# Sure Cross® Vibration and Temperature Sensor



## Datasheet

The Sure Cross® Vibration and Temperature Sensor works in a variety of machines to identify and predict failures in rotating machinery.



- Detects dual-axis vibration
- Provides high accuracy vibration and temperature measurements
- Manufactured with a robust zinc alloy housing
- Connects via a 1-wire serial interface
- Designed to work with *Flex*Power 1-Wire Serial Interface Node models DX80N9X1S-P6 and DX80N2X1S-P6, the 10 to 30 V dc powered 1-Wire Serial Interface Node models DX80N9X6S-P6 and DX80N2X6S-P6, MultiHop M-H6 and M-H6L radios, and Wireless Q45 Sensor Nodes DX80N2Q45VT and DX80N9Q45VT

For additional information, updated documentation, and a list of accessories, refer to Banner Engineering's website, *www.bannerengineering.com/wireless*.



#### WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition.

## Models

Model	Iodel Power Requirements Connection and Cable		Vo	
QM42VT1		3 m cable with a 5-pin M12/Euro-style male quick disconnect (QD)	Vibration and temperature using a 1-wire serial	
3.6 V dc to 5.5 V dc		150 mm (6 in) PVC cable with a 5-pin M12/Euro-style male quick disconnect (QD)	nterface	

Configure this sensor using the Sensor Configuration Tool and adapter cable BWA-USB1WIRE-001 (datasheet 170020).

ISO 10816 provides guidance for evaluating vibration velocity severity motors, pumps, fans, compressors, gear boxes, blowers, dryers, presses, and other machines that operate in the 10 to 1000 Hz frequency range.

	Machine	9	Class I	Class II	Class III	Class IV
	in/s	mm/s	Small Machines	Medium Machines	Large Rigid Foundation	Large Soft Foundation
	0.01	0.28				
	0.02	0.45				
6	0.03	0.71		good		
- L L W	0.04	1.12				
city	0.07	1.80				
Velo	0.11	2.80		satisfactory		
Vibration Velocity Vrms	0.18	4.50				
libra	0.28	7.10		unsatisfactory		
>	0.44	11.2				
	0.70	18.0				
	1.10	28.0		unacceptable		
	1.77	45.9				

Figure 1. Vibration Severity per ISO 10816



## Installation Instructions

## Connecting the Vibration/Temperature Sensor

To install the sensor to a device with a 5-pin M12/Euro-style female connector:

- 1. Align the notch in the female connector with the key in the sensor's male connector.
- 2. Gently slide the sensor end into the connector.
- 3. Rotate the threaded nut to tighten the sensor down.

#### Wiring

This sensor is designed to be plugged directly into compatible Nodes. The Node powers the sensor and periodically requests data using the 1-wire serial interface. Refer to the Class I Division 2 control drawings (p/n *143086*) for wiring specifications or limitations.

5-pin M12/Euro-style Connector (Male)	Pin	Wire Color	Sensor Connection
	1	Brown	Power IN (+), 3.6 to 5.5 V dc
	2	White	1-Wire serial device select (sinking input to sensing device)
	3	Blue	Ground (-)
3	4	Black	Not used/reserved
	5	Gray	1-Wire serial communications

## Installing the VT1 or VT2 Sensor

The vibration sensors have an X and Z axis indication on the face of the sensor. The Z axis goes in a plane through the sensor while the X is parallel to the sensor.

- Install the X axis in line with the shaft of the motor or axially.
- Install the Z axis to go into or through the motor or radial.

For the best results, install the sensor as close to the motor bearing as possible. If this is not possible, install the sensor on a surface that is in rigid connection with vibration characteristics of the motor. Using a cover shroud or other flexible mounting location may result in reduced accuracy or reduced ability to detect certain vibration characteristics.



After determining the sensor direction and location, mount the sensor for the best possible vibration sensing accuracy. Mounting options in order from least effective to most effective are as follows:

Mounting Options	Effectiveness	Description
BWA-HW-057 Thermally Conductive Adhesive tape	Least effective	Often provides a more than sufficient mounting type but does introduce some additional flex that reduces accuracy
BWA-BK-001 Flat magnet sensor bracket		Gives a solid, strong, and adjustable mount to a motor, but with a motor's curved surface it may not provide the best connection if the motor is too small for the magnet to get a full connection with the motor housing. Magnet mounts are susceptible to accidently rotation or change in sensor location if an outside force bumps or moves the sensor. This can lead to a change in sensor information that differs from the time-trended data from the previous location.
<b>BWA-BK-008</b> Curved surface magnet attached to sensor bracket via ¼-28 bolt		Curved surface magnet mounts may provide a stronger mount to smaller curved motor surfaces than a flat magnet mount and need to be oriented in the correct direction for the strongest mount. If the magnet feels loose, rotate the magnet 45° or 90° and check again for the strongest connection. Magnet mounts are susceptible to accidently rotation or change in sensor location if an outside force bumps or moves the sensor. This can lead to a change in sensor information that differs from the time-trended data from the previous location.

