

### FEATURES

- High common-mode transient immunity: 100 kV/ $\mu$ s
- High robustness to radiated and conducted noise
- Low propagation delay: 13 ns maximum for 5 V operation
- 150 Mbps minimum data rate
- 3.75 kV rms withstand voltage rating
- Safety and regulatory approvals (pending)
  - UL recognition (pending)
  - 3750 V rms for 1 minute per UL 1577
  - CSA component acceptance notice 5A
  - VDE certificate of conformity
  - DIN V VDE V 0884-10 (VDE V 0884-10):2006-12
  - $V_{IORM} = 848$  V peak
  - CQC11-471543-2012
- Backward compatibility
  - ADuM140E1 pin compatible with ADuM1400
- Low dynamic power consumption
- 1.8 V to 5 V level translation
- High temperature operation: 125°C
- Failsafe high or low options
- 16-lead, RoHS-compliant, SOIC package

### APPLICATIONS

- General-purpose multichannel isolation
- SPI interface/data converter isolation
- Industrial field bus isolation

### GENERAL DESCRIPTION

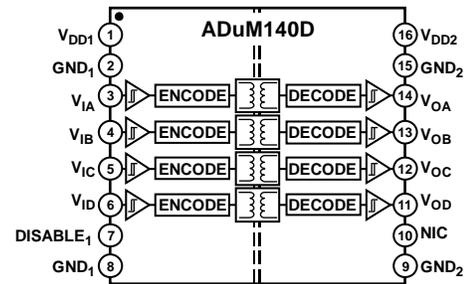
The ADuM140D/ADuM140E<sup>1</sup> are quad-channel digital isolators based on Analog Devices, Inc., iCoupler® technology. Combining high speed, complementary metal-oxide semiconductor (CMOS) and monolithic air core transformer technology, these isolation components provide outstanding performance characteristics superior to alternatives such as optocoupler devices and other integrated couplers. The maximum propagation delay is 13 ns with a pulse width distortion of less than 3 ns at 5 V operation. Channel matching is tight at 3.0 ns maximum.

The ADuM140D/ADuM140E data channels are independent and are available in a variety of configurations with a withstand

voltage rating of 3.75 kV rms (see the Ordering Guide). The devices operate with the supply voltage on either side ranging from 1.8 V to 5 V, providing compatibility with lower voltage systems as well as enabling voltage translation functionality across the isolation barrier.

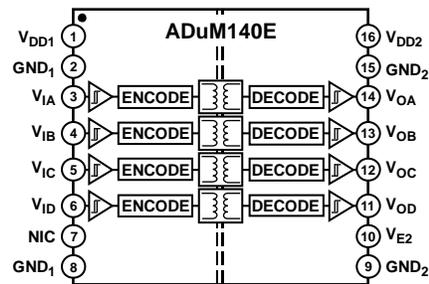
Unlike other optocoupler alternatives, dc correctness is ensured in the absence of input logic transitions. Two different fail-safe options are available, in which the outputs transition to a predetermined state when the input power supply is not applied or the inputs are disabled. The ADuM140E1 is pin compatible with the ADuM1400.

### FUNCTIONAL BLOCK DIAGRAMS



NIC = NO INTERNAL CONNECTION. LEAVE THIS PIN FLOATING. 13119-001

Figure 1. ADuM140D Functional Block Diagram



NIC = NO INTERNAL CONNECTION. LEAVE THIS PIN FLOATING. 13119-002

Figure 2. ADuM140E Functional Block Diagram

<sup>1</sup> Protected by U.S. Patents 5,952,849; 6,873,065; 6,903,578; and 7,075,329. Other patents are pending.

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## REVISION HISTORY

4/15—Revision 0: Initial Version

## SPECIFICATIONS

## ELECTRICAL CHARACTERISTICS—5 V OPERATION

All typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = V_{DD2} = 5\text{ V}$ . Minimum/maximum specifications apply over the entire recommended operation range of  $4.5\text{ V} \leq V_{DD1} \leq 5.5\text{ V}$ ,  $4.5\text{ V} \leq V_{DD2} \leq 5.5\text{ V}$ , and  $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , unless otherwise noted. Switching specifications are tested with  $C_L = 15\text{ pF}$  and CMOS signal levels, unless otherwise noted. Supply currents are specified with 50% duty cycle signals.

Table 1.

| Parameter                                    | Symbol                | Min                  | Typ             | Max                  | Unit                 | Test Conditions/Comments   |
|--|-----------------------|----------------------|-----------------|----------------------|----------------------|--|
| <b>SWITCHING SPECIFICATIONS</b>              |                       |                      |                 |                      |                      |  |
| Pulse Width                                  | PW                    | 6.6                  |                 |                      | ns                   | Within pulse width distortion (PWD) limit                        |
| Data Rate                                    |                       | 150                  |                 |                      | Mbps                 | Within PWD limit   |
| Propagation Delay                            | $t_{PHL}$ , $t_{PLH}$ | 4.8                  | 7.2             | 13                   | ns                   | 50% input to 50% output  |
| Pulse Width Distortion                       | PWD                   |                      | 0.5             | 3                    | ns                   | $ t_{PLH} - t_{PHL} $  |
| Change vs. Temperature                       |                       |                      | 1.5             |                      | ps/ $^\circ\text{C}$ |  |
| Propagation Delay Skew                       | $t_{PSK}$             |                      |                 | 6.1                  | ns                   | Between any two units at the same temperature, voltage, and load |
| Channel Matching                             |                       |                      |                 |                      |                      |  |
| Codirectional                                | $t_{PSKCD}$           |                      | 0.5             | 3.0                  | ns                   |  |
| Opposing Direction                           | $t_{PSKOD}$           |                      | 0.5             | 3.0                  | ns                   |  |
| Jitter                                       |                       |                      | 490             |                      | ps p-p               | See the Jitter Measurement section                               |
| <b>DC SPECIFICATIONS</b>                     |                       |                      |                 |                      |                      |  |
| Input Threshold                              |                       |                      |                 |                      |                      |  |
| Logic High                                   | $V_{IH}$              | $0.7 \times V_{DDx}$ |                 |                      | V                    |  |
| Logic Low                                    | $V_{IL}$              |                      |                 | $0.3 \times V_{DDx}$ | V                    |  |
| Output Voltage                               |                       |                      |                 |                      |                      |  |
| Logic High                                   | $V_{OH}$              | $V_{DDx} - 0.1$      | $V_{DDx}$       |                      | V                    | $I_{Ox}^1 = -20\ \mu\text{A}$ , $V_{Ix} = V_{IxH}^2$             |
|  |                       | $V_{DDx} - 0.4$      | $V_{DDx} - 0.2$ |                      | V                    | $I_{Ox}^1 = -4\ \text{mA}$ , $V_{Ix} = V_{IxH}^2$                |
| Logic Low                                    | $V_{OL}$              |                      | 0.0             | 0.1                  | V                    | $I_{Ox}^1 = 20\ \mu\text{A}$ , $V_{Ix} = V_{IxL}^3$              |
|  |                       |                      | 0.2             | 0.4                  | V                    | $I_{Ox}^1 = 4\ \text{mA}$ , $V_{Ix} = V_{IxL}^3$                 |
| Input Current per Channel                    | $I_i$                 | -10                  | +0.01           | +10                  | $\mu\text{A}$        | $0\text{ V} \leq V_{Ix} \leq V_{DDx}$                            |
| $V_{E2}$ Enable Input Pull-Up Current        | $I_{PU}$              | -10                  | -3              |                      | $\mu\text{A}$        | $V_{E2} = 0\text{ V}$  |
| DISABLE <sub>1</sub> Input Pull-Down Current | $I_{PD}$              |                      | 9               | 15                   | $\mu\text{A}$        | DISABLE <sub>1</sub> = $V_{DDx}$                                 |
| Tristate Output Current per Channel          | $I_{OZ}$              | -10                  | +0.01           | +10                  | $\mu\text{A}$        | $0\text{ V} \leq V_{Ox} \leq V_{DDx}$                            |
| Supply Current per Channel                   |                       |                      |                 |                      |                      |  |
| Quiescent Input                              | $I_{DDI(Q)}$          |                      | 0.3             | 0.55                 | mA                   | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                    |
| Quiescent Output                             | $I_{DDO(Q)}$          |                      | 0.5             | 0.68                 | mA                   | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                    |
| Quiescent Input                              | $I_{DDI(Q)}$          |                      | 3.0             | 5.0                  | mA                   | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                    |
| Quiescent Output                             | $I_{DDO(Q)}$          |                      | 0.5             | 0.73                 | mA                   | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                    |
| Dynamic Input                                | $I_{DDI(D)}$          |                      | 0.01            |                      | mA/Mbps              | Inputs switching, 50% duty cycle                                 |
| Dynamic Output                               | $I_{DDO(D)}$          |                      | 0.02            |                      | mA/Mbps              | Inputs switching, 50% duty cycle                                 |
| Undervoltage Lockout                         | UVLO                  |                      |                 |                      |                      |  |
| Positive $V_{DDx}$ Threshold                 | $V_{DDxUV+}$          |                      | 1.6             |                      | V                    |  |
| Negative $V_{DDx}$ Threshold                 | $V_{DDxUV-}$          |                      | 1.5             |                      | V                    |  |
| $V_{DDx}$ Hysteresis                         | $V_{DDxUVH}$          |                      | 0.1             |                      | V                    |  |

| Parameter                                   | Symbol    | Min | Typ | Max | Unit        | Test Conditions/Comments   |
|---|-----------|-----|-----|-----|-------------|--|
| AC SPECIFICATIONS                           |           |     |     |     |             |  |
| Output Rise/Fall Time                       | $t_R/t_F$ |     | 2.5 |     | ns          | 10% to 90%   |
| Common-Mode Transient Immunity <sup>6</sup> | $ CM_H $  | 75  | 100 |     | kV/ $\mu$ s | $V_{IX} = V_{DDX}$ , $V_{CM} = 1000$ V,<br>transient magnitude = 800 V |
|   | $ CM_L $  | 75  | 100 |     | kV/ $\mu$ s | $V_{IX} = 0$ V, $V_{CM} = 1000$ V,<br>transient magnitude = 800 V      |

<sup>1</sup>  $I_{Ox}$  is the Channel x output current, where x = A, B, C, or D.

