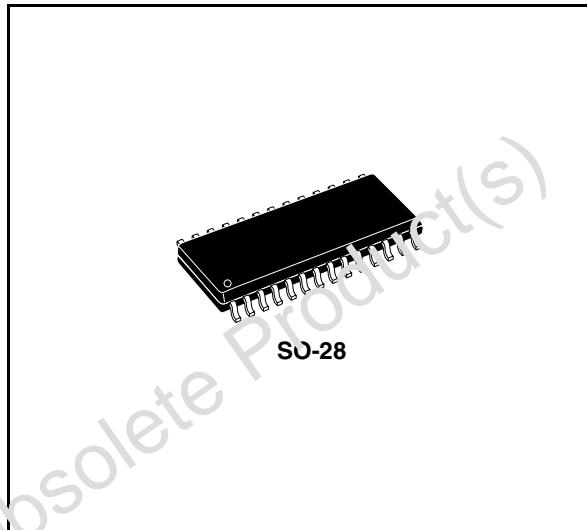


Digitally controlled audio processor

Features

- Input multiplexer
 - Three stereo and one mono inputs
 - Selectable input gain for optimal adaptation to different sources
- Volume control in 0.3db steps including gain up to 20dB
- Zero crossing mute and direct mute
- Pause detector with programmable threshold
- Soft mute controlled by software or hardware PIN
- Bass and treble control
- Four speaker attenuators
 - Four independent speakers control in 1.25dB steps for balance and fader facilities
 - Independent mute function
- All functions programmable via serial I²C bus



instead of standard bipolar multipliers, very low distortion and very low noise are obtained. Several new features like softmute, zero-crossing mute and pause detector are implemented.

The Soft Mute function can be activated in two ways, either via the serial bus (bit D0, Mute Byte), or directly on pin 22 through an I/O line of the microcontroller

Very low DC stepping is obtained by use of a BICMOS technology.

Description

The TDA7348 is an upgrade of the TDA7318 audioprocessor.

Thanks to the used BIPOLE/CMOS technology, very low distortion, low noise and DC-stepping are obtained. Due to a highly linear signal processing, using CMOS-switching techniques

Order codes

| Part number | Package | Packing |
|--------------------------------|---------|---------------|
| TDA7348D | SO-28 | Tube |
| TDA7348D013TR | SO-28 | Tape and reel |
| E-TDA7348D ⁽¹⁾ | SO-28 | Tube |
| E-TDA7348D013TR ⁽¹⁾ | SO-28 | Tape and reel |

1. This device is Pb-free Ecopack , see [Chapter 5](#) Package information.

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Obsolete Product(s) - Obsolete Product(s)

