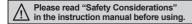
Shaft Type/Hollow Shaft Type/Blind Hollow Shaft Type Ø40mm Incremental Rotary Encoder

Features

- Easy installation at narrow space
- Low moment of inertia
- Power supply: 5VDC, 12-24VDC ±5%
- Various output types









E40HB Series

Ordering Information

| E40 H | | 8 | 5000 - | - 3 - | - N - | _ 24 - | - |
|---|-----------|--|-------------------|-----------------------|--|---------------------|--|
| Series | Shaft dia | meter | Pulses/revolution | Output phase | Control output | Power supply | Cable |
| Ø40mm S: shaft type | | 6: Ø6mm 8: Ø8mm | | 2: A, B 3: A, B, Z | T: Totem pole output N: NPN open collector | E · E\/DC +E% | No mark |
| Ø40mm H: hollow shaft type, HB: blind hollow shaft type | Inner | 6: Ø6mm 8: Ø8mm 10: Ø10mm 12: Ø12mm | | 4: A, Ā, B, B | output V: Voltage output L: Line driver output | 24: 12-24VDC ±5% | : Radial cable type C: Radial cable connector type |

E40S Series

Specifications

| Item | | | Shaft Type/Hollow Shaft Type/Blind Hollow Shaft Type Ø40mm Incremental Rotary Encoder | | | |
|--------------------------------|----------------------------|-------------------------------|---|--|--|--|
| Resolution (PPR) ^{×1} | |) ^{*1} | *1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000 | | | |
| Output phase | | se | A, B, Z phase (line driver A, \overline{A} , B, \overline{B} , Z, \overline{Z} phase) | | | |
| | Phase difference of output | | Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase) | | | |
| | | Totem pole output | • [Low] - Load current: max. 30mA, residual voltage: max. 0.4VDC=- • [High] - Load current: max. 10mA, output voltage (power voltage 5VDC=-): min. (power voltage-2.0)VDC=-, Output voltage (power voltage 12-24VDC=-): min. (power voltage-3.0)VDC=- | | | |
| _ | Control | NPN open collector output | Load current: max. 30mA, residual voltage: max. 0.4VDC== | | | |
| tion | output | Voltage output | Load current: max. 10mA, residual voltage: max. 0.4VDC== | | | |
| Electrical specification | | Line driver output | • [Low] - Load current: max. 20mA, residual voltage: max. 0.5VDC::- • [High] - Load current: max20mA, output voltage (power voltage 5VDC::-): min. 2.5VDC::-, Output voltage (power voltage 12-24VDC::-): min. (power voltage-3.0)VDC::- | | | |
| S | | Totem pole output | | | | |
| ica | Response time | NPN open collector output | Max. 1μs (cable length: 2m, I sink = 20mA) | | | |
| <u>t</u> | (rise/fall) | Voltage output | | | | |
| | | Line driver output | Max. 0.5µs (cable length: 2m, I sink = 20mA) | | | |
| | Max. respo | nse frequency | 300kHz | | | |
| | Power supply | | • 5VDC== ±5% (ripple P-P: max. 5%) • 12-24VDC== ±5% (ripple P-P: max. 5%) | | | |
| | Current cor | nsumption | Max. 80mA (disconnection of the load), line driver output: max. 50mA (disconnection of the load) | | | |
| | Insulation r | esistance | Over 100MΩ (at 500VDC megger between all terminals and case) | | | |
| | Dielectric s | trength | 750VAC 50/60Hz for 1 minute (between all terminals and case) | | | |
| | Connection | | Radial cable type, Radial cable connector type | | | |
| o g | Starting tor | que | • S type: max. 40gf·cm (0.004N·m) • H/HB type: max. 50gf·cm (0.005N·m) | | | |
| anic | Moment of | inertia | Max. 40g·cm² (4×10-6 kg·m²) | | | |
| | Shaft loadii | | Radial: max. 2kgf, Thrust: max. 1kgf | | | |
| ≅ g | Max. allowa | able revolution ^{*2} | 5,000rpm | | | |
| Vibra | tion | | 1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours | | | |
| Shoc | k | | Approx. max. 50G | | | |
| Fi | Ambient temperature | | -10 to 70°C, storage: -25 to 85°C | | | |
| Environment Ambient humidity | | Ambient humidity | 35 to 85%RH, storage: 35 to 90%RH | | | |
| Protection structure | | ure | IP50 (IEC standard) | | | |
| Cable | | | Ø5mm, 5-wire (line driver output: 8-wire), 2m, Shield cable (AWG24, core diameter: Ø1mm) | | | |
| Accessory | | | • S type: Ø6mm coupling, Ø8mm coupling • H/HB type: bracket | | | |
| Approval | | | C € (except line driver output) | | | |
| Unit v | weight | | Approx. 120g | | | |
| YVA IN I I I A D I VII I I | | | | | | |

X1: '*' pulse is only for A, B phase (line driver output is for A, A, B, B phase). Not indicated resolutions are customizable.
X2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

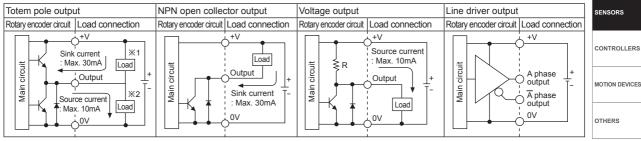
[Max. response revolution (rpm)= Max. response frequency × 60 sec] Resolution

XEnvironment resistance is rated at no freezing or condensation.