<sup>2</sup>  $V_{IH}$  is the input side logic high.

<sup>3</sup>  $V_{IL}$  is the input side logic low.

<sup>4</sup>  $V_I$  is the voltage input.

<sup>5</sup> E0 is the ADuM140E0 model, D0 is the ADuM140D0 model, E1 is the ADuM140E1 model, and D1 is the ADuM140D1 model. See the Ordering Guide section.

<sup>6</sup>  $|CM_H|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining the voltage output ( $V_O$ ) > 0.8  $V_{DDX}$ .  $|CM_L|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining  $V_O > 0.8$  V. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

Table 2. Total Supply Current vs. Data Throughput

| Parameter             | Symbol    | 1 Mbps |     |     | 25 Mbps |     |     | 100 Mbps |      |      | Unit |
|-----------------------|-----------|--------|-----|-----|---------|-----|-----|----------|------|------|------|
|                       |           | Min    | Typ | Max | Min     | Typ | Max | Min      | Typ  | Max  |      |
| SUPPLY CURRENT        |           |        |     |     |         |     |     |          |      |      |      |
| Supply Current Side 1 | $I_{DD1}$ |        | 6.8 | 10  |         | 7.8 | 12  |          | 11.8 | 17.4 | mA   |
| Supply Current Side 2 | $I_{DD2}$ |        | 2.1 | 3.7 |         | 3.9 | 5.7 |          | 9.2  | 13   | mA   |

## ELECTRICAL CHARACTERISTICS—3.3 V OPERATION

All typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = V_{DD2} = 3.3$  V. Minimum/maximum specifications apply over the entire recommended operation range:  $3.0\text{ V} \leq V_{DD1} \leq 3.6\text{ V}$ ,  $3.0\text{ V} \leq V_{DD2} \leq 3.6\text{ V}$ , and  $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , unless otherwise noted. Switching specifications are tested with  $C_L = 15$  pF and CMOS signal levels, unless otherwise noted. Supply currents are specified with 50% duty cycle signals.

Table 3.

| Parameter                                    | Symbol                | Min                  | Typ             | Max | Unit                 | Test Conditions/Comments   |
|--|-----------------------|----------------------|-----------------|-----|----------------------|--|
| SWITCHING SPECIFICATIONS                     |                       |                      |                 |     |                      |  |
| Pulse Width                                  | PW                    | 6.6                  |                 |     | ns                   | Within PWD limit   |
| Data Rate                                    |                       | 150                  |                 |     | Mbps                 | Within PWD limit   |
| Propagation Delay                            | $t_{PHL}$ , $t_{PLH}$ | 4.8                  | 6.8             | 14  | ns                   | 50% input to 50% output  |
| Pulse Width Distortion                       | PWD                   |                      | 0.7             | 3   | ns                   | $ t_{PLH} - t_{PHL} $  |
| Change vs. Temperature                       |                       |                      | 1.5             |     | ps/ $^\circ\text{C}$ |  |
| Propagation Delay Skew                       | $t_{PSK}$             |                      |                 | 7.5 | ns                   | Between any two units at the same temperature, voltage, and load |
| Channel Matching                             |                       |                      |                 |     |                      |  |
| Codirectional                                | $t_{PSKCD}$           |                      | 0.7             | 3.0 | ns                   |  |
| Opposing Direction                           | $t_{PSKOD}$           |                      | 0.7             | 3.0 | ns                   |  |
| Jitter                                       |                       |                      | 580             |     | ps p-p               | See the Jitter Measurement section                               |
| DC SPECIFICATIONS                            |                       |                      |                 |     |                      |  |
| Input Threshold                              |                       |                      |                 |     |                      |  |
| Logic High                                   | $V_{IH}$              | $0.7 \times V_{DDX}$ |                 |     | V                    |  |
| Logic Low                                    | $V_{IL}$              |                      |                 |     | $0.3 \times V_{DDX}$ | V  |
| Output Voltage                               |                       |                      |                 |     |                      |  |
| Logic High                                   | $V_{OH}$              | $V_{DDX} - 0.1$      | $V_{DDX}$       |     | V                    | $I_{Ox}^1 = -20\ \mu\text{A}$ , $V_{IX} = V_{IXH}^2$             |
|  |                       | $V_{DDX} - 0.4$      | $V_{DDX} - 0.2$ |     | V                    | $I_{Ox}^1 = -2\ \text{mA}$ , $V_{IX} = V_{IXH}^2$                |
| Logic Low                                    | $V_{OL}$              |                      | 0.0             | 0.1 | V                    | $I_{Ox}^1 = 20\ \mu\text{A}$ , $V_{IX} = V_{IXL}^3$              |
|  |                       |                      | 0.2             | 0.4 | V                    | $I_{Ox}^1 = 2\ \text{mA}$ , $V_{IX} = V_{IXL}^3$                 |
| Input Current per Channel                    | $I_I$                 | -10                  | +0.01           | +10 | $\mu\text{A}$        | $0\text{ V} \leq V_{IX} \leq V_{DDX}$                            |
| $V_{E2}$ Enable Input Pull-Up Current        | $I_{PU}$              | -10                  | -3              |     | $\mu\text{A}$        | $V_{E2} = 0\text{ V}$  |
| DISABLE <sub>1</sub> Input Pull-Down Current | $I_{PD}$              |                      | 9               | 15  | $\mu\text{A}$        | DISABLE <sub>1</sub> = $V_{DDX}$                                 |
| Tristate Output Current per Channel          | $I_{OZ}$              | -10                  | +0.01           | +10 | $\mu\text{A}$        | $0\text{ V} \leq V_{Ox} \leq V_{DDX}$                            |

| Parameter                                   | Symbol       | Min | Typ  | Max  | Unit        | Test Conditions/Comments   |
|---|--------------|-----|------|------|-------------|--|
| Supply Current per Channel                  |              |     |      |      |             |  |
| Quiescent Input                             | $I_{DDI(Q)}$ |     | 0.3  | 0.53 | mA          | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                          |
| Quiescent Output                            | $I_{DDO(Q)}$ |     | 0.5  | 0.67 | mA          | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                          |
| Quiescent Input                             | $I_{DDI(Q)}$ |     | 3.0  | 4.9  | mA          | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                          |
| Quiescent Output                            | $I_{DDO(Q)}$ |     | 0.5  | 0.7  | mA          | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                          |
| Dynamic Input                               | $I_{DDI(D)}$ |     | 0.01 |      | mA/Mbps     | Inputs switching, 50% duty cycle                                       |
| Dynamic Output                              | $I_{DDO(D)}$ |     | 0.01 |      | mA/Mbps     | Inputs switching, 50% duty cycle                                       |
| Undervoltage Lockout                        |              |     |      |      |             |  |
| Positive $V_{DDx}$ Threshold                | $V_{DDxUV+}$ |     | 1.6  |      | V           |  |
| Negative $V_{DDx}$ Threshold                | $V_{DDxUV-}$ |     | 1.5  |      | V           |  |
| $V_{DDx}$ Hysteresis                        | $V_{DDxUVH}$ |     | 0.1  |      | V           |  |
| AC SPECIFICATIONS                           |              |     |      |      |             |  |
| Output Rise/Fall Time                       | $t_R/t_F$    |     | 2.5  |      | ns          | 10% to 90%   |
| Common-Mode Transient Immunity <sup>6</sup> | $ CM_H $     | 75  | 100  |      | kV/ $\mu$ s | $V_{ix} = V_{DDx}$ , $V_{CM} = 1000$ V,<br>transient magnitude = 800 V |
|   | $ CM_L $     | 75  | 100  |      | kV/ $\mu$ s | $V_{ix} = 0$ V, $V_{CM} = 1000$ V,<br>transient magnitude = 800 V      |

<sup>1</sup>  $I_{ox}$  is the Channel x output current, where x = A, B, C, or D.

<sup>2</sup>  $V_{iKH}$  is the input side logic high.

<sup>3</sup>  $V_{iKL}$  is the input side logic low.

<sup>4</sup>  $V_i$  is the voltage input.

<sup>5</sup> E0 is the ADuM140E0 model, D0 is the ADuM140D0 model, E1 is the ADuM140E1 model, and D1 is the ADuM140D1 model. See the Ordering Guide section.

