma board.
- 3. Download the latest **RD14V01_00.ZIP** file located at the Sonoma page.
- 4. Extract the **RD14V01_00.ZIP** file to a directory on your PC.
- 5. Open the Xilinx SDK.
- 6. Download the bitstream (.BIT) file to the board. This bitstream contains the FPGA hardware design and software bootloader.
- 7. Open a terminal program to communicate with FPGA board.
- Use Xilinx SDK to download and run the executable file (.ELF) on the MicroBlaze[™].



Figure 1. Sonoma Board Connected to LX9 Kit





Figure 2. Pmod[™] Connector Alignment

3. Included Files

The top level of the hardware design is a Xilinx ISE Project Navigator Project (.XISE) for Xilinx ISE version 13.4. The Verilog-based HDL design instantiates the MicroBlaze core, the support hardware required to run the MicroBlaze, and the peripherals that interface to the Pmod ports. This is supplied as a Xilinx software development kit (SDK) project which includes a demonstration software application to evaluate the Sonoma subsystem reference design. The lower level c-code driver routines are portable to the user's own software project.



* SPI only used.

Figure 3. Block Diagram of FPGA Hardware Design

4. Procedure

- 1. Connect the Sonoma board to the JB1 port of a LX9 MicroBoard as shown in Figure 1.
- 2. Connect the P1 USB connector of the LX9 MicroBoard directly to the computer. Or, use a USB extension cable to connect the LX9 MicroBoard to the computer.
- 3. Connect the AC power supply and the load to the Sonoma board as shown in <u>Figure 4</u>.
- Download the latest RD14V01_00.ZIP file located at <u>www.maximintegrated.com/sonoma</u>. All files available for download are available at the bottom of the page.
- 5. Extract the **RD14V01_00.ZIP** file to a directory on your PC. The location is arbitrary but the path prior to where you extract the .ZIP file must not exceed 82 characters due to the Windows 250-character total path limitation. For example, this 90-character preceding path would be an example of a path that would be too long:

C:\0123456789\0123456789\0123456789\0123456789\0123456789\0123456789\0123456789\ 0123456789\0123456789\0123456789\RD14V01_00.ZIP (This path is too long.) In addition, the Xilinx tools require the path to not contain any spaces.

C:\Do Not Use Spaces In The Path\RD14V01_00.ZIP (This path has spaces.)

For the purposes of this document, it will be **C:\designs\maxim\RD14V01_00**. See <u>Appendix A: Project Structure and Key Filenames</u> in this document for the project structure and key filenames.



Figure 4. Sonoma Power and Load Connections

6. Open the Xilinx Software Development Kit (SDK) from the Windows <u>Start</u> menu.

Xilinx ISE Design Suite 13.4	
Accessories	
퉬 ChipScope Pro	
Documentation	Ξ
🐌 EDK	
🎯 Xilinx Platform Studio	
🧼 Xilinx Software Development Kit	
Documentation	
퉬 Tools	Ŧ
4 Back	
Search programs and files	
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7. SDK will prompt for a workspace directory, which is the location where the software project is located. For this example, it is:

C:\designs\maxim\RD14V01_00\RD14_LX9_V01_00\Design_Files\sdkWorkspace

Click **OK** and SDK will open. The Xilinx SDK is based on an Eclipse[™]-based IDE, so it will be a familiar flow for many software developers.



8. Review the SDK IDE. The **Project Explorer** in the upper left tab should have three components as shown in the image below. If all three subfolders are present, you can skip the next step.



9. If the Project Explorer does not contain these three subfolders, launch the <u>File</u> | <u>Import</u> menu, expand the General folder, and select Existing Projects into Workspace. Click Next. Set the root directory to:

C:\designs\maxim\RD14V01_00\RD14_LX9_V01_00\Design_Files\sdkWorkspace

and the missing projects should appear in SDK **Project Explorer** with their checkboxes checked.

Click **Finish** to import the projects.

