General Description

The MAX4265–MAX4270 ultra-low distortion, voltage-feedback op amps are capable of driving a 100 Ω load while maintaining ultra-low distortion over a wide bandwidth. They offer superior spurious-free dynamic range (SFDR) performance: -90dBc at 5MHz and -59dBc at 100MHz (MAX4269). Additionally, input voltage noise density is 8nV/VHz while operating from a single +4.5V to +8.0V supply or from dual ±2.25V to ±4.0V supplies. These features make the MAX4265–MAX4270 ideal for use in high-performance communications and signal-processing applications that require low distortion and wide bandwidth.

The MAX4265 single and MAX4268 dual amplifiers are unity-gain stable. The MAX4266 single and MAX4269 dual amplifiers are compensated for a minimum stable gain of +2V/V, while the MAX4267 single and MAX4270 dual amplifiers are compensated for a minimum stable gain of +5V/V.

Applications

Base-Station Amplifiers IF Amplifiers High-Frequency ADC Drivers High-Speed DAC Buffers RF Telecom Applications High-Frequency Signal Processing

Pin Configurations appear at end of data sheet.

Features

- Operates from +4.5V to +8.0V
- Superior SFDR with 100Ω Load
 -90dBc (fc = 5MHz)
 -59dBc (fc = 100MHz)
- 35dBm IP3 (f_C = 20MHz)
- ♦ 8nV/√Hz Voltage Noise Density
- ♦ 100MHz 0.1dB Gain Flatness (MAX4268)
- ♦ 900V/µs Slew Rate
- ♦ ±45mA Output Driving Capability
- Disable Mode Places Outputs in High-Impedance State

Ordering Information

PIN-PACKAGE PART TEMP. RANGE MAX4265EUA -40°C to +85°C 8 µMAX MAX4265ESA -40°C to +85°C 8 SO -40°C to +85°C MAX4266EUA 8 µMAX MAX4266ESA -40°C to +85°C 8 SO MAX4267EUA -40°C to +85°C 8 µMAX MAX4267ESA -40°C to +85°C 8 SO MAX4268EEE -40°C to +85°C 16 QSOP -40°C to +85°C MAX4268ESD 14 SO MAX4269EEE -40°C to +85°C 16 QSOP MAX4269ESD -40°C to +85°C 14 SO MAX4270EEE -40°C to +85°C 16 QSOP MAX4270ESD -40°C to +85°C 14 SO

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Selector Guide

PART	NO. OF OP AMPS	MIN GAIN (V/V)	-3dB BANDWIDTH (MHz)	GBP (MHz)	FULL-POWER BANDWIDTH (MHz)
MAX4265	1	1	400	400	270
MAX4266	1	2	350	700	350
MAX4267	1	5	300	1500	300
MAX4268	2	1	300	300	175
MAX4269	2	2	350	700	200
MAX4270	2	5	200	1000	200

_ Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

Supply Voltage (V _{CC} to V _{EE})+8.5V Voltage on Any Other Pin(V _{EE} - 0.3V) to (V _{CC} + 0.3V) Short-Circuit Duration (V _{OUT} to V _{CC} or V _{EE})Continuous
Continuous Power Dissipation ($T_A = +70^{\circ}C$)
8-Pin µMAX (derate 4.10mW/°C above +70°C)330mW
16-Pin QSOP (derate 8.33mW/°C above +70°C)667mW
8-Pin SO (derate 5.9mW/°C above +70°C)471mW
14-Pin SO (derate 8.33mW/°C above +70°C)667mW

Operating Temperature Range	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