<sup>6</sup>  $|CM_H|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining the voltage output ( $V_O$ ) > 0.8  $V_{DDx}$ .  $|CM_L|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining  $V_O > 0.8$  V. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

**Table 4. Total Supply Current vs. Data Throughput**

| Parameter             | Symbol    | 1 Mbps |     |     | 25 Mbps |     |      | 100 Mbps |      |      | Unit |
|-----------------------|-----------|--------|-----|-----|---------|-----|------|----------|------|------|------|
|                       |           | Min    | Typ | Max | Min     | Typ | Max  | Min      | Typ  | Max  |      |
| SUPPLY CURRENT        |           |        |     |     |         |     |      |          |      |      |      |
| Supply Current Side 1 | $I_{DD1}$ |        | 6.6 | 9.8 |         | 7.4 | 11.2 |          | 10.7 | 15.9 | mA   |
| Supply Current Side 2 | $I_{DD2}$ |        | 2.0 | 3.7 |         | 3.5 | 5.5  |          | 8.2  | 11.6 | mA   |

## ELECTRICAL CHARACTERISTICS—2.5 V OPERATION

All typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = V_{DD2} = 2.5$  V. Minimum/maximum specifications apply over the entire recommended operation range:  $2.25$  V  $\leq V_{DD1} \leq 2.75$  V,  $2.25$  V  $\leq V_{DD2} \leq 2.75$  V,  $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , unless otherwise noted. Switching specifications are tested with  $C_L = 15$  pF and CMOS signal levels, unless otherwise noted. Supply currents are specified with 50% duty cycle signals.

**Table 5.**

| Parameter                | Symbol                | Min | Typ | Max | Unit                 | Test Conditions/Comments                                     |
|--------------------------|-----------------------|-----|-----|-----|----------------------|--|
| SWITCHING SPECIFICATIONS |                       |     |     |     |                      |  |
| Pulse Width              | PW                    | 6.6 |     |     | ns                   | Within PWD limit   |
| Data Rate                |                       | 150 |     |     | Mbps                 | Within PWD limit   |
| Propagation Delay        | $t_{PHL}$ , $t_{PLH}$ | 5.0 | 7.0 | 14  | ns                   | 50% input to 50% output                                      |
| Pulse Width Distortion   | PWD                   |     | 0.7 | 3   | ns                   | $ t_{PLH} - t_{PHL} $  |
| Change vs. Temperature   |                       |     | 1.5 |     | ps/ $^\circ\text{C}$ |  |
| Propagation Delay Skew   | $t_{PSK}$             |     |     | 6.8 | ns                   | Between any two units at the same temperature, voltage, load |
| Channel Matching         |                       |     |     |     |                      |  |
| Codirectional            | $t_{PSKCD}$           |     | 0.7 | 3.0 | ns                   |  |
| Opposing Direction       | $t_{PSKOD}$           |     | 0.7 | 3.0 | ns                   |  |
| Jitter                   |                       |     | 800 |     | ps p-p               | See the Jitter Measurement section                           |

| Parameter                                    | Symbol       | Min                  | Typ             | Max                  | Unit        | Test Conditions/Comments  |
|--|--------------|----------------------|-----------------|----------------------|-------------|---|
| <b>DC SPECIFICATIONS</b>                     |              |                      |                 |                      |             |   |
| Input Threshold                              |              |                      |                 |                      |             |   |
| Logic High                                   | $V_{IH}$     | $0.7 \times V_{DDx}$ |                 |                      | V           |   |
| Logic Low                                    | $V_{IL}$     |                      |                 | $0.3 \times V_{DDx}$ | V           |   |
| Output Voltage                               |              |                      |                 |                      |             |   |
| Logic High                                   | $V_{OH}$     | $V_{DDx} - 0.1$      | $V_{DDx}$       |                      | V           | $I_{Ox}^1 = -20 \mu A, V_{Ix} = V_{IxH}^2$                          |
| Logic Low                                    | $V_{OL}$     | $V_{DDx} - 0.4$      | $V_{DDx} - 0.2$ | 0.1                  | V           | $I_{Ox}^1 = -2 \text{ mA}, V_{Ix} = V_{IxH}^2$                      |
|  |              |                      | 0.0             | 0.2                  | V           | $I_{Ox}^1 = 20 \mu A, V_{Ix} = V_{IxL}^3$                           |
|  |              |                      | 0.2             | 0.4                  | V           | $I_{Ox}^1 = 2 \text{ mA}, V_{Ix} = V_{IxL}^3$                       |
| Input Current per Channel                    | $I_I$        | -10                  | +0.01           | +10                  | $\mu A$     | $0 V \leq V_{Ix} \leq V_{DDx}$                                      |
| $V_{E2}$ Enable Input Pull-Up Current        | $I_{PU}$     | -10                  | -3              |                      | $\mu A$     | $V_{E2} = 0 V$  |
| DISABLE <sub>1</sub> Input Pull-Down Current | $I_{PD}$     |                      | 9               | 15                   | $\mu A$     | DISABLE <sub>1</sub> = $V_{DDx}$                                    |
| Tristate Output Current per Channel          | $I_{OZ}$     | -10                  | +0.01           | +10                  | $\mu A$     | $0 V \leq V_{Ox} \leq V_{DDx}$                                      |
| Supply Current per Channel                   |              |                      |                 |                      |             |   |
| Quiescent Input                              | $I_{DDI(Q)}$ |                      | 0.3             | 0.5                  | mA          | $V_i^4 = 0 (E0, D0), 1 (E1, D1)^5$                                  |
| Quiescent Output                             | $I_{DDO(Q)}$ |                      | 0.5             | 0.66                 | mA          | $V_i^4 = 0 (E0, D0), 1 (E1, D1)^5$                                  |
| Quiescent Input                              | $I_{DDI(Q)}$ |                      | 3.0             | 4.9                  | mA          | $V_i^4 = 1 (E0, D0), 0 (E1, D1)^5$                                  |
| Quiescent Output                             | $I_{DDO(Q)}$ |                      | 0.5             | 0.69                 | mA          | $V_i^4 = 1 (E0, D0), 0 (E1, D1)^5$                                  |
| Dynamic Input                                | $I_{DDI(D)}$ |                      | 0.01            |                      | mA/Mbps     | Inputs switching, 50% duty cycle                                    |
| Dynamic Output                               | $I_{DDO(D)}$ |                      | 0.01            |                      | mA/Mbps     | Inputs switching, 50% duty cycle                                    |
| Undervoltage Lockout                         |              |                      |                 |                      |             |   |
| Positive $V_{DDx}$ Threshold                 | $V_{DDxUV+}$ |                      | 1.6             |                      | V           |   |
| Negative $V_{DDx}$ Threshold                 | $V_{DDxUV-}$ |                      | 1.5             |                      | V           |   |
| $V_{DDx}$ Hysteresis                         | $V_{DDxUVH}$ |                      | 0.1             |                      | V           |   |
| <b>AC SPECIFICATIONS</b>                     |              |                      |                 |                      |             |   |
| Output Rise/Fall Time                        | $t_R/t_F$    |                      | 2.5             |                      | ns          | 10% to 90%  |
| Common-Mode Transient Immunity <sup>6</sup>  | $ CM_H $     | 75                   | 100             |                      | kV/ $\mu s$ | $V_{Ix} = V_{DDx}, V_{CM} = 1000 V,$<br>transient magnitude = 800 V |
|  | $ CM_L $     | 75                   | 100             |                      | kV/ $\mu s$ | $V_{Ix} = 0 V, V_{CM} = 1000 V,$<br>transient magnitude = 800 V     |

<sup>1</sup>  $I_{Ox}$  is the Channel x output current, where x = A, B, C, or D.

<sup>2</sup>  $V_{IxH}$  is the input side logic high.

<sup>3</sup>  $V_{IxL}$  is the input side logic low.

<sup>4</sup>  $V_i$  is the voltage input.

<sup>5</sup> E0 is the ADuM140E0 model, D0 is the ADuM140D0 model, E1 is the ADuM140E1 model, and D1 is the ADuM140D1 model. See the Ordering Guide section.

<sup>6</sup>  $|CM_H|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining the voltage output ( $V_O$ ) > 0.8  $V_{DDx}$ .  $|CM_L|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining  $V_O > 0.8 V$ . The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

**Table 6. Total Supply Current vs. Data Throughput**

| Parameter             | Symbol    | 1 Mbps |     |     | 25 Mbps |     |      | 100 Mbps |      |      | Unit |
|-----------------------|-----------|--------|-----|-----|---------|-----|------|----------|------|------|------|
|                       |           | Min    | Typ | Max | Min     | Typ | Max  | Min      | Typ  | Max  |      |
| <b>SUPPLY CURRENT</b> |           |        |     |     |         |     |      |          |      |      |      |
| Supply Current Side 1 | $I_{DD1}$ |        | 6.5 | 9.8 |         | 7.3 | 11.1 |          | 10.4 | 15.5 | mA   |
| Supply Current Side 2 | $I_{DD2}$ |        | 2.0 | 3.6 |         | 3.3 | 5.2  |          | 7.3  | 10.2 | mA   |

**ELECTRICAL CHARACTERISTICS—1.8 V OPERATION**

All typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = V_{DD2} = 1.8\text{ V}$ . Minimum/maximum specifications apply over the entire recommended operation range:  $1.7\text{ V} \leq V_{DD1} \leq 1.9\text{ V}$ ,  $1.7\text{ V} \leq V_{DD2} \leq 1.9\text{ V}$ , and  $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , unless otherwise noted. Switching specifications are tested with  $C_L = 15\text{ pF}$  and CMOS signal levels, unless otherwise noted. Supply currents are specified with 50% duty cycle signals.