1 Block diagram and PIN connections

Figure 1. Block diagram

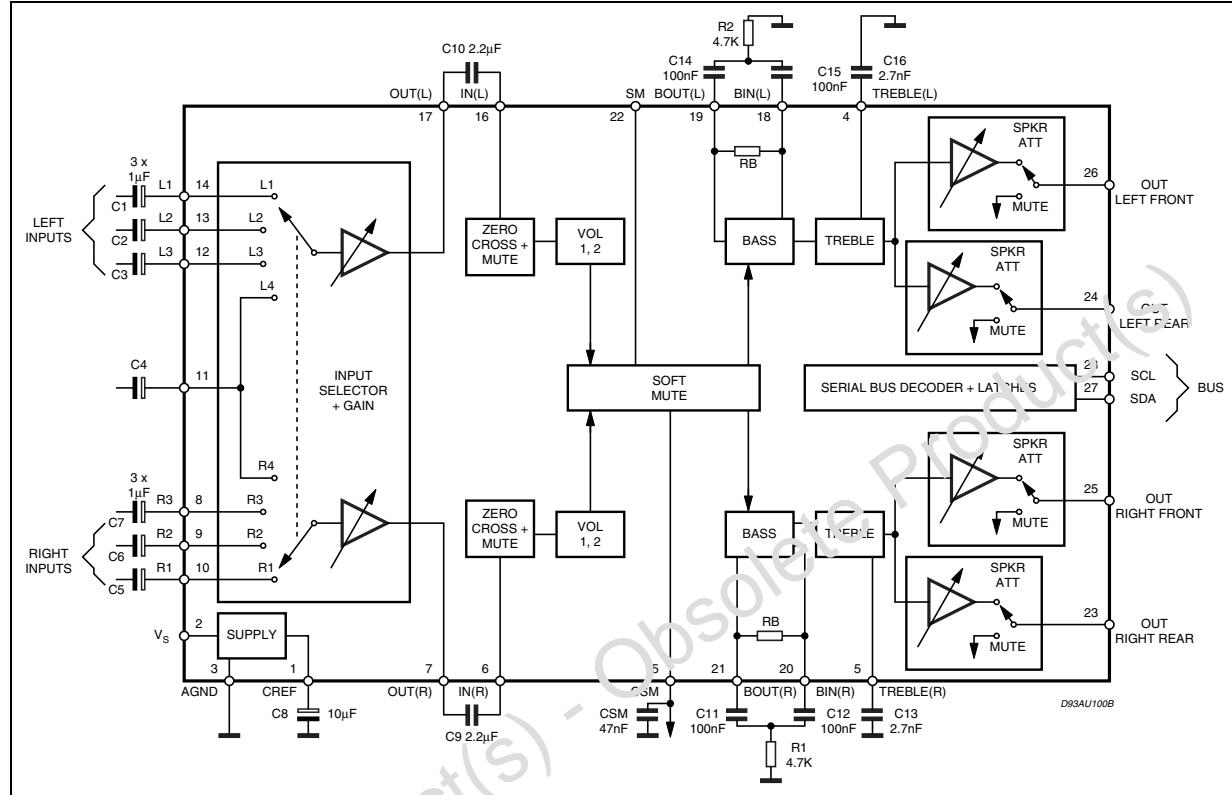
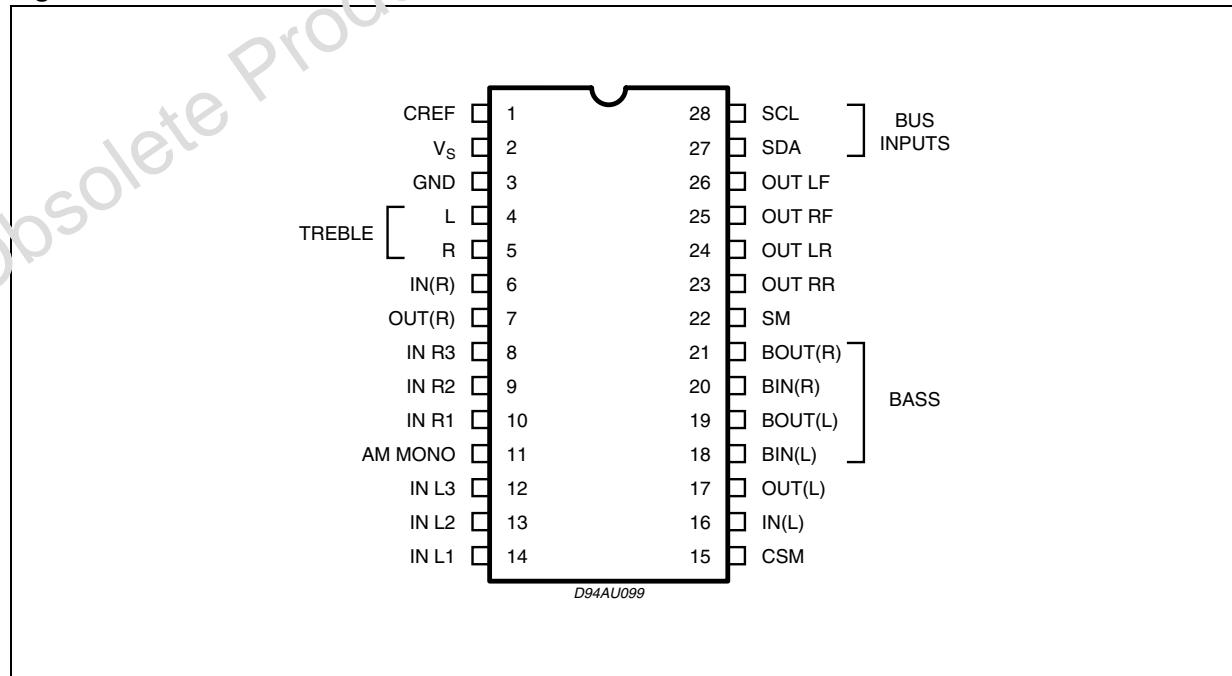


Figure 2. PIN connections



2 Electrical characteristics

Table 1. Electrical characteristics

$V_S = 9V$; $R_L = 10K\Omega$; $R_g = 50\Omega$; $T_{amb} = 25^\circ C$; all controls flat ($G = 0.3dB$ step 0dB); $f = 1KHz$. Refer to the test circuit, unless otherwise specified.