PARAMETER	PARAMETER SYMBOL CONDITIONS		MIN	ΤΥΡ	MAX	UNITS
Operating Supply Voltage Range	V _{CC}	Inferred from PSRR test	4.5		8.0	V
Common-Mode Input Voltage	V _{CM}	Inferred from CMRR test	V _{EE} + 1.6		V _{CC} - 1.6	V
Input Offset Voltage	Vos			1	9	mV
Input Offset Voltage Drift	TCVOS			1.5		µV/°C
Input Offset Voltage Channel Matching		MAX4268/MAX4269/MAX4270		1		mV
Input Bias Current	IB			3.5	40	μA
Input Offset Current	IOS			0.1	6	μA
Common-Mode Input Resistance	RINCM	Either input (V _{EE} + 1.6V) \leq V _{CM} \leq (V _{CC} - 1.6V)		1		MΩ
Differential Input Resistance	RINDIFF	$-10mV \le V_{IN} \le 10mV$		40		kΩ
Common-Mode Rejection Ratio	CMRR	$(V_{EE} + 1.6V) \le V_{CM} \le (V_{CC} - 1.6V)$, no load	60	85		dB
Power-Supply Rejection Ratio	PSRR	$V_{CC} = 4.5 V$ to 8.0 V	60	85		dB
Open-Loop Voltage Gain	AOL	$1.75V \le V_{OUT} \le 3.25V$	60	95		dB
Output Voltage Swing	Vout	V _{CC} - V _{OH} , V _{OL} - V _{EE}		1.1	1.5	V
Output Current Drive	lout	$R_L = 20\Omega$	±30	±45		mA
Output Short-Circuit Current	I _{SC}	Sinking or sourcing to V_{CC} or V_{EE}		100		mA
Closed-Loop Output Resistance	Rout			0.035		Ω
Power-Up Time	tpwrup.	$V_{OUT} = 1V$ step, 0.1% settling time		10		μs
Quiescent Supply Current	Is	Normal mode, $\overline{\text{DISABLE}} = V_{\text{CC}}$ or floating		28	32	mA
(per amplifier)	15	Disable mode, $\overline{\text{DISABLE}} = V_{\text{EE}}$		1.6	5	ШA
Disable Output Leakage Current		$\overline{\text{DISABLE}} = V_{\text{EE}}, V_{\text{EE}} \leq V_{\text{OUT}} \leq V_{\text{CC}}$		0.2	2.5	μΑ
DISABLE_ Logic Low					V _{CC} - 3.5	V
DISABLE_ Logic High			V _{CC} - 1.5			V
DISABLE_ Logic Input Low Current		$\overline{\text{DISABLE}} = \text{V}_{\text{EE}}$		5	100	μΑ
DISABLE_ Logic Input High Current		DISABLE_ = V _{CC}		1	30	μA

AC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS		MIN	ТҮР	MAX	UNITS
			MAX4265		400		
		V _{OUT} = 100mVp-p	MAX4266		350]
			MAX4267		300		MHz
Small-Signal -3dB Bandwidth	BW-3dB		MAX4268		300		
			MAX4269		350		
			MAX4270		200		
			MAX4265		270		
			MAX4266		350		
Full Davies Daviely islate			MAX4267		300		
Full-Power Bandwidth	FPBW	V _{OUT} = 1Vp-p	MAX4268		175		MHz
			MAX4269		200		
			MAX4270		200		
	BW _{0.1dB}		MAX4265		80		MHz
0.1dB Gain Flatness		V _{OUT} = 100mVp-p	MAX4266		30		
			MAX4267		55		
			MAX4268		100		
			MAX4269		35		
			MAX4270		35		
All-Hostile Crosstalk		f = 10MHz			85		dB
Slew Rate	SR	V _{OUT} = +1V step			900		V/µs
Rise/Fall Times	t _R , t _F	V _{OUT} = +1V step			1		ns
Settling Time (0.1%)	ts,0.1	V _{OUT} = +1V step			15		ns
			$f_{\rm C} = 1 {\rm MHz}$		83		
		V _{OUT} = 1Vp-p	$f_{\rm C} = 5 {\rm MHz}$		85		
		(MAX4265/	$f_{\rm C} = 10 {\rm MHz}$		87		7
		MAX4266/	$f_{\rm C} = 20 {\rm MHz}$		81		
		MAX4267)	$f_{\rm C} = 60 {\rm MHz}$		50		
Spurious-Free	SFDR		$f_{\rm C} = 100 {\rm MHz}$		47		
Dynamic Range	SFDR		$f_{\rm C} = 1 \rm MHz$		85		dBc
			$f_{\rm C} = 5 {\rm MHz}$		85]
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		84		
		(MAX4268)	$f_{\rm C} = 20 \text{MHz}$		79		
			$f_{\rm C} = 60 \text{MHz}$		68		
			$f_{\rm C} = 100 \text{MHz}$		60		1

AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CC	NDITIONS	MIN	ТҮР	MAX	UNITS
			$f_{C} = 1MHz$		88		
		V _{OUT} = 1Vp-p (MAX4269)	$f_{\rm C} = 5 {\rm MHz}$		90		
			$f_{\rm C} = 10 {\rm MHz}$		88		
			$f_{\rm C} = 20 MHz$		79		
			$f_{\rm C} = 60 \text{MHz}$		68		
Spurious-Free			$f_{\rm C} = 100 \text{MHz}$		59		-ID -
Dynamic Range	SFDR		$f_{\rm C} = 1 \rm MHz$		86		dBc
			$f_{\rm C} = 5 {\rm MHz}$		81		
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		75		
		(MAX4270)	$f_{\rm C} = 20 \text{MHz}$		68		
			$f_{\rm C} = 60 \text{MHz}$		60]
			$f_{\rm C} = 100 \text{MHz}$		56		1
		V _{OUT} = 1Vp-p (MAX4265/ MAX4266/ MAX4267)	$f_{\rm C} = 1 \rm MHz$		83		
			$f_{\rm C} = 5 {\rm MHz}$		85		
			$f_{\rm C} = 10 \rm MHz$		87		
			$f_{\rm C} = 20 \text{MHz}$		81		
			$f_{\rm C} = 60 \text{MHz}$		50		
			$f_{\rm C} = 100 \text{MHz}$		47		
			$f_{\rm C} = 1 \rm MHz$		85		
			$f_{\rm C} = 5 MHz$		85		
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		84		
		(MAX4268)	$f_{\rm C} = 20 MHz$		79		
			$f_{\rm C} = 60 \text{MHz}$		68		
Second Harmonic			$f_{\rm C} = 100 {\rm MHz}$		60		
Distortion			$f_{\rm C} = 1 \rm MHz$		88		dBc
			$f_{\rm C} = 5 MHz$		90		-
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		88		
		(MAX4269)	$f_{\rm C} = 20 MHz$		79		
			$f_{\rm C} = 60 \text{MHz}$		68		1
			$f_{\rm C} = 100 \text{MHz}$		59		1
			$f_{\rm C} = 1 \rm MHz$		86		1
			$f_{\rm C} = 5 {\rm MHz}$		81		
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 \rm MHz$		75		
		(MAX4270)	$f_{\rm C} = 20 \text{MHz}$		68		
			$f_{\rm C} = 60 \text{MHz}$		60		
			$f_{\rm C} = 100 \text{MHz}$		56		1

AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL		NDITIONS	MIN	ТҮР	MAX	UNITS	
			$f_{\rm C} = 1 {\rm MHz}$		98			
		V _{OUT} = 1Vp-p (MAX4265/ MAX4266/	$f_{\rm C} = 5 {\rm MHz}$		96			
			$f_{\rm C} = 10 {\rm MHz}$		91			
			$f_{\rm C} = 20 {\rm MHz}$		85			
		MAX4267)	$f_{\rm C} = 60 {\rm MHz}$		75			
			$f_{\rm C} = 100 {\rm MHz}$		61			
			$f_{C} = 1MHz$		95			
			$f_{\rm C} = 5 {\rm MHz}$		95		dBc	
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		93			
	Vou	(MAX4268)	$f_{\rm C} = 20 {\rm MHz}$		86			
			$f_{\rm C} = 60 {\rm MHz}$		72			
Third Harmonic			$f_{\rm C} = 100 {\rm MHz}$		64			
Distortion		V _{OUT} = 1Vp-p (MAX4269)	$f_{\rm C} = 1 {\rm MHz}$		88			
			$f_{\rm C} = 5 {\rm MHz}$		90			
			$f_{\rm C} = 10 {\rm MHz}$		88			
			$f_{\rm C} = 20 {\rm MHz}$		79			
			$f_{\rm C} = 60 {\rm MHz}$		68			
			$f_{\rm C} = 100 {\rm MHz}$		59			
			$f_{\rm C} = 1 {\rm MHz}$		96			
			$f_{\rm C} = 5 {\rm MHz}$		97			
		V _{OUT} = 1Vp-p	$f_{\rm C} = 10 {\rm MHz}$		91			
		(MAX4270)	$f_{\rm C} = 20 {\rm MHz}$		84			
			$f_{\rm C} = 60 {\rm MHz}$		74			
			$f_{\rm C} = 100 {\rm MHz}$		69			
		V _{OUT} = 1Vp-p,	MAX4265/MAX4268		32			
Two-Tone, Third-Order ntercept Distortion	IP3 $f_{CA} = 2$	$f_{CA} = 20MHz$,	MAX4266/MAX4269		35		dBm	
		$f_{CB} = 21.25 MHz$	MAX4267/MAX4270		35			

AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4260/MAX4269 A_V = +2V/V, MAX4260/MAX4260/MAX4269 A_V = +2V/V, MAX4260/MAX420/MAX420/MAX4260/MAX4260/MAX4260/MAX4260/MAX4260/MAX4260/MAX4260$ MAX4267/MAX4270 Av = +5V/V, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)