Table 7.

| Parameter                                    | Symbol                | Min                  | Typ             | Max                  | Unit                 | Test Conditions/Comments  |
|--|-----------------------|----------------------|-----------------|----------------------|----------------------|---|
| <b>SWITCHING SPECIFICATIONS</b>              |                       |                      |                 |                      |                      |   |
| Pulse Width                                  | PW                    | 6.6                  |                 |                      | ns                   | Within PWD limit  |
| Data Rate                                    |                       | 150                  |                 |                      | Mbps                 | Within PWD limit  |
| Propagation Delay                            | $t_{PHL}$ , $t_{PLH}$ | 5.8                  | 8.7             | 15                   | ns                   | 50% input to 50% output   |
| Pulse Width Distortion                       | PWD                   |                      | 0.7             | 3                    | ns                   | $ t_{PLH} - t_{PHL} $   |
| Change vs. Temperature                       |                       |                      | 1.5             |                      | ps/ $^\circ\text{C}$ |   |
| Propagation Delay Skew                       | $t_{PSK}$             |                      |                 | 7.0                  | ns                   | Between any two units at the same temperature, voltage, and load                  |
| Channel Matching                             |                       |                      |                 |                      |                      |   |
| Codirectional                                | $t_{PSKCD}$           |                      | 0.7             | 3.0                  | ns                   |   |
| Opposing Direction                           | $t_{PSKOD}$           |                      | 0.7             | 3.0                  | ns                   |   |
| Jitter                                       |                       |                      | 470             |                      | ps p-p               | See the Jitter Measurement section  |
| <b>DC SPECIFICATIONS</b>                     |                       |                      |                 |                      |                      |   |
| Input Threshold                              |                       |                      |                 |                      |                      |   |
| Logic High                                   | $V_{IH}$              | $0.7 \times V_{DDx}$ |                 |                      | V                    |   |
| Logic Low                                    | $V_{IL}$              |                      |                 | $0.3 \times V_{DDx}$ | V                    |   |
| Output Voltage                               |                       |                      |                 |                      |                      |   |
| Logic High                                   | $V_{OH}$              | $V_{DDx} - 0.1$      | $V_{DDx}$       |                      | V                    | $I_{Ox}^1 = -20\ \mu\text{A}$ , $V_{Ix} = V_{IxH}^2$                              |
|  |                       | $V_{DDx} - 0.4$      | $V_{DDx} - 0.2$ |                      | V                    | $I_{Ox}^1 = -2\ \text{mA}$ , $V_{Ix} = V_{IxH}^2$                                 |
| Logic Low                                    | $V_{OL}$              |                      | 0.0             | 0.1                  | V                    | $I_{Ox}^1 = 20\ \mu\text{A}$ , $V_{Ix} = V_{IxL}^3$                               |
|  |                       |                      | 0.2             | 0.4                  | V                    | $I_{Ox}^1 = 2\ \text{mA}$ , $V_{Ix} = V_{IxL}^3$                                  |
| Input Current per Channel                    | $I_i$                 | -10                  | +0.01           | +10                  | $\mu\text{A}$        | $0\text{ V} \leq V_{Ix} \leq V_{DDx}$   |
| $V_{E2}$ Enable Input Pull-Up Current        | $I_{PU}$              | -10                  | -3              |                      | $\mu\text{A}$        | $V_{E2} = 0\text{ V}$   |
| DISABLE <sub>1</sub> Input Pull-Down Current | $I_{PD}$              |                      | 9               | 15                   | $\mu\text{A}$        | DISABLE <sub>1</sub> = $V_{DDx}$  |
| Tristate Output Current per Channel          | $I_{OZ}$              | -10                  | +0.01           | +10                  | $\mu\text{A}$        | $0\text{ V} \leq V_{Ox} \leq V_{DDx}$   |
| Supply Current per Channel                   |                       |                      |                 |                      |                      |   |
| Quiescent Input                              | $I_{DDI(Q)}$          |                      | 0.3             | 0.48                 | mA                   | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                                     |
| Quiescent Output                             | $I_{DDO(Q)}$          |                      | 0.5             | 0.66                 | mA                   | $V_i^4 = 0$ (E0, D0), 1 (E1, D1) <sup>5</sup>                                     |
| Quiescent Input                              | $I_{DDI(Q)}$          |                      | 3.0             | 4.9                  | mA                   | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                                     |
| Quiescent Output                             | $I_{DDO(Q)}$          |                      | 0.5             | 0.69                 | mA                   | $V_i^4 = 1$ (E0, D0), 0 (E1, D1) <sup>5</sup>                                     |
| Dynamic Input                                | $I_{DDI(D)}$          |                      | 0.01            |                      | mA/Mbps              | Inputs switching, 50% duty cycle  |
| Dynamic Output                               | $I_{DDO(D)}$          |                      | 0.01            |                      | mA/Mbps              | Inputs switching, 50% duty cycle  |
| Undervoltage Lockout                         | UVLO                  |                      |                 |                      |                      |   |
| Positive $V_{DDx}$ Threshold                 | $V_{DDxUV+}$          |                      | 1.6             |                      | V                    |   |
| Negative $V_{DDx}$ Threshold                 | $V_{DDxUV-}$          |                      | 1.5             |                      | V                    |   |
| $V_{DDx}$ Hysteresis                         | $V_{DDxUVH}$          |                      | 0.1             |                      | V                    |   |
| <b>AC SPECIFICATIONS</b>                     |                       |                      |                 |                      |                      |   |
| Output Rise/Fall Time                        | $t_R/t_F$             |                      | 2.5             |                      | ns                   | 10% to 90%  |
| Common-Mode Transient Immunity <sup>6</sup>  | $ CM_H $              | 75                   | 100             |                      | kV/ $\mu\text{s}$    | $V_{Ix} = V_{DDx}$ , $V_{CM} = 1000\text{ V}$ ,<br>transient magnitude = 800 V    |
|  | $ CM_L $              | 75                   | 100             |                      | kV/ $\mu\text{s}$    | $V_{Ix} = 0\text{ V}$ , $V_{CM} = 1000\text{ V}$ ,<br>transient magnitude = 800 V |

<sup>1</sup>  $I_{Ox}$  is the Channel x output current, where x = A, B, C, or D.

<sup>2</sup>  $V_{IxH}$  is the input side logic high.

<sup>3</sup>  $V_{IxL}$  is the input side logic low.

<sup>4</sup>  $V_i$  is the voltage input.

<sup>5</sup> E0 is the ADuM140E0 model, D0 is the ADuM140D0 model, E1 is the ADuM140E1 model, and D1 is the ADuM140D1 model. See the Ordering Guide section.

<sup>6</sup>  $|CM_H|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining the voltage output ( $V_O$ ) > 0.8  $V_{DDx}$ .  $|CM_L|$  is the maximum common-mode voltage slew rate that can be sustained while maintaining  $V_O > 0.8\text{ V}$ . The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

Table 8. Total Supply Current vs. Data Throughput

| Parameter             | Symbol           | 1 Mbps |     |     | 25 Mbps |     |     | 100 Mbps |      |      | Unit |
|-----------------------|------------------|--------|-----|-----|---------|-----|-----|----------|------|------|------|
|                       |                  | Min    | Typ | Max | Min     | Typ | Max | Min      | Typ  | Max  |      |
| SUPPLY CURRENT        |                  |        |     |     |         |     |     |          |      |      |      |
| Supply Current Side 1 | I <sub>DD1</sub> |        | 6.4 | 9.8 |         | 7.2 | 11  |          | 10.2 | 15.2 | mA   |
| Supply Current Side 2 | I <sub>DD2</sub> |        | 1.9 | 3.5 |         | 3.1 | 5.0 |          | 6.8  | 10   | mA   |

## INSULATION AND SAFETY RELATED SPECIFICATIONS

For additional information, see [www.analog.com/icouplersafety](http://www.analog.com/icouplersafety).