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------------------|------------------------------------|----------------------------|-------|-------|-------|-----------|
| Input selector | | | | | | |
| R_I | Input resistance | | 70 | 100 | 130 | $K\Omega$ |
| V_{CL} | Clipping level | $d \leq 0.3\%$ | 2.1 | 2.6 | | V_{RMS} |
| S_I | Input separation | | 80 | 100 | | dB |
| R_L | Output load resistance | | 2 | | | $K\Omega$ |
| $G_{I MIN}$ | Minimum input gain | | -0.75 | 0 | 0.75 | dB |
| $G_{I MAX}$ | Maximum input gain | | 10.25 | 11.25 | 12.25 | dB |
| G_{step} | Step resolution | | 2.75 | 3.75 | 4.75 | dB |
| e_N | Input noise | 20Hz to 20 KHz unweighted | | 2.3 | | μV |
| V_{DC} | DC steps | Adiacent gain steps | | 1.5 | 10 | mV |
| | | $G_{I MIN}$ to $G_{I MAX}$ | | 3 | | mV |
| Volume control (1 + 2) | | | | | | |
| R_I | Input resistance | | 35 | 50 | | $K\Omega$ |
| G_{MAX} | Maximum gain | | 18.75 | 20 | 21.25 | dB |
| A_{MAX} | Maximum attenuation | | | 78.45 | | dB |
| A_{STEPC} | Step resolution coarse attenuation | | 0.5 | 1.25 | 2.0 | dB |
| A_{STEPF} | Step resolution fine attenuation | | 0.11 | 0.31 | 0.51 | dB |
| E_A | Attenuation set error | $G = 20$ to $-20dB$ | -1.25 | 0 | 1.25 | dB |
| | | $G = -20$ to $-58dB$ | -3 | | 2 | dB |
| E_t | Tracking error | | | | 2 | dB |
| V_{DC} | DC steps | Adiacent attenuation steps | -3 | 0 | 3 | mV |
| | | From 0dB to A_{MAX} | | 0.5 | 5 | mV |
| Zero crossing mute | | | | | | |
| V_{TH} | Zero crossing threshold | WIN = 11 | | 20 | | mV |
| | | WIN = 10 | | 40 | | mV |
| | | WIN = 01 | | 80 | | mV |
| | | WIN = 00 | | 160 | | mV |
| A_{MUTE} | Mute attenuation | | 80 | 100 | | dB |
| V_{DC} | DC step | 0dB to Mute | | 0 | 3 | mV |

Table 1. Electrical characteristics (continued)
 $V_S = 9V$; $R_L = 10K\Omega$; $R_g = 50\Omega$; $T_{amb} = 25^\circ C$; all controls flat ($G = 0.3dB$ step $0dB$); $f = 1KHz$. Refer to the test circuit, unless otherwise specified.

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|----------------------------|------------------------------|--|----------|----------|----------|-----------|
| Soft mute | | | | | | |
| A_{MUTE} | Mute attenuation | | 45 | 60 | | dB |
| T_{DON} | ON delay time | $C_{CSM} = 22nF$; 0 to -20dB; $I = I_{MAX}$ | 0.7 | 1 | 1.7 | ms |
| | | $C_{CSM} = 22nF$; 0 to -20dB; $I = I_{MIN}$ | 20 | 35 | 55 | ms |
| T_{DOFF} | OFF delay time | $V_{CSM} = 0V$; $I = I_{MAX}$ | 25 | 50 | 75 | μA |
| | | $V_{CSM} = 0V$; $I = I_{MIN}$ | | 1 | | μA |
| V_{THSM} | Soft mute threshold | | 1.5 | 2.5 | 3.5 | V |
| R_{INT} | Pull-up resistor (pin 22) | | 50 | 65 | 85 | $K\Omega$ |
| V_{SMH} | (pin 22) level high | Soft Mute active | 3.5 | | | V |
| V_{SML} | (pin 22) level low | | | | 1 | V |
| Bass control | | | | | | |
| B_{BOOST} | Max bass boost | | 15 | 18 | 20 | dB |
| B_{CUT} | Max bass cut | | -8.5 | -10 | -11.5 | dB |
| A_{step} | Step resolution | | 1 | 2 | 3 | dB |
| R_g | Internal feedback resistance | | 45 | 65 | 85 | $K\Omega$ |
| Treble control | | | | | | |
| C_{RANGE} | Control range | | ± 13 | ± 14 | ± 15 | dB |
| A_{step} | Step resolution | | 1 | 2 | 3 | dB |
| Speaker attenuators | | | | | | |
| C_{RANGE} | Control range | | 35 | 37.5 | 40 | dB |
| A_{step} | Step resolution | | 0.5 | 1.25 | 2.0 | dB |
| A_{MUTE} | Output mute attenuation | Data word = XXX11111 | 80 | 100 | | dB |
| E_A | Attenuation set error | | | | 1.25 | dB |
| V_{DC} | DC steps | Adjacent attenuation steps | | 0 | 3 | mV |
| Audio output | | | | | | |
| V_{clip} | Clipping level | $d = 0.3\%$ | 2.1 | 2.6 | | Vrms |
| R_L | Output load resistance | | 2 | | | $K\Omega$ |
| R_O | Output impedance | | | 30 | 100 | W |
| V_{DC} | DC voltage level | | 3.5 | 3.8 | 4.1 | V |
| General | | | | | | |
| V_{CC} | Supply voltage | | 6 | 9 | 10.2 | V |

Table 1. Electrical characteristics (continued)
 $V_S = 9V$; $R_L = 10K\Omega$; $R_g = 50\Omega$; $T_{amb} = 25^\circ C$; all controls flat ($G = 0.3dB$ step
 $0dB$); $f = 1KHz$. Refer to the test circuit, unless otherwise specified.