			-			
SYMBOL	CONDITIONS			ТҮР	МАХ	UNITS
	$f_{\rm C} = 20 {\rm MHz}$			12		dBm
DG	NTSC, f = 3.58M	Hz, R _L = 150 Ω to V _{CC} /2		0.015		%
DP	NTSC, f = 3.58M	Hz, R _L = 150 Ω to V _{CC} /2		0.03		degrees
CIN				2		рF
Rout	f = 10MHz			1		Ω
	$\overline{\text{DISABLE}} = V_{\text{EE}}$			5		рF
t _{EN}	$V_{IN} = +1V$			100		ns
tDIS	$V_{IN} = +1V$			750		μs
		MAX4265/MAX4268		15		
	No sustained	MAX4266/MAX4269		15		рF
	oscillation	MAX4267/MAX4270	Ī	22]
en	f = 1kHz			8		nV/√Hz
in	f = 1kHz			1		pA/√Hz
	DG DP CIN ROUT tEN tDIS	$f_{C} = 20MHz$ $D_{G} NTSC, f = 3.58MH$ $D_{P} NTSC, f = 3.58MH$ C_{IN} $R_{OUT} f = 10MHz$ $\overline{DISABLE} = V_{EE}$ $t_{EN} V_{IN} = +1V$ $t_{DIS} V_{IN} = +1V$ $No sustained oscillation$ $e_{n} f = 1kHz$	$f_{C} = 20MHz$ $f_{C} = 20MHz$ D_{G} $NTSC, f = 3.58MHz, R_{L} = 150\Omega \text{ to } V_{CC}/2$ D_{P} $NTSC, f = 3.58MHz, R_{L} = 150\Omega \text{ to } V_{CC}/2$ C_{IN} R_{OUT} $f = 10MHz$ $\overline{DISABLE_{-}} = V_{EE}$ t_{EN} $V_{IN} = +1V$ t_{DIS} $V_{IN} = +1V$ $MAX4265/MAX4268$ $MAX4266/MAX4269$ $Oscillation$ $MAX4267/MAX4270$ e_{n} $f = 1kHz$	$f_{C} = 20MHz$ $f_{C} = 20MHz$ D_{G} $NTSC, f = 3.58MHz, R_{L} = 150\Omega \text{ to } V_{CC}/2$ D_{P} $NTSC, f = 3.58MHz, R_{L} = 150\Omega \text{ to } V_{CC}/2$ C_{IN} R_{OUT} $f = 10MHz$ $\overline{DISABLE_{-}} = V_{EE}$ t_{EN} $V_{IN} = +1V$ t_{DIS} $V_{IN} = +1V$ $MAX4265/MAX4268$ $MAX4266/MAX4269$ $Oscillation$ $MAX4266/MAX4270$ e_{n} $f = 1kHz$	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $

Typical Operating Characteristics

 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE} = +5V, R_{L} = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 Ay = +1V/V, MAX4266/MAX4269 Ay = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = $+25^{\circ}C$, unless otherwise noted.)



Typical Operating Characteristics (continued)

 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE} = +5V, R_{L} = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A =+25°C, unless otherwise noted.)



MAX4265-MAX4270

Typical Operating Characteristics (continued)

 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE} = +5V, R_L = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = +25°C, unless otherwise noted.)



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MAX4265-MAX4270



 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE} = +5V, R_L = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4266/MAX4268 A_V = +2V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, A_V = +2V/V, A_V = +2V/V, A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = $+25^{\circ}$ C, unless otherwise noted.)



Typical Operating Characteristics (continued)

 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE_} = +5V, R_L = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4269/MAX4269 A_V = +2V/V, A_V MAX4267/MAX4270 A_V = +5V/V, T_A = $+25^{\circ}$ C, unless otherwise noted.)



Typical Operating Characteristics (continued)

5ns/div

 $(V_{CC} = +5V, V_{EE} = 0, \overline{DISABLE} = +5V, R_L = 100\Omega$ to $V_{CC}/2$, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A =+25°C, unless otherwise noted.)