Table 9.

| Parameter   | Symbol  | Value      | Unit   | Test Conditions/Comments   |
|---|---------|------------|--------|--|
| Rated Dielectric Insulation Voltage   |         | 3750       | V rms  | 1-minute duration  |
| Minimum External Air Gap (Clearance)  | L (I01) | 7.8        | mm min | Measured from input terminals to output terminals, shortest distance through air   |
| Minimum External Tracking (Creepage)  | L (I02) | 7.8        | mm min | Measured from input terminals to output terminals, shortest distance path along body                                       |
| Minimum Clearance in the Plane of the Printed Circuit Board (PCB Clearance) | L (PCB) | 8.1        | mm min | Measured from input terminals to output terminals, shortest distance through air, line of sight, in the PCB mounting plane |
| Minimum Internal Gap (Internal Clearance)                                   |         | 25.5       | μm min | Insulation distance through insulation   |
| Tracking Resistance (Comparative Tracking Index) Material Group             | CTI     | >400<br>II | V      | DIN IEC 112/VDE 0303 Part 1<br>Material Group (DIN VDE 0110, 1/89, Table 1)  |

## PACKAGE CHARACTERISTICS

Table 10.

| Parameter                                  | Symbol           | Min | Typ              | Max | Unit | Test Conditions/Comments                            |
|--|------------------|-----|------------------|-----|------|---|
| Resistance (Input to Output) <sup>1</sup>  | R <sub>I-O</sub> |     | 10 <sup>13</sup> |     | Ω    |   |
| Capacitance (Input to Output) <sup>1</sup> | C <sub>I-O</sub> |     | 2.2              |     | pF   | f = 1 MHz   |
| Input Capacitance <sup>2</sup>             | C <sub>I</sub>   |     | 4.0              |     | pF   |   |
| IC Junction to Ambient Thermal Resistance  | θ <sub>JA</sub>  |     | 45               |     | °C/W | Thermocouple located at center of package underside |

<sup>1</sup> The device is considered a 2-terminal device: Pin 1 through Pin 8 are shorted together, and Pin 9 through Pin 16 are shorted together.

<sup>2</sup> Input capacitance is from any input data pin to ground.

**REGULATORY INFORMATION**

See Table 15 and the Insulation Lifetime section for details regarding recommended maximum working voltages for specific cross-isolation waveforms and insulation levels.

**Table 11.**

| <b>UL (Pending)</b>   | <b>CSA (Pending)</b>   | <b>VDE (Pending)</b>   | <b>CQC (Pending)</b>   |
|---|--|--|--|
| Recognized under 1577 Component Recognition Program <sup>1</sup><br>Single Protection, 3750 V rms Isolation Voltage | Approved under CSA Component Acceptance Notice 5A<br><br>Basic insulation per CSA 60950-1-07+A1+A2 and IEC 60950-1, Second Edition +A1+A2, 800 V rms (1131 V peak)<br>Reinforced insulation per CSA 60950-1-07+A1+A2 and IEC 60950-1 Second Edition +A1+A2, 400V rms (565 V peak) maximum working voltage<br>Reinforced insulation (2MOPP) per IEC 60601-1 Edition 3.1, 250 V rms (353 V peak) maximum<br>Reinforced insulation per CSA 61010-1-12 and IEC 61010-1 Third Edition (Pollution Degree 2, Material Group III, Overvoltage Category II, and Overvoltage Category III): 300 V rms (424 V peak) maximum working voltage | Certified according to DIN V VDE V 0884-10 (VDE V 0884-10):2006-12 <sup>2</sup><br>Reinforced insulation, 849 V peak | Certified by CQC11-471543-2012<br><br>Basic insulation per GB4943.1-2011<br><br>Working voltage 800 V rms (1131 V peak), tropical climate, altitude ≤5000 meters |
| File E214100  | File 205078  | File 2471900-4880-0001   | File (pending)   |

<sup>1</sup> In accordance with UL 1577, each ADuM140D/ADuM140E is proof tested by applying an insulation test voltage ≥ 4500 V rms for 1 sec.

<sup>2</sup> In accordance with DIN V VDE V 0884-10, each ADuM140D/ADuM140E is proof tested by applying an insulation test voltage ≥ 1018 V peak for 1 sec (partial discharge detection limit = 5 pC). The \* marking branded on the component designates DIN V VDE V 0884-10 approval.

**DIN V VDE V 0884-10 (VDE V 0884-10) INSULATION CHARACTERISTICS**

These isolators are suitable for reinforced electrical isolation only within the safety limit data. Protective circuits ensure the maintenance of the safety data. The \* marking on packages denotes DIN V VDE V 0884-10 approval.

Table 12.

| Description   | Test Conditions/Comments   | Symbol      | Characteristic                  | Unit   |
|---|--|-------------|---------------------------------|--------|
| Installation Classification per DIN VDE 0110<br>For Rated Mains Voltage ≤ 150 V rms<br>For Rated Mains Voltage ≤ 300 V rms<br>For Rated Mains Voltage ≤ 400 V rms |  |             | I to IV<br>I to III<br>I to III |        |
| Climatic Classification   |  |             | 40/125/21                       |        |
| Pollution Degree per DIN VDE 0110, Table 1  |  |             | 2                               |        |
| Maximum Working Insulation Voltage  |  | $V_{IORM}$  | 848                             | V peak |
| Input to Output Test Voltage, Method B1   | $V_{IORM} \times 1.875 = V_{pd(m)}$ , 100% production test,<br>$t_{ini} = t_m = 1$ sec, partial discharge < 5 pC | $V_{pd(m)}$ | 1592                            | V peak |
| Input to Output Test Voltage, Method A<br>After Environmental Tests Subgroup 1  | $V_{IORM} \times 1.5 = V_{pd(m)}$ , $t_{ini} = 60$ sec, $t_m = 10$ sec,<br>partial discharge < 5 pC              | $V_{pd(m)}$ | 1274                            | V peak |
| After Input and/or Safety Test Subgroup 2<br>and Subgroup 3   | $V_{IORM} \times 1.2 = V_{pd(m)}$ , $t_{ini} = 60$ sec, $t_m = 10$ sec,<br>partial discharge < 5 pC              |             | 1019                            | V peak |
| Highest Allowable Overvoltage   |  | $V_{IOTM}$  | 5303                            | V peak |
| Surge Isolation Voltage   | V peak = 12.8 kV, 1.2 μs rise time, 50 μs,<br>50% fall time  | $V_{IOSM}$  | 8000                            | V peak |
| Safety Limiting Values  | Maximum value allowed in the event of a<br>failure (see Figure 3)  |             |                                 |        |
| Maximum Junction Temperature  |  | $T_S$       | 150                             | °C     |
| Total Power Dissipation at 25°C   |  | $P_S$       | 2.78                            | W      |
| Insulation Resistance at $T_S$  | $V_{IO} = 500$ V   | $R_S$       | >10 <sup>9</sup>                | Ω      |

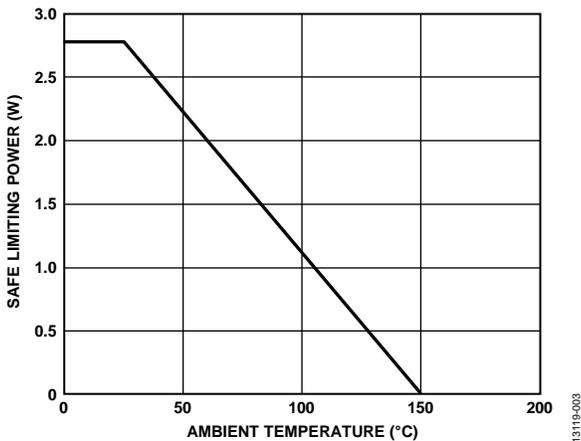


Figure 3. Thermal Derating Curve, Dependence of Safety Limiting Values with Ambient Temperature per DIN V VDE V 0884-10

**RECOMMENDED OPERATING CONDITIONS**

Table 13.

| Parameter                        | Symbol             | Rating          |
|----------------------------------|--------------------|-----------------|
| Operating Temperature            | $T_A$              | -40°C to +125°C |
| Supply Voltages                  | $V_{DD1}, V_{DD2}$ | 1.7 V to 5.5 V  |
| Input Signal Rise and Fall Times |                    | 1.0 ms          |

## ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

Table 14.

| Parameter  | Rating   |
|--|--|
| Storage Temperature ( $T_{ST}$ ) Range   | $-65^\circ\text{C}$ to $+150^\circ\text{C}$                  |
| Ambient Operating Temperature ( $T_A$ ) Range  | $-40^\circ\text{C}$ to $+125^\circ\text{C}$                  |
| Supply Voltages ( $V_{DD1}$ , $V_{DD2}$ )  | $-0.5\text{ V}$ to $+7.0\text{ V}$                           |
| Input Voltages ( $V_{IA}$ , $V_{IB}$ , $V_{IC}$ , $V_{ID}$ , $V_{E2}$ , $\text{DISABLE}_1$ ) | $-0.5\text{ V}$ to $V_{DD1} + 0.5\text{ V}$                  |
| Output Voltages ( $V_{OA}$ , $V_{OB}$ , $V_{OC}$ , $V_{OD}$ )                                | $-0.5\text{ V}$ to $V_{DDO} + 0.5\text{ V}$                  |
| Average Output Current per Pin <sup>3</sup>  |  |
| Side 1 Output Current ( $I_{O1}$ )   | $-10\text{ mA}$ to $+10\text{ mA}$                           |
| Side 2 Output Current ( $I_{O2}$ )   | $-10\text{ mA}$ to $+10\text{ mA}$                           |
| Common-Mode Transients <sup>4</sup>  | $-150\text{ kV}/\mu\text{s}$ to $+150\text{ kV}/\mu\text{s}$ |

<sup>1</sup>  $V_{DD1}$  is the input side supply voltage.

<sup>2</sup>  $V_{DDO}$  is the output side supply voltage.