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|--------------------------------|---|------|------|------|---------|
| I_{CC} | Supply current | | 5 | 10 | 15 | mA |
| PSRR | Power supply rejection ratio | $f = 1KHz$ | 60 | 80 | | dB |
| | | $B = 20$ to $20kHz$ "A" weighted | | 65 | | dB |
| e_{NO} | Output noise | Output Muted ($B = 20$ to $20kHz$ flat) | | 2.5 | | μV |
| | | All Gains 0dB ($B = 20$ to $20kHz$ flat) | | 5 | 15 | μV |
| E_t | Total tracking error | $A_V = 0$ to $-20dB$ | 0 | 1 | | dB |
| | | $A_V = -20$ to $-60dB$ | 0 | 2 | | dB |
| S/N | Signal to noise ratio | All Gains = 0dB; $V_O = 1Vrms$ | 106 | | | dB |
| S_C | Channel separation | | 80 | 100 | | dB |
| d | Distortion | $V_{in} = 1V$ | | 0.01 | 0.08 | % |
| Bus inputs | | | | | | |
| V_{IL} | Input low voltage | | | | 1 | V |
| V_{IN} | Input high voltage | | 3 | | | V |
| I_{IN} | Input current | $V_{IN} = 0.4V$ | -5 | | 5 | μA |
| V_O | Output voltage SDA acknowledge | $I_O = 1.6mA$ | | 0.4 | 0.8 | V |

Table 2. Absolute maximum ratings

| Symbol | Parameter | Value | Unit |
|-----------|-------------------------------|------------|------------|
| V_S | Operating supply voltage | 10.5 | V |
| T_{amb} | Operating ambient temperature | -40 to 85 | $^\circ C$ |
| T_{stg} | Storage temperature range | -55 to 150 | $^\circ C$ |

Table 3. Thermal data

| Symbol | Parameter | SO28 | Unit |
|----------------|----------------------------------|------|--------------|
| $R_{th,j-amb}$ | Thermal Resistance Junction pins | 65 | $^\circ C/W$ |

Table 4. Quick reference data

| Symbol | Parameter | Min. | Typ. | Max. | Unit |
|----------|--|------|------|------|------|
| V_S | Supply voltage | 6 | 9 | 10.2 | V |
| V_{CL} | Max. input signal handling | 2.1 | 2.6 | | Vrms |
| THD | Total harmonic distortion $V = 1Vrms$ $f = 1KHz$ | | 0.01 | 0.08 | % |
| S/N | Signal to noise ratio | | 106 | | dB |

Table 4. Quick reference data (continued)

| Symbol | Parameter | Min. | Typ. | Max. | Unit |
|--------|---------------------------------------|--------|------|-----------|------|
| Sc | Channel separation f = 1KHz | | 100 | | dB |
| | Volume control | -78.45 | | 20 | dB |
| | Treble control 2dB step | -14 | | +14 | dB |
| | Bass control 2dB step | -10 | | +18 | dB |
| | Fader and balance control 1.25dB step | -38.75 | | 0 | dB |
| | Input gain 3.75dB step | 0 | | 11.2 5 | dB |
| | Mute attenuation | | 100 | | dB |

3 I²C BUS interface

Data transmission from microprocessor to the TDA7348 and vice-versa takes place through the 2 wires of the I²C BUS interface, consisting of the two lines SDA and SCL (pull-up resistors to the positive supply voltage must be externally connected).

3.1 Data validity

As shown in *Figure 3.*, the data on the SDA line must be stable during the high period of the clock. The HIGH and LOW state of the data line can only change when the clock signal on the SCL line is LOW.

3.2 Start and stop conditions

As shown in *Figure 4.* a start condition is a HIGH to LOW transition of the SDA line while SCL is HIGH. The stop condition is a LOW to HIGH transition on the SDA line while SCL is HIGH.

A STOP conditions must be sent before each START condition.

3.3 Byte format

Every byte transferred to the SDA line must contain 8 bits. Each byte must be followed by an acknowledge bit. The MSB is transferred first.