///XI/// ___

5ns/div

	PIN			
MAX4265 MAX4266 MAX4267	MAX4268 MAX4269 MAX4270		NAME	FUNCTION
8 µMAX/SO	14 SO	16 QSOP		
1		_	DISABLE	Disable Input. Active low.
_	4, 5	4, 5	DISABLEA, DISABLEB	Disable Input. Active low.
2	_	_	IN-	Inverting Input
_	2, 9	2, 11	INA-, INB-	Inverting Input
3	_	_	IN+	Noninverting Input
_	3, 10	3, 12	INA+, INB+	Noninverting Input
4, 5	6, 7	6, 7	V _{EE}	Negative Power Supply
6	_	_	OUT	Amplifier Output
_	1, 8	1, 10	OUTA, OUTB	Amplifier Output
7, 8	13, 14	15, 16	Vcc	Positive Power Supply. Connect to a +4.5V to +8.0V supply.
_	11, 12	8, 9, 13, 14	N.C.	No Connection. Not internally connected.

Pin Description

Detailed Description

The MAX4265–MAX4270 family of operational amplifiers features ultra-low distortion and wide bandwidth. Their low distortion and low noise make them ideal for driving high-speed ADCs up to 16 bits in telecommunications applications and high-performance signal processing.

These devices can drive a 100 Ω load and deliver 45mA while maintaining DC accuracy and AC performance. The input common-mode voltage ranges from (V_{EE} + 1.6V) to (V_{CC} - 1.6V), while the output typically swings to within 1.1V of the rails.

Low Distortion

The MAX4265–MAX4270 use proprietary bipolar technology to achieve minimum distortion in low-voltage systems. This feature is typically available only in dualsupply op amps.

Several factors can affect the noise and distortion that a device contributes to the input signal. The following guidelines explain how various design choices impact the total harmonic distortion (THD):

- Choose the proper feedback-resistor and gain-resistor values for the application. In general, the smaller the closed-loop gain, the smaller the THD generated, especially when driving heavy resistive loads. Largevalue feedback resistors can significantly improve distortion. The MAX4265–MAX4270's THD normally increases at approximately 20dB per decade at frequencies above 1MHz; this is a lower rate than that of comparable dual-supply op amps.
- Operating the device near or above the full-power bandwidth significantly degrades distortion (see the Total Harmonic Distortion vs. Frequency graph in the *Typical Operating Characteristics*).
- The decompensated devices (MAX4266/MAX4267/ MAX4269/MAX4270) deliver the best distortion performance since they have a slightly higher slew rate and provide a higher amount of loop gain for a given closed-loop gain setting.



Choosing Resistor Values

Unity-Gain Configurations

The MAX4265 and MAX4268 are internally compensated for unity gain. When configured for unity gain, they require a small resistor (R_F) in series with the feedback path (Figure 1). This resistor improves AC response by reducing the Q of the tank circuit, which is formed by parasitic feedback inductance and capacitance.

Inverting and Noninverting Configurations

The values of the gain-setting feedback and input resistors are important design considerations. Large resistor values will increase voltage noise and interact with the amplifier's input and PC board capacitance to generate undesirable poles and zeros, which can decrease bandwidth or cause oscillations. For example, a noninverting gain of +2V/V (Figure 1) using $R_F = R_G = 1k\Omega$ combined with 2pF of input capacitance and 0.5pF of board capacitance will cause a feedback pole at 128MHz. If this pole is within the anticipated amplifier bandwidth, it will jeopardize stability. Reducing the $1k\Omega$ resistors to 100Ω extends the pole frequency to 1.28GHz, but could limit output swing by adding 200Ω in parallel with the amplifier's load. Clearly, the selection of resistor values must be tailored to the specific application.

Distortion Considerations

The MAX4265–MAX4270 are ultra-low-distortion, highbandwidth op amps. Output distortion will degrade as the total load resistance seen by the amplifier decreases. To minimize distortion, keep the input and gain-setting resistor values relatively large. A 500 Ω feedback resistor combined with an appropriate input resistor to set the gain will provide excellent AC performance without significantly increasing distortion.

Noise Considerations

The amplifier's input-referred noise-voltage density is dominated by flicker noise at lower frequencies and by thermal noise at higher frequencies. Because the thermal noise contribution is affected by the parallel combination of the feedback resistive network, those resistor values should be reduced in cases where the system bandwidth is large and thermal noise is dominant. This noise-contribution factor decreases, however, with increasing gain settings. For example, the input noise voltage density at the op amp input with a gain of +10V/V using R_F = 100k Ω and R_G = 11k Ω is e_n = 18nV/√Hz. The input noise can be reduced to 8nV/√Hz by choosing R_F = 1k Ω , R_G = 110 Ω .