<sup>3</sup> See Figure 3 for the maximum rated current values for various temperatures.

<sup>4</sup> Refers to the common-mode transients across the insulation barrier.

Common-mode transients exceeding the absolute maximum ratings may cause latch-up or permanent damage.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

Table 15. Maximum Continuous Working Voltage<sup>1</sup>

| Parameter             | Rating      | Constraint  |
|-----------------------|-------------|---|
| AC Voltage            |             |   |
| Bipolar Waveform      |             |   |
| Basic Insulation      | 849 V peak  | 50-year minimum insulation lifetime   |
| Reinforced Insulation | 790 V peak  | 50-year minimum insulation lifetime   |
| Unipolar Waveform     |             |   |
| Basic Insulation      | 1698 V peak | 50-year minimum insulation lifetime   |
| Reinforced Insulation | 849 V peak  | 50-year minimum insulation lifetime   |
| DC Voltage            |             |   |
| Basic Insulation      | 1118 V peak | Lifetime limited by package creepage maximum approved working voltage per IEC 60950-1 |
| Reinforced Insulation | 559 V peak  | Lifetime limited by package creepage maximum approved working voltage per IEC 60950-1 |

<sup>1</sup> Refers to the continuous voltage magnitude imposed across the isolation barrier. See the Insulation Lifetime section for more details.

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

**Truth Tables****Table 16. ADuM140D Truth Table (Positive Logic)**

| <b>V<sub>ix</sub> Input<sup>1,2</sup></b> | <b>V<sub>DISABLE1</sub> Input<sup>1,2</sup></b> | <b>V<sub>DDI</sub> State<sup>2</sup></b> | <b>V<sub>DDO</sub> State<sup>2</sup></b> | <b>Default Low (D0),<sup>3</sup><br/>V<sub>Ox</sub> Output<sup>1,2</sup></b> | <b>Default High (D1),<sup>3</sup><br/>V<sub>Ox</sub> Output<sup>1,2</sup></b> | <b>Test Conditions/<br/>Comments</b> |
|---|---|--|--|--|---|--------------------------------------|
| L   | L or NC   | Powered                                  | Powered                                  | L  | L   | Normal operation                     |
| H   | L or NC   | Powered                                  | Powered                                  | H  | H   | Normal operation                     |
| X   | H   | Powered                                  | Powered                                  | L  | H   | Inputs disabled,<br>fail-safe output |
| X <sup>4</sup>                            | X <sup>4</sup>                                  | Unpowered                                | Powered                                  | L  | H   | Fail-safe output                     |
| X <sup>4</sup>                            | X <sup>4</sup>                                  | Powered                                  | Unpowered                                | Indeterminate  | Indeterminate   |                                      |

<sup>1</sup> H means high, L means low, X means don't care, and NC means not connected.

<sup>2</sup> V<sub>ix</sub> and V<sub>Ox</sub> refer to the input and output signals of a given channel (A, B, C, or D). V<sub>DISABLE1</sub> refers to the input disable signal on the same side as the V<sub>ix</sub> inputs. V<sub>DDI</sub> and V<sub>DDO</sub> refer to the supply voltages on the input and output sides of the given channel, respectively.

<sup>3</sup> D0 is the ADuM140D0 model and D1 is the ADuM140D1 model. See the Ordering Guide section.

<sup>4</sup> Input pins (V<sub>ix</sub>, DISABLE<sub>1</sub>, and V<sub>E2</sub>) on the same side as an unpowered supply must be in a low state to avoid powering the device through its ESD protection circuitry.

**Table 17. ADuM140E Truth Table (Positive Logic)**

| <b>V<sub>ix</sub> Input<sup>1,2</sup></b> | <b>V<sub>Ex</sub> Input<sup>1,2</sup></b> | <b>V<sub>DDI</sub> State<sup>2</sup></b> | <b>V<sub>DDO</sub> State<sup>2</sup></b> | <b>Default Low (E0),<sup>3</sup><br/>V<sub>Ox</sub> Output<sup>1,2</sup></b> | <b>Default High (E1),<sup>3</sup><br/>V<sub>Ox</sub> Output<sup>1,2</sup></b> | <b>Test Conditions/<br/>Comments</b> |
|---|---|--|--|--|---|--------------------------------------|
| L   | H or NC                                   | Powered                                  | Powered                                  | L  | L   | Normal operation                     |
| H   | H or NC                                   | Powered                                  | Powered                                  | H  | H   | Normal operation                     |
| X   | L   | Powered                                  | Powered                                  | Z  | Z   | Outputs disabled                     |
| L   | H or NC                                   | Unpowered                                | Powered                                  | L  | H   | Fail-safe output                     |
| X <sup>4</sup>                            | L <sup>4</sup>                            | Unpowered                                | Powered                                  | Z  | Z   | Outputs disabled                     |
| X <sup>4</sup>                            | X <sup>4</sup>                            | Powered                                  | Unpowered                                | Indeterminate  | Indeterminate   |                                      |

<sup>1</sup> H means high, L means low, X means don't care, and NC means not connected, and Z means high impedance.

<sup>2</sup> V<sub>ix</sub> and V<sub>Ox</sub> refer to the input and output signals of a given channel (A, B, C, or D). V<sub>DISABLE1</sub> refers to the input disable signal on the same side as the V<sub>ix</sub> inputs. V<sub>DDI</sub> and V<sub>DDO</sub> refer to the supply voltages on the input and output sides of the given channel, respectively.

<sup>3</sup> E0 is the ADuM140E0 model and E1 is the ADuM140E1 model. See the Ordering Guide section.

<sup>4</sup> Input pins (V<sub>ix</sub>, DISABLE<sub>1</sub>, and V<sub>E2</sub>) on the same side as an unpowered supply must be in a low state to avoid powering the device through its ESD protection circuitry.

## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

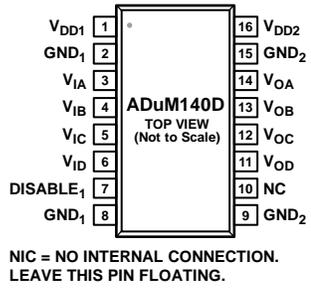


Figure 4. ADuM140D Pin Configuration

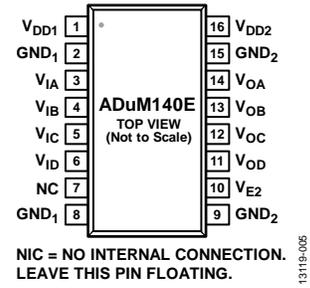


Figure 5. ADuM140E Pin Configuration

Reference the [AN-1109 Application Note](#) for specific layout guidelines.

Table 18. Pin Function Descriptions

| Pin No.        |                | Mnemonic             | Description   |
|----------------|----------------|----------------------|---|
| ADuM140D       | ADuM140E       |                      |   |
| 1              | 1              | V <sub>DD1</sub>     | Supply Voltage for Isolator Side 1.   |
| 2, 8           | 2, 8           | GND <sub>1</sub>     | Ground 1. Ground reference for Isolator Side 1.   |
| 3              | 3              | V <sub>IA</sub>      | Logic Input A.  |
| 4              | 4              | V <sub>IB</sub>      | Logic Input B.  |
| 5              | 5              | V <sub>IC</sub>      | Logic Input C.  |
| 6              | 6              | V <sub>ID</sub>      | Logic Input D.  |
| 7              | Not applicable | DISABLE <sub>1</sub> | Input Disable 1. This pin disables the isolator inputs. Outputs take on the logic state determined by the fail-safe option shown in the Ordering Guide.   |
| 9, 15          | 9, 15          | GND <sub>2</sub>     | Ground 2. Ground reference for Isolator Side 2.   |
| 10             | 7              | NIC                  | No Internal Connection. Leave this pin floating.  |
| Not applicable | 10             | V <sub>E2</sub>      | Output Enable 2. Active high logic input. When V <sub>E2</sub> is high or disconnected, the V <sub>OA</sub> , V <sub>OB</sub> , V <sub>OC</sub> , and V <sub>OD</sub> outputs are enabled. When V <sub>E2</sub> is low, the V <sub>OA</sub> , V <sub>OB</sub> , V <sub>OC</sub> , and V <sub>OD</sub> outputs are disabled to the high-Z state. |
| 11             | 11             | V <sub>OD</sub>      | Logic Output D.   |
| 12             | 12             | V <sub>OC</sub>      | Logic Output C.   |
| 13             | 13             | V <sub>OB</sub>      | Logic Output B.   |
| 14             | 14             | V <sub>OA</sub>      | Logic Output A.   |
| 16             | 16             | V <sub>DD2</sub>     | Supply Voltage for Isolator Side 2.   |