3.4 Acknowledge

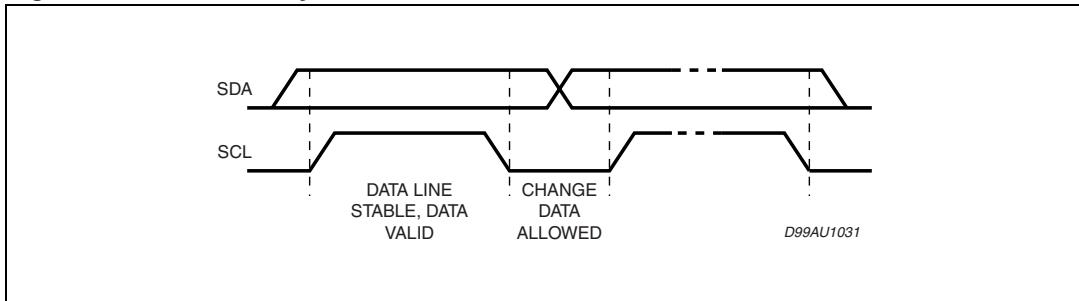
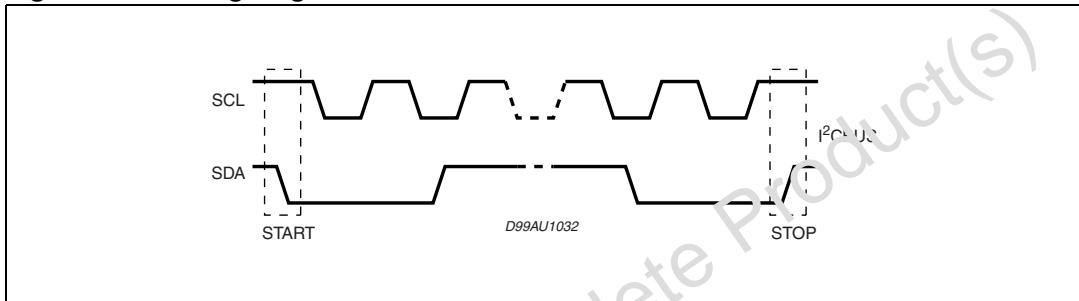
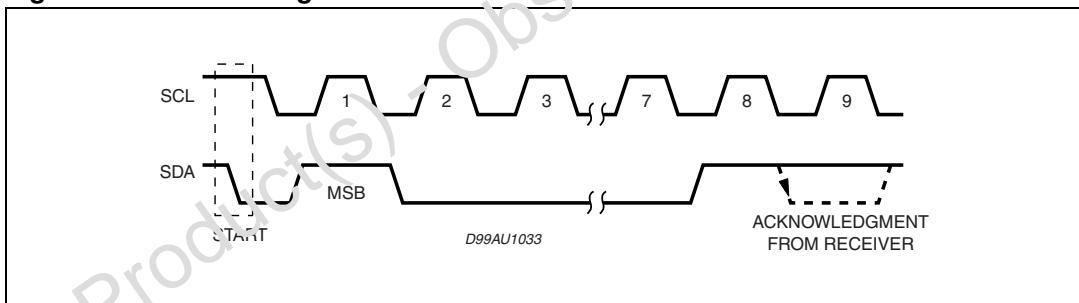
The master (microprocessor) puts a resistive HIGH level on the SDA line during the acknowledge clock pulse (see *Figure 5.*). The peripheral (audioprocessor) that acknowledges has to pull-down (LOW) the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during this clock pulse.

The audioprocessor which has been addressed has to generate an acknowledge after the reception of each byte, otherwise the SDA line remains at the HIGH level during the ninth clock pulse time. In this case the master transmitter can generate the STOP information in order to abort the transfer.

3.5 Transmission without acknowledgement

The microprocessor can use a simpler transmission, if it avoids detection of the acknowledgement from the audio processor. It simply waits one clock pulse without checking the slave acknowledgment, and sends the new data.

This approach of course is less protected from errors, increases the possibility of interference, and decreases the immunity to noise.

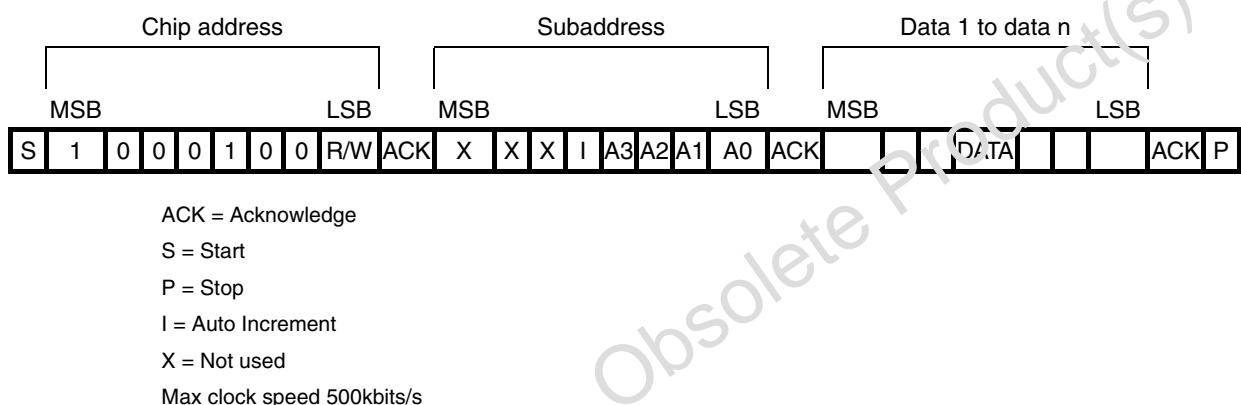
Figure 3. Data validity on the I²C BUS**Figure 4. Timing diagram of I²C BUS****Figure 5. Acknowledge on the I²C BUS**

4 Software specification

4.1 Interface protocol

The interface protocol comprises:

- A start condition (s)
- A chip address byte, (the LSB bit determines read/write transmission)
- A subaddress byte.
- A sequence of data (N-bytes + acknowledge)
- A stop condition (P)



4.2 Auto increment

If bit I in the subaddress byte is set to "1", the auto-increment of the subaddress is enabled

Table 5. Subaddress (receive mode)

| MSB | | | | | | | | LSB | Function |
|-----|---|---|---|----|----|----|----|-----|-----------------------|
| X | X | X | I | A3 | A2 | A1 | A0 | | |
| | | | | 0 | 0 | 0 | 0 | | Input selector |
| | | | | 0 | 0 | 0 | 1 | | Loudness |
| | | | | 0 | 0 | 1 | 0 | | Volume |
| | | | | 0 | 0 | 1 | 1 | | Bass, Treble |
| | | | | 0 | 1 | 0 | 0 | | Speaker attenuator LF |
| | | | | 0 | 1 | 0 | 1 | | Speaker attenuator LR |
| | | | | 0 | 1 | 1 | 0 | | Speaker attenuator RF |
| | | | | 0 | 1 | 1 | 1 | | Speaker attenuator RR |
| | | | | 1 | 0 | 0 | 0 | | Mute |