Mounting Options	Effectiveness	Description
<b>BWA-BK-002</b> or <b>BWA-BK-005</b> Flat bracket epoxied to motor and sensor screwed to bracket		Epoxying a bracket to a motor provides a permanent installation of the bracket to which the sensor can be attached.
Recommend using an epoxy designed for accelerometer mounting, such as Loctite Depend 330 and 7388 activator.		This more rigid mounting solution ensures some of the best sensor accuracy and frequency response, but is not flexible for future adjustments.
<b>BWA-BK-002</b> or <b>BWA-BK-005</b> Flat bracket with direct screw mount to motor and sensor	Most effective	When available, directly mounting the bracket to the motor using a ¼-28 bolt provides a rigid surface with the highest sensor accuracy and frequency response. This mounting option offers flexibility for future sensor and bracket movement.

## Configuration Instructions

## Sensor Configuration Tool

The Sensor Configuration Tool offers an easy way to manage sensor parameters, retrieve data, and visually show sensor data from a number of different sensors. The Sensor Configuration Tool software runs on any Windows machine and uses an adapter cable to connect the sensor to your computer.

Download the most recent version of the Sensor Configuration Tool from Banner Engineering's website: *www.bannerengineering.com/wireless.* The Sensor Configuration Tool currently supports the following sensors:

Sensor Type	Model	USB Adapter Cable			
Temperature and Humidity	M12FTH3Q and M12FT3Q	Model BWA-HW-006: USB-to-RS-485 adapter cable OR			
		Model BWA-UCT-900: USB to RS-485 adapter cable			
	M12FTH4Q and M12FT4Q	Model BWA-USB1WIRE-001: USB-to-RS-232 1-Wire adapter cable			
Vibration and Temperature	QM42VT1	Model BWA-USB1WIRE-001: USB-to-RS-232 1-Wire adapter cable			
	QM42VT2	Model BWA-HW-006: USB-to-RS-485 adapter cable OR			
		Model BWA-UCT-900: USB to RS-485 adapter cable OR			
		When updating the firmware, you must use one of the two USB to RS-485 adapter cables plus a splitter pigtail cable p/n $83265$			
GPS	GPS50M	Model BWA-HW-006: USB-to-RS-485 adapter cable AND a field-wireable M12/Euro-style connector or connecter with pigtail OR			
		Model BWA-UCT-900: USB to RS-485 adapter cable AND a field-wireable M12/Euro-style connector or connecter with pigtail			
U-GAGE K50U Ultrasonic	K50UX1CRA	Model BWA-USB1WIRE-001: USB-to-RS-232 1-Wire adapter cable			
	K50UX2CRA	Model BWA-HW-006: USB-to-RS-485 adapter cable OR			
		Model BWA-UCT-900: USB to RS-485 adapter cable			
	K50UX1ARA	Model BWA-USB1WIRE-001: USB-to-RS-232 1-Wire adapter cable			
	K50UX2ARA	Model BWA-HW-006: USB-to-RS-485 adapter cable OR			
		Model BWA-UCT-900: USB to RS-485 adapter cable			

## Holding Registers

By default, data is supplied to the Node every two and a half minutes, unless the Node requests the data sooner. Use the Sensor Configuration Tool to adjust the sensor's sample rate if a different value is needed. The default configuration is shown. The sensor register output data types are user configurable. Use the Sensor Configuration Tool to change the output types. All optional output types are listed below. Temperature values outside the operating range of the device are forced to the maximum or minimum values.

Sensor Register	Output Type	I/C	) Range	Holding Register Representation		
		Min	Мах	Min (Dec)	Max (Dec)	
1	Z-Axis RMS Velocity (in/sec) <sup>1, 5</sup>	0	6.5535	0	65535	
2	Z-Axis RMS Velocity (mm/sec) <sup>2, 5</sup>	0	65.535	0	65535	
3	Temperature (°F) <sup>3</sup>	-1638.4	1638.3	-32768	32767	
4	Temperature (°C) <sup>3</sup>	-1638.4	1638.3	-32768	32767	

Sensor Register	Output Type	I/	O Range	Holding Register Representation	
		Min	Мах	Min (Dec)	Max (Dec)
5	X-Axis RMS Velocity (in/sec) <sup>1, 5</sup>	0	6.5535	0	65535
6	X-Axis RMS Velocity (mm/sec) <sup>2, 5</sup>	0	65.535	0	65535