TYPICAL PERFORMANCE CHARACTERISTICS

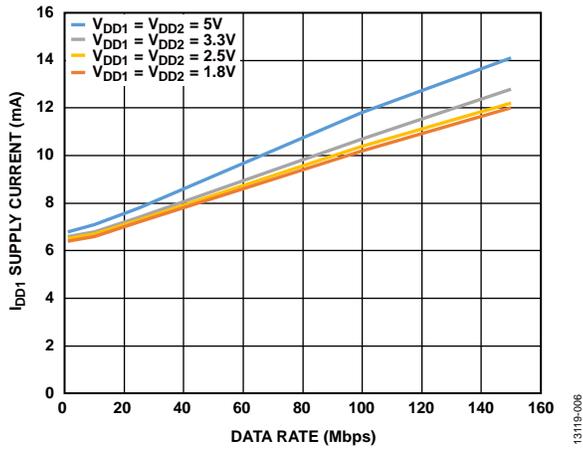


Figure 6. I<sub>DD1</sub> Supply Current vs. Data Rate at Various Voltages

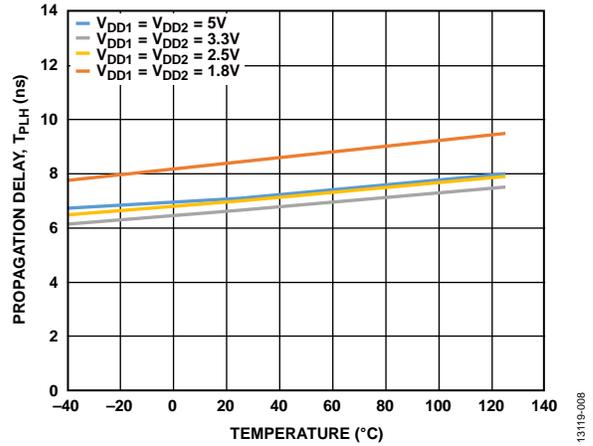


Figure 8. Propagation Delay, T<sub>PLH</sub> vs. Temperature at Various Voltages

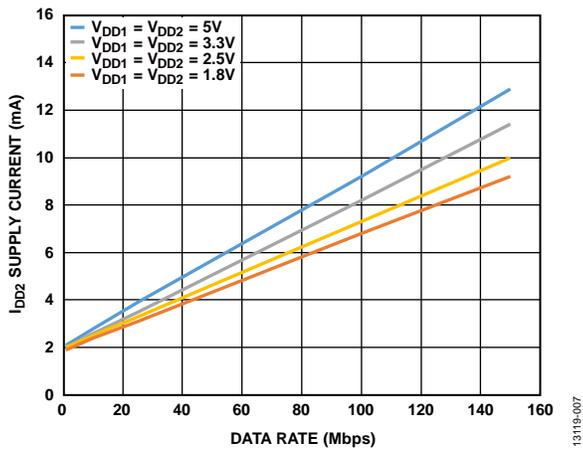


Figure 7. I<sub>DD2</sub> Supply Current vs. Data Rate at Various Voltages

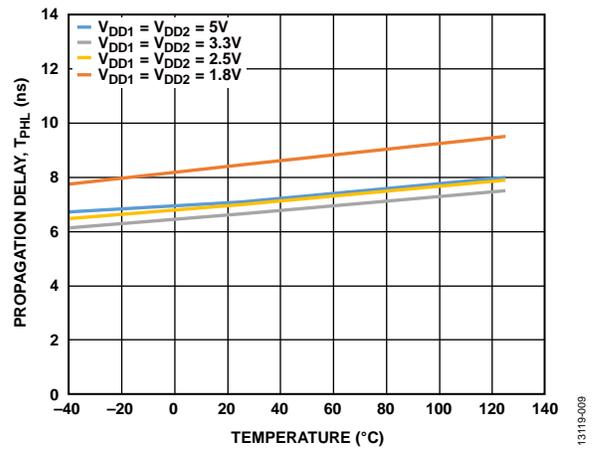


Figure 9. Propagation Delay, T<sub>PHL</sub> vs. Temperature at Various Voltages

# APPLICATIONS INFORMATION

## OVERVIEW

The ADuM140D/ADuM140E use a high frequency carrier to transmit data across the isolation barrier using iCoupler chip scale transformer coils separated by layers of polyimide isolation. Using an on-off keying (OOK) technique and the differential architecture shown in Figure 11 and Figure 12, the ADuM140D/ADuM140E have very low propagation delay and high speed. Internal regulators and input/output design techniques allow logic and supply voltages over a wide range from 1.7 V to 5.5 V, offering voltage translation of 1.8 V, 2.5 V, 3.3 V, and 5 V logic. The architecture is designed for high common-mode transient immunity and high immunity to electrical noise and magnetic interference. Radiated emissions are minimized with a spread spectrum OOK carrier and other techniques.

Figure 11 illustrates the waveforms for models of the ADuM140D/ADuM140E with the condition of the fail-safe output state equal to low, where the carrier waveform is off when the input state is low. If the input side is off or not operating, the fail-safe output state of low sets the output to low. For the ADuM140D/ADuM140E with a fail-safe output state of high, Figure 12 illustrates the conditions where the carrier waveform is off when the input state is high. When the input side is off or not operating, the fail-safe output state of high sets the output to high. See the Ordering Guide for the model numbers that have the fail-safe output state of low or the fail-safe output state of high.

## PCB LAYOUT

The ADuM140D/ADuM140E digital isolators require no external interface circuitry for the logic interfaces. Power supply bypassing is strongly recommended at the input and output supply pins (see Figure 10). Bypass capacitors are most conveniently connected between Pin 1 and Pin 2 for V<sub>DD1</sub> and between Pin 15 and Pin 16 for V<sub>DD2</sub>. The recommended bypass capacitor value is between 0.01 μF and 0.1 μF. The total lead length between both ends of the capacitor and the input power supply pin must not exceed 10 mm. Bypassing between Pin 1 and Pin 8 and between Pin 9 and Pin 16 must also be considered, unless the ground pair on each package side is connected close to the package.

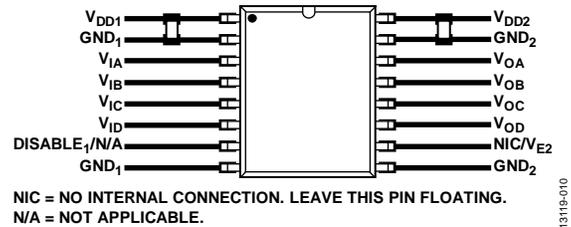


Figure 10. Recommended Printed Circuit Board Layout

In applications involving high common-mode transients, ensure that board coupling across the isolation barrier is minimized. Furthermore, design the board layout such that any coupling that does occur equally affects all pins on a given component side. Failure to ensure this can cause voltage differentials between pins exceeding the Absolute Maximum Ratings of the device, thereby leading to latch-up or permanent damage.

See the AN-1109 Application Note for board layout guidelines.

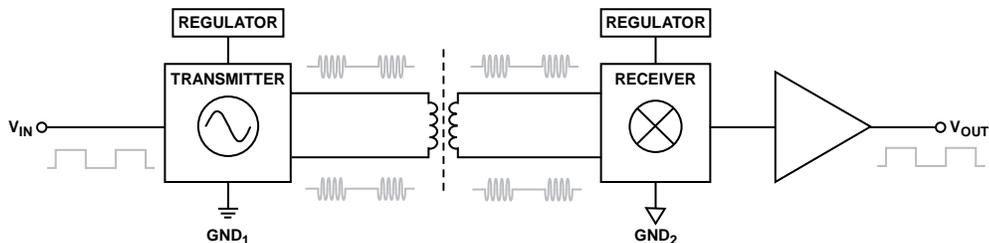


Figure 11. Operational Block Diagram of a Single Channel with a Low Fail-Safe Output State

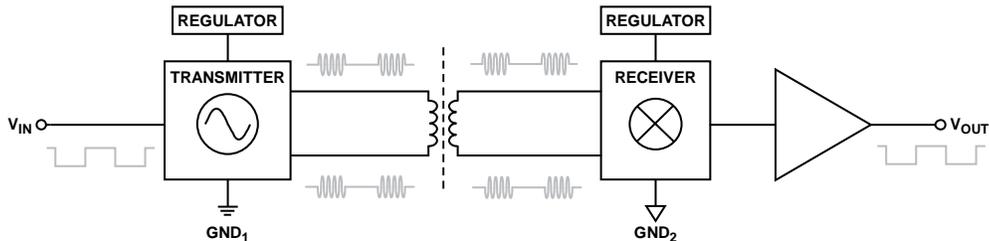


Figure 12. Operational Block Diagram of a Single Channel with a High Fail-Safe Output State

## PROPAGATION DELAY RELATED PARAMETERS

Propagation delay is a parameter that describes the time it takes a logic signal to propagate through a component. The propagation delay to a Logic 0 output may differ from the propagation delay to a Logic 1 output.

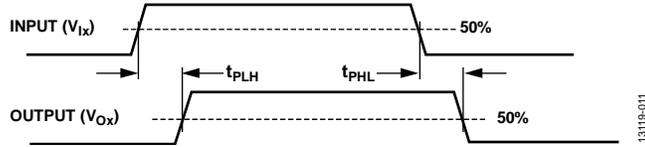


Figure 13. Propagation Delay Parameters

Pulse width distortion is the maximum difference between these two propagation delay values and is an indication of how accurately the timing of the input signal is preserved.

Channel matching is the maximum amount the propagation delay differs between channels within a single ADuM140D/ADuM140E component.