4.3 Transmitted data

Table 6. Send mode

| MSB | | | | | | | | LSB |
|-----|---|---|---|---|---|----|----|-----|
| X | X | X | X | X | X | SM | ZM | X |

ZM = Zero crossing muted (HIGH active)

SM = Soft mute activated (HIGH active)

X = Not used

The transmitted data is automatically updated after each ACK.

Transmission can be repeated without new chip address.

4.4 Data byte specification

X = not relevant; set to "1" during testing

Table 7. Input Selector

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|--------------|----------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| X | X | 1 | | | 0 | 0 | 0 | not used | |
| X | X | 1 | | | 0 | 0 | 1 | IN 2 | |
| X | X | 1 | | | 0 | 1 | 0 | IN 1 | |
| X | X | 1 | | | 0 | 1 | 1 | AM mono | |
| X | X | 1 | | | 1 | 0 | 0 | not used | |
| X | X | 1 | | | 1 | 0 | 1 | IN 3 | |
| X | X | 1 | | | 1 | 1 | 0 | not allowed | |
| X | X | 1 | | | 1 | 1 | 1 | not allowed | |
| X | X | 1 | 0 | 0 | | | | 11.25dB gain | |
| X | X | 1 | 0 | 1 | | | | 7.5dB gain | |
| X | X | 1 | 1 | 0 | | | | 3.75dB gain | |
| X | X | 1 | 1 | 1 | | | | 0dB gain | |

For example to select the IN 2 input with a gain of 7.5dB the Data Byte is: X X 1 0 1 0 0 1

Table 8. Loudness

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|---------|----------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| X | X | X | 1 | 0 | 0 | 0 | 0 | 0dB | |
| X | X | X | 1 | 0 | 0 | 0 | 1 | -1.25dB | |
| X | X | X | 1 | 0 | 0 | 1 | 0 | -2.5dB | |

Table 8. Loudness (continued)

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|----------|----------|
| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | | |
| X | X | X | 1 | 0 | 0 | 1 | 1 | -3.75dB | |
| X | X | X | 1 | 0 | 1 | 0 | 0 | -5dB | |
| X | X | X | 1 | 0 | 1 | 0 | 1 | -6.25dB | |
| X | X | X | 1 | 0 | 1 | 1 | 0 | -7.5dB | |
| X | X | X | 1 | 0 | 1 | 1 | 1 | -8.75dB | |
| X | X | X | 1 | 1 | 0 | 0 | 0 | -10dB | |
| X | X | X | 1 | 1 | 0 | 0 | 1 | -11.25dB | |
| X | X | X | 1 | 1 | 0 | 1 | 0 | -12.5dB | |
| X | X | X | 1 | 1 | 0 | 1 | 1 | -13.75dB | |
| X | X | X | 1 | 1 | 1 | 0 | 0 | -15dB | |
| X | X | X | 1 | 1 | 1 | 0 | 1 | -16.25dB | |
| X | X | X | 1 | 1 | 1 | 1 | 0 | -17.5dB | |
| X | X | X | 1 | 1 | 1 | 1 | 1 | -18.75dB | |

For example to select -17.5dB attenuation, loudness > OFF, the Data Byte is: X X X1 1 1 1 0

Table 9. Mute

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|-----|---|
| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | | |
| | | | | | | | | 1 | Soft mute on |
| | | | | | | | 0 | 1 | Soft mute with fast slope ($I = I_{MAX}$) |
| | | | | | | | 1 | 1 | Soft mute with slow slope ($I = I_{MIN}$) |
| | | | | 1 | | | | | Direct mute |
| | | | | 0 | | 1 | | | Zero crossing mute on |
| | | | | 0 | | 0 | | | Zero crossing mute off (delayed until next zerocrossing) |
| | | | | 1 | | | | | Zero crossing mute and pause detector reset |
| 0 | 0 | | | | | | | | 160mV ZC window threshold (WIN = 00) |
| 0 | 1 | | | | | | | | 80mV ZC window threshold (WIN = 01) |
| 1 | 0 | | | | | | | | 40mV ZC window threshold (WIN = 10) |
| 1 | 1 | | | | | | | | 20mV ZC window threshold (WIN = 11) |
| 0 | | | | | | | | | Non-symmetrical Bass Cut |
| 1 | | | | | | | | | Symmetrical Bass Cut |

An additional direct mute function is included in the speaker attenuators.