Driving Capacitive Loads

The MAX4265–MAX4270 are not designed to drive highly reactive loads. Stability is maintained with loads up to 15pF with less than 2dB peaking in the frequency response. To drive higher capacitive loads, place a small isolation resistor in series between the amplifier's output and the capacitive load (Figure 1). This resistor improves the amplifier's phase margin by isolating the capacitor from the op amp's output.

To ensure a load capacitance that limits peaking to less than 2dB, select a resistance value from Figure 2. For example, if the capacitive load is 100pF, the corresponding isolation resistor is 6Ω (MAX4266/MAX4269). Figures 3 and 4 show the peaking that occurs in the frequency response with and without an isolation resistor.

Coaxial cable and other transmission lines are easily driven when terminated at both ends with their characteristic impedance. When driving back-terminated transmission lines, the capacitive load of the transmission line is essentially eliminated.

ADC Input Buffer

Input buffer amplifiers can be a source of significant errors in high-speed ADC applications. The input buffer is usually required to rapidly charge and discharge the ADC's input, which is often capacitive (see *Driving Capacitive Loads*). In addition, since a high-speed ADC's input impedance often changes very rapidly during the conversion cycle, measurement accuracy must



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Figure 1. Noninverting Configuration



be maintained using an amplifier with very low output impedance at high frequencies. The combination of high speed, fast slew rate, low noise, and a low and stable distortion overload makes the MAX4265– MAX4270 ideally suited for use as buffer amplifiers in high-speed ADC applications.

Low-Power Disable Mode

The MAX4265–MAX4270 feature an active-low disable mode that can be used to save power <u>and place</u> the outputs in a high-impedance state. Drive DISABLE_ with logic levels, or connect DISABLE_ to V_{CC} for normal operation. In the dual versions (MAX4268/ MAX4269/ MAX4270), each individual op amp is disabled separately, allowing the devices to be used in a multiplex configuration. The supply current in low-power mode is reduced to 1.6mA per amplifier. Enable time is typically 100ns, and disable time is typically 750µs.



Figure 3a. MAX4268 Small-Signal Gain vs. Frequency Without Isolation Resistor



Figure 3c. MAX4270 Small-Signal Gain vs. Frequency Without Isolation Resistor



Figure 2. MAX4265–MAX4270 Isolation Resistance vs. Capacitive Load



Figure 3b. MAX4269 Small-Signal Gain vs. Frequency Without Isolation Resistor



Figure 4a. MAX4268 Small-Signal Gain vs. Frequency With Isolation Resistor





Figure 4b. MAX4269 Small-Signal Gain vs. Frequency With Isolation Resistor

Power Supplies, Bypassing, and Layout The MAX4265–MAX4270 operate from a single +4.5V to +8.0V supply or in a dual-supply configuration.

When operating with a single supply, connect the VEE pins directly to the ground plane. Bypass V_{CC} to ground with ceramic chip capacitors. Due to the MAX4265–MAX4270s' wide bandwidth, use a 1nF capacitor in parallel with a 0.1μ F to 1μ F capacitor. If the device is located more than 10cm from the power supply, adding a larger bulk capacitor will improve performance.

When operating with dual supplies, ensure that the total voltage across the device (V_{CC} to V_{EE}) does not exceed +8V. Therefore, supplies of $\pm 2.5V$, $\pm 3.3V$, and asymmetrical supplies are possible. For example, operation with V_{CC} = +5V and V_{EE} = -3V provides sufficient voltage swing for the negative pulses found in video signals. When operating with dual supplies, the V_{CC} pins and the V_{EE} pins should be bypassed using the same guidelines stated in the paragraph above.



Figure 4c. MAX4270 Small-Signal Gain vs. Frequency With Isolation Resistor

Because the MAX4265–MAX4270 have high bandwidth, circuit layout becomes critical. A solid ground plane provides a low-inductance path for high-speed transient currents. Use multiple vias to the ground plane for each bypass capacitor. If VEE is connected to ground, use multiple vias here, too. Avoid sharing ground vias with other signals to reduce crosstalk between circuit sections.

Avoid stray capacitance at the op amp's inverting inputs. Stray capacitance, in conjunction with the feedback resistance, forms an additional pole in the circuit's transfer function, with its associate phase shift. Minimizing the trace lengths connected to the inverting input helps minimize stray capacitance.

Chip Information

MAX4265/66/67 TRANSISTOR COUNT: 132 MAX4268/69/70 TRANSISTOR COUNT: 285 PROCESS: Bipolar



Pin Configurations

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to **www.maxim-ic.com/packages**.)



_Package Information (continued)

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M/X/M

Package Information (continued)

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MAX4265-MAX4270

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