Mark Import
Select Create new projects from an archive file or directory.
<u>S</u> elect an import source:
type filter text
 ✓ General ☑ Archive File ☑ Existing Projects into Workspace ☑ File System ☑ Preferences ▷ ☑ C/C++ ▷ ☑ Remote Systems ▷ ☑ Run/Debug ▷ ☑ Team
(?) < <u>Back</u> <u>Next</u> > <u>Finish</u> Cancel

10. To download the bitstream (.BIT) file to the board, click on the **Program FPGA** icon (which looks like a green chain of devices).



The **Program FPGA** dialog box appears. From here, an FPGA bitstream (.BIT) file is selected as well as an FPGA bmm (.BMM) file. Be sure to select the .BIT file and the .BMM by using the paths below.

Bitstream:

```
C:\designs\maxim\RD14V01_00\RD14_LX9_V01_00\Design_Files\
sdkWorkspace\system_hw_platform\system.bit
```

BMM File:

C:\designs\maxim\RD14V01_00\RD14_LX9_V01_00\Design_Files\ sdkWorkspace\system_hw_platform\system_bd.bmm

Also make sure the bootloop file is selected as shown, then press **Program**.

Program FPGA			X
Program FPGA Specify the bitstre	╺ <mark>⟩-</mark> ⊡-		
Hardware Specifi	ation: path filled in autor	natically	
Bitstream: BMM File:	nter the path from the ir	nstructions	Browse
Processor	ELF File to Initialize in Block RAM		
microblaze_0	bootloop	•	
?			Program Cancel

It takes approximately 10 seconds to download the FPGA and a message box indicating **FPGA configuration complete** appears.

11. Set up the terminal program to run on the PC using the following steps. Before loading the executable firmware file on the FPGA, the terminal program on the PC should be running. The example firmware running on the FPGA communicates with the PC via a USB port set up to emulate a serial port (UART). To establish this communication link, the PC must be configured with the appropriate Windows drivers. A suitable terminal program such as Tera Term or HyperTerminal should be invoked.

The micro USB (J3) on the LX9 is the communication port. The LX9 utilizes the Silicon Labs CP2102 USB-UART bridge IC, so you need to install Silicon Labs' virtual COM port (VCP) driver for their CP210x device family. These may be obtained from the Silicon Labs website (www.silabs.com).

Once installed, Windows will assign a previously unused COM port. Use the Windows <u>Control Panel</u> | <u>System</u> | <u>Device Manager</u> to determine the COM port number. (It will be named Silicon Labs CP210x USB to UART Bridge.) Make a note of which COM port this is. That information is needed in the next step.

Next, a terminal emulation program needs to be installed and launched. For Windows XP® and earlier systems, the HyperTerminal program is the usual choice. However, since HyperTerminal was eliminated from Windows 7, it may be necessary to locate an alternative. Several are available; one good choice is called Tera Term (http://ttssh2.sourceforge.jp/). Whatever terminal program you choose, the communication should be set up by opening the COM port number previously described above and the port configured as:

bits per second: 115200;

data bits: 8;

parity: none;

stop bits: 1;

flow control: **none**.

12. Use the Xilinx SDK to download and run the executable ELF (.ELF) file on the MicroBlaze using the following steps.

Right-click the mouse while the **MAXREFDES14 C** project is selected, choose the **Run As** menu, and then **Run Configurations...** menu as shown below.

Project Expl		New	۲		🛞 Mał	
		Go Into			®	
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D 📂 MAXRE		Сору	Ctrl+C		1	
⊳ 进 system_	Ê	Paste	Ctrl+V		Right	Click Mouse on
	×	Delete	Delete			REFDESX C project
		Move				
		Rename	F2		Selec	t Run As
	2	Import				
	4	Export			Run (Configurations
		Build Project				garatononi
		Clean Project				
	5	Refresh	F5			
		Close Project				
		Close Unrelated Projects				
		Build Configurations	•			
		Make Targets				
		Index	+			
		Show in Remote Systems view Convert To				
				📮 Console 🛿 🔲 Properti	ies 🖉 1	
	7	Format Project With Jindent Run As	•	1 Launch on Hardware		
	•	Debug As		2 Local C/C++ Application		
		Profile As		 3 Remote ARM Linux Appli 		,
		Team				
1		(Com		Run Configurations		

Next, double-click the mouse on the Xilinx C/C++ ELF menu.