Propagation delay skew is the maximum amount the propagation delay differs between multiple ADuM140D/ADuM140E components operating under the same conditions

## JITTER MEASUREMENT

Figure 14 shows the eye diagram for the ADuM140D/ADuM140E. The measurement was taken using an Agilent 81110A pulse pattern generator at 150 Mbps with pseudorandom bit sequences (PRBS)  $2(n - 1)$ ,  $n = 14$ , for 5 V supplies. Jitter was measured with the Tektronix Model 5104B oscilloscope, 1 GHz, 10 GS/sec with the DPOJET jitter and eye diagram analysis tools. The result shows a typical measurement on the ADuM140D/ADuM140E with 490 ps p-p jitter.

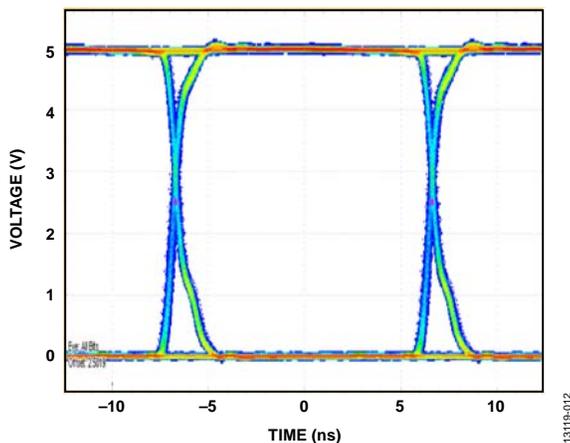


Figure 14. ADuM140D/ADuM140E Eye Diagram

## INSULATION LIFETIME

All insulation structures eventually break down when subjected to voltage stress over a sufficiently long period. The rate of insulation degradation is dependent on the characteristics of the voltage waveform applied across the insulation as well as on the materials and material interfaces.

The two types of insulation degradation of primary interest are breakdown along surfaces exposed to the air and insulation wear out. Surface breakdown is the phenomenon of surface tracking, and the primary determinant of surface creepage requirements in system level standards. Insulation wear out is the phenomenon where charge injection or displacement currents inside the insulation material cause long-term insulation degradation.

### Surface Tracking

Surface tracking is addressed in electrical safety standards by setting a minimum surface creepage based on the working voltage, the environmental conditions, and the properties of the insulation material. Safety agencies perform characterization testing on the surface insulation of components that allows the components to be categorized in different material groups. Lower material group ratings are more resistant to surface tracking and, therefore, can provide adequate lifetime with smaller creepage. The minimum creepage for a given working voltage and material group is in each system level standard and is based on the total rms voltage across the isolation, pollution degree, and material group. The material group and creepage for the ADuM140D/ADuM140E isolators are presented in Table 9.

### Insulation Wear Out

The lifetime of insulation caused by wear out is determined by its thickness, material properties, and the voltage stress applied. It is important to verify that the product lifetime is adequate at the application working voltage. The working voltage supported by an isolator for wear out may not be the same as the working voltage supported for tracking. It is the working voltage applicable to tracking that is specified in most standards.

Testing and modeling have shown that the primary driver of long-term degradation is displacement current in the polyimide insulation causing incremental damage. The stress on the insulation can be broken down into broad categories, such as: dc stress, which causes very little wear out because there is no displacement current, and an ac component time varying voltage stress, which causes wear out.

The ratings in certification documents are usually based on 60 Hz sinusoidal stress because this reflects isolation from line voltage. However, many practical applications have combinations of 60 Hz ac and dc across the barrier as shown in Equation 1. Because only the ac portion of the stress causes wear out, the equation can be rearranged to solve for the ac rms voltage, as is shown in Equation 2. For insulation wear out with the polyimide materials used in these products, the ac rms voltage determines the product lifetime.

$$V_{RMS} = \sqrt{V_{AC\ RMS}^2 + V_{DC}^2} \tag{1}$$

or

$$V_{AC\ RMS} = \sqrt{V_{RMS}^2 - V_{DC}^2} \tag{2}$$

where:

$V_{AC\ RMS}$  is the time varying portion of the working voltage.

$V_{DC}$  is the dc offset of the working voltage.

$V_{RMS}$  is the total rms working voltage.

**Calculation and Use of Parameters Example**

The following example frequently arises in power conversion applications. Assume that the line voltage on one side of the isolation is 240 V<sub>AC RMS</sub> and a 400 V<sub>DC</sub> bus voltage is present on the other side of the isolation barrier. The isolator material is polyimide. To establish the critical voltages in determining the creepage, clearance and lifetime of a device, see Figure 15 and the following equations.

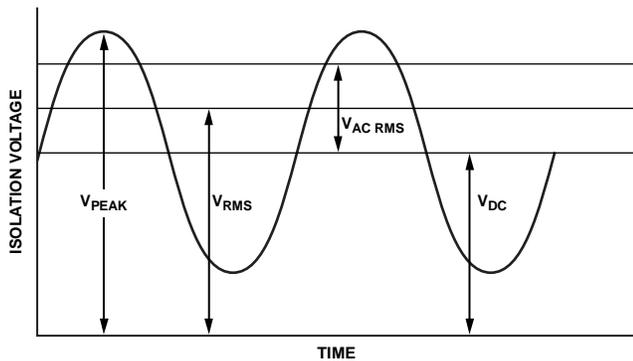


Figure 15. Critical Voltage Example

13119-013

The working voltage across the barrier from Equation 1 is

$$V_{RMS} = \sqrt{V_{AC\ RMS}^2 + V_{DC}^2}$$

$$V_{RMS} = \sqrt{240^2 + 400^2}$$

$$V_{RMS} = 466\ V$$

This is the working voltage used together with the material group and pollution degree when looking up the creepage required by a system standard.

To determine if the lifetime is adequate, obtain the time varying portion of the working voltage. To obtain the ac rms voltage, use Equation 2.

$$V_{AC\ RMS} = \sqrt{V_{RMS}^2 - V_{DC}^2}$$

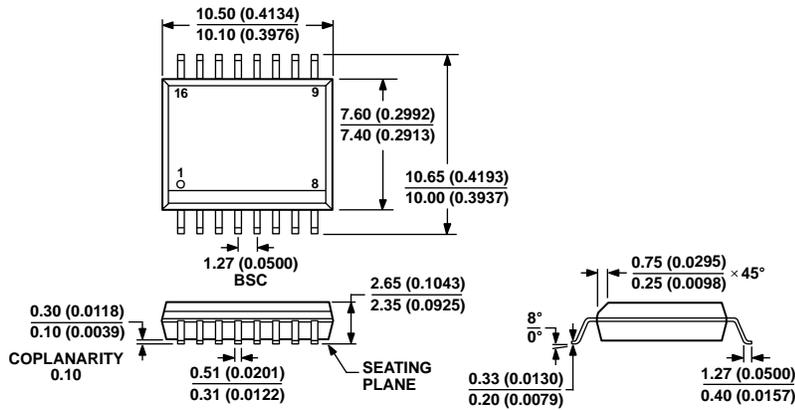
$$V_{AC\ RMS} = \sqrt{466^2 - 400^2}$$

$$V_{AC\ RMS} = 240\ V\ rms$$

In this case, the ac rms voltage is simply the line voltage of 240 V rms. This calculation is more relevant when the waveform is not sinusoidal. The value is compared to the limits for working voltage in Table 15 for the expected lifetime, less than a 60 Hz sine wave, and it is well within the limit for a 50-year service life.

Note that the dc working voltage limit in Table 15 is set by the creepage of the package as specified in IEC 60664-1. This value can differ for specific system level standards.

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-013-AA  
 CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS  
 (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR  
 REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

03-27-2007-B

Figure 16. 16-Lead Standard Small Outline Package [SOIC\_W]  
 Wide Body  
 (RW-16)

Dimensions shown in millimeters and (inches)

ORDERING GUIDE

| Model <sup>1</sup> | Temperature Range | No. of Inputs, V <sub>DD1</sub> Side | No. of Inputs, V <sub>DD2</sub> Side | Withstand Voltage Rating (kV rms) | Fail-Safe Output State | Input Disable | Output Enable | Package Description | Package Option |
|--------------------|-------------------|--------------------------------------|--------------------------------------|-----------------------------------|------------------------|---------------|---------------|---------------------|----------------|
| ADuM140D1BRWZ      | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | High                   | Yes           | No            | 16-Lead SOIC_W      | RW-16          |
| ADuM140D1BRWZ-RL   | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | High                   | Yes           | No            | 16-Lead SOIC_W      | RW-16          |
| ADuM140D0BRWZ      | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | Low                    | Yes           | No            | 16-Lead SOIC_W      | RW-16          |
| ADuM140D0BRWZ-RL   | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | Low                    | Yes           | No            | 16-Lead SOIC_W      | RW-16          |
| ADuM140E1BRWZ      | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | High                   | No            | Yes           | 16-Lead SOIC_W      | RW-16          |
| ADuM140E1BRWZ-RL   | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | High                   | No            | Yes           | 16-Lead SOIC_W      | RW-16          |
| ADuM140E0BRWZ      | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | Low                    | No            | Yes           | 16-Lead SOIC_W      | RW-16          |
| ADuM140E0BRWZ-RL   | -40°C to +125°C   | 4                                    | 0                                    | 3.75                              | Low                    | No            | Yes           | 16-Lead SOIC_W      | RW-16          |

<sup>1</sup> Z = RoHS Compliant Part.