H-24 **Autonics**

Incremental Ø40mm Shaft/Hollow Shaft/Blind Hollow Shaft Type

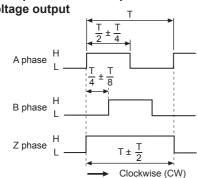
Control Output Diagram



- Totem pole output type can be used for NPN open collector output type (X1) or Voltage output type (X2).
- All output circuits of A, B, Z phase are same. (line driver output is A, A, B, B, Z, Z)

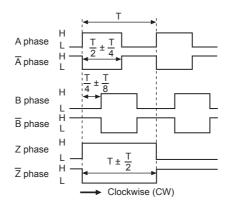
Output Waveform

 Totem pole output / NPN open collector output / Voltage output



XZ reverse phase output is optional.

• Line driver output





Pressure Sensors

(A) Photoelectric

Sensors

(B) Fiber Optic Sensors

(C) Door/Area

Sensors

(D) Vision

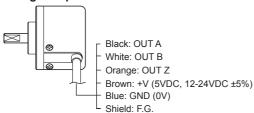
Sensors

Proximity Sensors

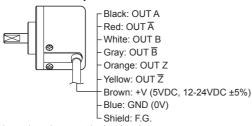
(H)
Connectors/
Connector Cables/
Sensor Distribution
Boxes/ Sockets

Connections

- Radial cable type
- Totem pole output / NPN open collector output / Voltage output



Line driver output



XNon-using wires must be insulated.

*The shield cable and metal case of encoder must be grounded (F.G.).

XDo not apply tensile strength over 30N to the cable.

Radial cable connector type

Totem pole output /
 NPN open collector output /
 Voltage output



| Pin No | Cable color | Function |
|--------|-------------|----------|
| 1 | Black | OUTA |
| 2 | White | OUT B |
| 3 | Orange | OUT Z |
| 4 | Brown | +V |
| (5) | Blue | GND |
| 6 | | F.G. |



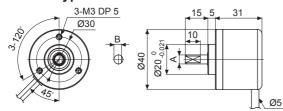
| Pin No | Cable color | Function |
|--------|-------------|----------|
| 1 | Black | OUT A |
| 2 | Red | OUTĀ |
| 3 | Brown | +V |
| 4 | Blue | GND |
| ⑤ | White | OUT B |
| 6 | Gray | OUT B |
| 7 | Orange | OUT Z |
| 8 | Yellow | OUT Z |
| 9 | Shield | F.G. |

XF.G. (field ground): It should be grounded separately.

Autonics G-25

Dimensions

⊚ Shaft type



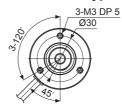
| Α | Ø6 | -0.004 -0.016 | Ø8 | -0.005 -0.02 |
|---|----|------------------|----|-----------------|
| В | 5 | | 7 | |

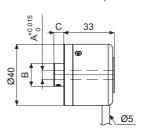
Cable for radial cable type

Ø5mm, 5-wire (line driver output: 8-wire), Length: 2m, Shield cable

Cable for radial cable connector type Ø5mm, 5-wire (line driver output: 8-wire), Length: 250mm, Shield cable

O Hollow shaft type





(unit: mm)

| Α | Ø6 | Ø8 | Ø10 | Ø12 |
|---|-----|----|-----|-----|
| В | Ø15 | | Ø17 | |
| С | 6.5 | | 6.3 | |

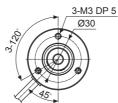
Cable for radial cable type Ø5mm, 5-wire (line driver output: 8-wire).

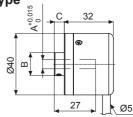
Length: 2m, Shield cable

Cable for radial cable connector type

Ø5mm, 5-wire (line driver output: 8-wire),
Length: 250mm, Shield cable

Blind hollow shaft type





| Α | Ø6 | Ø8 | Ø10 | Ø12 |
|---|-----|----|-----|-----|
| В | Ø15 | | Ø17 | |
| С | 6.5 | | 6.3 | |

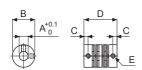
Cable for radial cable type

Ø5mm, 5-wire (line driver output: 8-wire)

Length: 2m, Shield cable

Cable for radial cable connector type Ø5mm, 5-wire (line driver output: 8-wire), Length: 250mm, Shield cable

O Coupling (shaft type)



- Parallel misalignment: max. 0.25mm
- Angular misalignment: max. 5°
- End-play: max. 0.5mm

| | Α | В | С | D | E |
|---------------------|----|-----|-----|----|------|
| E40S6 Ø6mm coupling | Ø6 | Ø15 | 2.8 | 22 | 4-M3 |
| E40S8 Ø8mm coupling | Ø8 | Ø19 | 3.4 | 25 | 4-M4 |

 $\normalfootnotemark{\mbox{\ensuremath{\mbox{χ}}}\mbox{\ensuremath{\mbox{\mbox{Do}}}}\mbox{\ensuremath{\mbox{\mbox{not}}}\mbox{\ensuremath{\mbox{put}}}\mbox{\ensuremath{\mbox{q}}}\mbox{\ensuremath{\mbox{mot}}}$

Failure to follow this instruction may result in product damage.

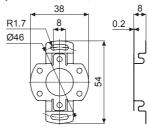
% Fix the unit or a coupling by a wrench under 0.15 N·m of torque.

When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.

※For parallel misalignment, angular misalignment, end-play terms, refer to page G-98.

※For flexible coupling (ERB series) information, refer to page G-91

(Hollow shaft, blind hollow shaft type)



G-26 Autonics