Run Configurations	Contract of the second state of the second sta	×
Create, manage, and run confi	gurations	
Image: Second system Image: Second system	Configure launch settings from this dialog: [•] Press the 'New' button to create a configuration of the selected type. [•] Press the 'Duplicate' button to copy the selected configuration. [•] Press the 'Delete' button to remove the selected configuration. [•] Press the 'Delete' button to configure filtering options. [•] Press the 'Filter' button to configuration by selecting it. Configure launch perspective settings from the Perspectives preference page.	
?	Run	Close

Next, press the **Search Project** button.

💀 Run Configurations		
Create, manage, and run confi Ø Program not specified	gurations	
Yee Image: Second	Name: MAXREFDESX Debug	STDIO Connection R Profile Options Debugger Options Common Search Project Browse Browse O Disable auto build Configure Workspace Settings erminal.
✓ III ► Filter matched 6 of 6 items		Apply Revert
?		Run Close

Program Selection
Choose a <u>p</u> rogram to run:
Binaries:
MAXREFDESX.elf
Qualifier:
microblazele - /MAXREFDESX/Debug/MAXREFDESX.elf microblazele - /MAXREFDESX/Release/MAXREFDESX.el
۰ III ا
OK Cancel

Double-click on the **MAXREFDES14.elf** binary.

🚳 Run Configurations		
Create, manage, and run confi	gurations	
Image: Second system type filter text Image: C/C++ Application Image: C/C++ Remote Application Image: Launch Group Remote ARM Linux Applicati Xilinx C/C++ ELF Image: MAXREFDESX Debug	Name: MAXREFDESX Debug	STDIO Connection Profile Options Debugger Options Common Search Project Browse Browse O Disable auto build Configure Workspace Settings terminal.
		Apply Revert
?		<u>R</u> un Close

Verify the application is selected on the **Main** tab and press the **Run** button.

Once the Debug/MAXREFDES14 configuration is setup once, you just need to press the **Run** button if you ever want to run the program again.



At this point, the application is running on the MicroBlaze and the terminal program should show the menu below. Make the desired selections by pressing the appropriate keys on the keyboard. For example, to select **Register Read** command, press **0**.

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5. Code Documentation

Code documentation can be found at: C:\...\RD14V01_00\RD14_LX9_V01_00\Code_Documentation\

χ	VXX_XX ▶ RDX_LX9_VXX_XX ▶ Code_Docume	ntation 🕨	- 4 ∳ St	earch Code_Doo
1	are with 🔻 New folder			
	Name	Date modified	Туре	Size
	鷆 html	8/7/2013 10:10 AM	File folder	
	퉬 latex	8/7/2013 10:10 AM	File folder	
	🔊 MainPage.html	3/29/2013 2:57 PM	HTML Document	1 KB
	MAXREFDESX_Code_Documentation.pdf	8/2/2013 4:43 PM	Adobe Acrobat 7	254 KB

To view the code documentation in HTML format with a browser, open the **MainPage.html** file.

To view the code documentation in pdf format with a PDF reader, open the **MAXREFDES14_Code_Documentation.pdf** file.

6. Appendix A: Project Structure and Key Filenames



7. Trademarks

Eclipse is a trademark of Eclipse Foundation, Inc.

MicroBlaze is a trademark of Xilinx, Inc.

Pmod is a trademark of Digilent Inc.

Spartan-6 is a registered trademark of Xilinx, Inc.

Windows is a registered trademark and registered service mark and Windows XP is a registered trademark of Microsoft Corporation.

Xilinx is a registered trademark and registered service mark of Xilinx, Inc.

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0	9/13	Initial release		_

8. Revision History