Note: Bass cut for very low frequencies should not be used at +16 & +18dB bass boost (DC gain)

Table 10. Speaker attenuators

| MSB | | | | | | | | LSB | Speaker attenuator LF, LR, RF, RR |
|-----|----|----|----|----|----|----|----|-------------|-----------------------------------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| | | | | | | | | 1.25dB step | |
| X | X | X | | | 0 | 0 | 0 | | 0dB |
| X | X | X | | | 0 | 0 | 1 | | -1.25dB |
| X | X | X | | | 0 | 1 | 0 | | -2.5dB |
| X | X | X | | | 0 | 1 | 1 | | -3.75dB |
| X | X | X | | | 1 | 0 | 0 | | -5dB |
| X | X | X | | | 1 | 0 | 1 | | -6.25dB |
| X | X | X | | | 1 | 1 | 0 | | -7.5dB |
| X | X | X | | | 1 | 1 | 1 | | -8.75dB |
| | | | | | | | | 10dB step | |
| X | X | X | 0 | 0 | | | | | 0dB |
| X | X | X | 0 | 1 | | | | | -10dB |
| X | X | X | 1 | 0 | | | | | -20dB |
| X | X | X | 1 | 1 | | | | | -30dB |
| X | X | X | 1 | 1 | 1 | 1 | 1 | | Speaker mute |

For example an attenuation of 25dB on a selected output is given by: X X X 1 0 1 0 0

Table 11. Bass/Treble

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|-------------|----------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| | | | | | | | | Treble step | |
| | | | | 0 | 0 | 0 | 0 | | -14dB |
| | | | | 0 | 0 | 0 | 1 | | -12dB |
| | | | | 0 | 0 | 1 | 0 | | -10dB |
| | | | | 0 | 0 | 1 | 1 | | -8dB |
| | | | | 0 | 1 | 0 | 0 | | -6dB |
| | | | | 0 | 1 | 0 | 1 | | -4dB |
| | | | | 0 | 1 | 1 | 0 | | -2dB |
| | | | | 0 | 1 | 1 | 1 | | 0dB |
| | | | | 1 | 1 | 1 | 1 | | 0dB |
| | | | | 1 | 1 | 1 | 0 | | 2dB |

Table 11. Bass/Treble (continued)

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|------------|----------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| | | | | 1 | 1 | 0 | 1 | | 4dB |
| | | | | 1 | 1 | 0 | 0 | | 6dB |
| | | | | 1 | 0 | 1 | 1 | | 8dB |
| | | | | 1 | 0 | 1 | 0 | | 10dB |
| | | | | 1 | 0 | 0 | 1 | | 12dB |
| | | | | 1 | 0 | 0 | 0 | | 14dB |
| | | | | | | | | BASS STEPS | |
| 0 | 0 | 1 | 0 | | | | | | -10dB |
| 0 | 0 | 1 | 1 | | | | | | 0dB |
| 0 | 1 | 0 | 0 | | | | | | -6dB |
| 0 | 1 | 0 | 1 | | | | | | -4dB |
| 0 | 1 | 1 | 0 | | | | | | -2dB |
| 0 | 1 | 1 | 1 | | | | | | -0dB |
| 1 | 1 | 1 | 1 | | | | | | -0dB |
| 1 | 1 | 1 | 0 | | | | | | 2dB |
| 1 | 1 | 0 | 1 | | | | | | 4dB |
| 1 | 1 | 0 | 0 | | | | | | 6dB |
| 1 | 0 | 1 | 1 | | | | | | 8dB |
| 1 | 0 | 1 | 0 | | | | | | 10dB |
| 1 | 0 | 0 | 1 | | | | | | 12dB |
| 1 | 0 | 0 | 0 | | | | | | 14dB |
| 0 | 0 | 0 | 1 | | | | | | 146B |
| 0 | 0 | 0 | 0 | | | | | | 18dB |

For example 12dB Treble and -8dB Bass give the following DATA BYTE: 0 0 1 1 1 0 0 1

Table 12. Volume

| MSB | | | | | | | | LSB | Function |
|-----|----|----|----|----|----|----|----|-----|---------------------------------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| | | | | | | | | | 0.31dB Fine attenuation steps |
| | | | | | | 0 | 0 | | 0dB |
| | | | | | | 0 | 1 | | -0.31dB |
| | | | | | | 1 | 0 | | -0.62dB |
| | | | | | | 1 | 1 | | -0.94dB |
| | | | | | | | | | 1.25dB Coarse attenuation steps |
| | | | 0 | 0 | 0 | | | | 0dB |
| | | | 0 | 0 | 1 | | | | -1.25dB |
| | | | 0 | 1 | 0 | | | | -2.5dB |
| | | | 0 | 1 | 1 | | | | -3.75dB |
| | | | 1 | 0 | 0 | | | | -5dB |
| | | | 1 | 0 | 1 | | | | -6.25dB |
| | | | 1 | 1 | 0 | | | | -7.5dB |
| | | | 1 | 1 | 1 | | | | -8.75dB |
| | | | | | | | | | 10dB Gain / attenuation steps |
| 0 | 0 | 0 | | | | | | | 20dB |
| 0 | 0 | 1 | | | | | | | 10dB |
| 0 | 1 | 0 | | | | | | | 0dB |
| 0 | 1 | 1 | | | | | | | -10dB |
| 1 | 0 | 0 | | | | | | | -20dB |
| 1 | 0 | 1 | | | | | | | -30dB |
| 1 | 1 | 0 | | | | | | | -40dB |
| 1 | 1 | 1 | | | | | | | -50dB |