<sup>1</sup> Value = Register value  $\div$  10000

<sup>2</sup> Value = Register value  $\div$  1000

<sup>3</sup> Value = Register value  $\div$  20

<sup>4</sup> Value = Register value  $\div$  10

<sup>5</sup> Measurement bandwidth = 10 Hz to 1 kHz

<sup>6</sup> Measurement bandwidth = 1 kHz to 4 kHz

#### **Optional Output Types**

	I/O	Range	Holding Register Representation	
Optional Output Types	Min Max		Min (dec)	Max (dec)
Z-Axis Peak Acceleration (G) <sup>2, 6</sup>	0	65.535	0	65535
X-Axis Peak Acceleration (G) <sup>2, 6</sup>	0	65.535	0	65535
Z-Axis Peak Velocity Component Frequency (Hz) <sup>4, 5</sup>	0	6553.5	0	65535
X-Axis Peak Velocity Component Frequency (Hz) <sup>4, 5</sup>	0	6553.5	0	65535
Z-Axis RMS Acceleration (G) <sup>2, 5</sup>	0	65.535	0	65535
X-Axis RMS Acceleration (G) <sup>2, 5</sup>	0	65.535	0	65535
Z-Axis Kurtosis <sup>2, 6</sup>	0	65.535	0	65535
X-Axis Kurtosis <sup>2, 6</sup>	0	65.535	0	65535
Z-Axis Crest Factor <sup>2, 6</sup>	0	65.535	0	65535
X-Axis Crest Factor <sup>2, 6</sup>	0	65.535	0	65535
Z-Axis Peak Velocity (in/sec) <sup>1, 5</sup>	0	6.5535	0	65535
Z-Axis Peak Velocity (mm/sec) <sup>2, 5</sup>	0	65.535	0	65535
X-Axis Peak Velocity (in/sec) <sup>1, 5</sup>	0	6.5535	0	65535
X-Axis Peak Velocity (mm/sec) <sup>2, 5</sup>	0	65.535	0	65535
Z-Axis High-Frequency RMS Acceleration (G) <sup>2, 6</sup>	0	65.535	0	65535
X-Axis High-Frequency RMS Acceleration (G) <sup>2, 6</sup>	0	65.535	0	65535

<sup>1</sup> Value = Register value  $\div$  10000

<sup>2</sup> Value = Register value  $\div$  1000

<sup>3</sup> Value = Register value  $\div$  20

<sup>4</sup> Value = Register value  $\div$  10

<sup>5</sup> Measurement bandwidth = 10 Hz to 1 kHz

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### Specifications

#### Supply Voltage

3.6 to 5.5 V dc

#### Current

Default sensing: 197 μA Disabled sensing: 95 μA Active comms: 3.1 mA

## Communication Hardware

Interface: 1-wire serial interface

Baud rates: 9.6k, 19.2k (default), or 38.4k Data format: 8 data bits, no parity (default), 1 stop bit (even or odd parity available)

#### Vibration Sensor

Mounted base resonance: 4.5 kHz nominal Measuring Range: 0 to 46 mm/sec or 0 to 1.8 in/sec RMS Frequency Range: 10 Hz to 4 kHz Accuracy:  $\pm 10\%$  at 25 °C Sampling Frequency: 20 kHz (default) Record Length: 8192 points (default) Sample Duration: 0.4 s (default)

#### Indicators

Green flashing: Power ON Amber flicker: Serial Tx

#### Communication Protocol

Sure Cross DX80 Sensor Node 1-Wire Serial Interface

#### **Communications Line**

Level Receive ON: Greater than 2 V Level Receive OFF: Less than 0.7 V Level Transmit ON: 2.7 to 3 V Level Transmit OFF: 0 V (pulldown resistor of 10 kOhm)

#### Compatible Nodes

#### 900 MHz Models

DX80N9X1S-P6 DX80N9X6S-P6 DX80DR9M-H6 and -H6L DX80N9Q45VT 2.4 GHz Models DX80N2X1S-P6 DX80N2X6S-P6 DX80DR2M-H6 and -H6L DX80N2Q45VT



Measuring Range: –40 °C to +105 °C (–40 °F to +221 °F) Resolution: 1 °C Accuracy:  $\pm$  3 °C

#### Environmental Rating

NEMA 6P, IEC IP67

#### Operating Temperature

-40 °C to +105 °C (-40 °F to +221 °F)<sup>1</sup>

#### Shock 400G

### Mounting Options

The VT1 sensor can be mounted using a variety of methods, including 1/4"-28 hex screw, epoxy, thermal tape, or magnetic mount.



### Battery Life for a P6 Node Connected to a Vibration and Temperature (VT1) Sensor

The following battery life estimates use the default configuration of the Performance P6 Node, which is a 5 minute sample and report rate.

900 MHz 1 Watt: 2.5 years 900 MHz 250 mW: 3.4 years 2.4 GHz: 4.3 years

Battery Life for a Q45VA or a Q45VT/Q45U Node with 1-Wire Serial Sensor

This is the battery life curve for the following models:

- Q45VT or Q45U 1-Wire Serial Interface Node connected to a 1-wire serial sensor (such as a VT1 Vibration/Temperature sensor)
- Q45VA All-in-One Sensor Node



<sup>1</sup> Operating the devices at the maximum operating conditions for extended periods can shorten the life of the device.

## Dimensions



## Accessories for the Vibration and Temperature Sensor



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