For example to select -47.81dB volume the data byte is: 1 1 0 1 1 0 0 1

Power on RESET: All bytes set to 1 1 1 1 1 1 1 0

5 Package information

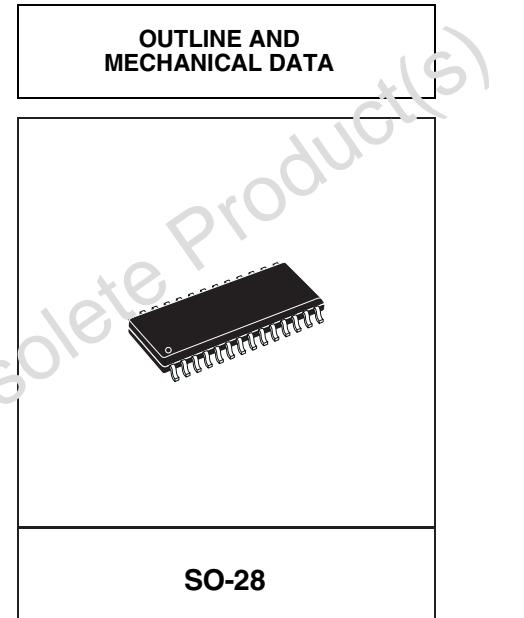
In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a lead-free second level interconnect. The category of second level interconnect is marked on the package and on the inner box label, in compliance with JEDEC standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label.

ECOPACK is an ST trademark. ECOPACK specifications are available at: www.st.com.

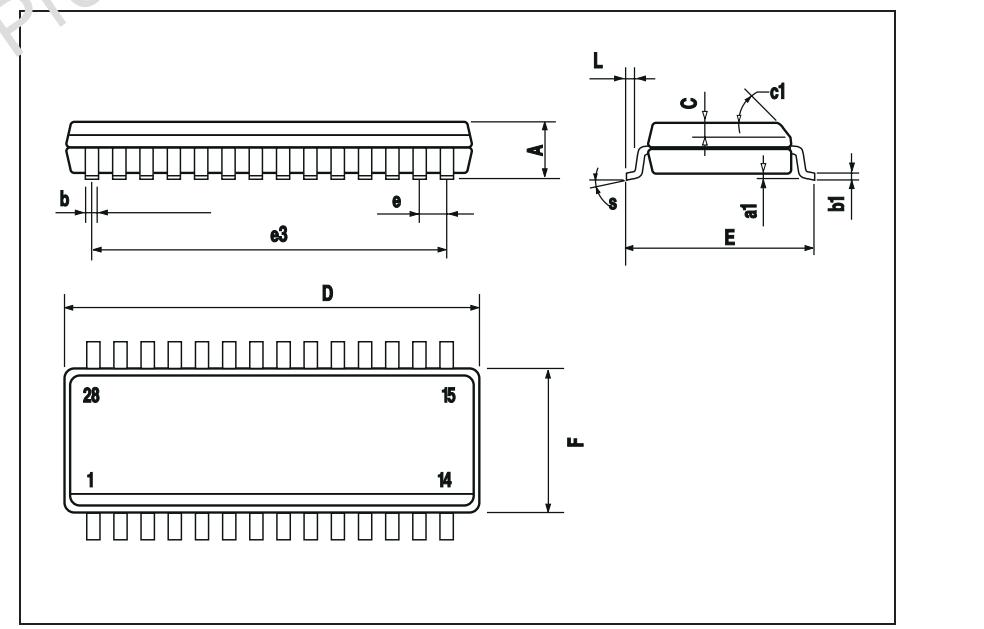
Figure 6. SO-28 mechanical, data and package dimensions

| DIM. | mm | | | inch | | |
|------|------------|-------|-------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | | | 2.65 | | | 0.104 |
| a1 | 0.1 | | 0.3 | 0.004 | | 0.012 |
| b | 0.35 | | 0.49 | 0.014 | | 0.019 |
| b1 | 0.23 | | 0.32 | 0.009 | | 0.013 |
| C | | 0.5 | | | 0.020 | |
| c1 | 45° (typ.) | | | | | |
| D | 17.7 | | 18.1 | 0.697 | | 0.713 |
| E | 10 | | 10.65 | 0.394 | | 0.49 |
| e | | 1.27 | | | 0.05 | |
| e3 | | 16.51 | | | 0.65 | |
| F | 7.4 | | 7.6 | 0.29 | | 0.299 |
| L | 0.4 | | 1.27 | 0.016 | | 0.050 |
| S | 8 ° (max.) | | | | | |

OUTLINE AND MECHANICAL DATA



SO-28



6 Revision history

Table 13. Document revision history

| Date | Revision | Changes |
|-------------|----------|--|
| 14-Jan-2004 | 1 | Initial release. |
| 21-Jun-2004 | 2 | Technical migration from ST-PRESS to EDOCS DMS |
| 26-Jan-2007 | 3 | DIP28 package removed, block diagram changed, layout modified. |

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