U-GAGE[™] S18U Series Sensors with Analog Output



Datasheet

18 mm Ultrasonic Sensors with TEACH-mode programming





WARNING:

- Do not use this device for personnel protection
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or deenergized (off) output condition.

Models

Model Number	Sensing Range	Cable ¹	Supply Voltage	Output	Housing Configuration	
S18UUA		5-wire, 2 m (6.5 ft) cable	5-wire, 2 m (6.5 ft) cable			
S18UUAQ		5-pin Euro style QD		0 V dc to 10 V dc	Chusischt	
S18UIA		5-wire, 2 m (6.5 ft) cable		4 mA to 20 mA	Straight	
S18UIAQ	30 mm to 300 mm	5-pin Euro style QD				
S18UUAR	(1.2 in to 11.8 in)	5-wire, 2 m (6.5 ft) cable				
S18UUARQ	_	5-pin Euro style QD	_	0 V dc to 10 V dc	Right-Angle	
S18UIAR		5-wire, 2 m (6.5 ft) cable				
S18UIARQ		5-pin Euro style QD		4 mA to 20 mA		

Note: Information about discrete models is available at http://www.bannerengineering.com.

9 m cables are available by adding suffix "W/30" to the model number of any cabled sensor (for example, S18UUA W/30).

• A model with a QD connector requires a mating cable.



¹

Configuration Instructions

Status Indicators

Power On/Off LED State	Indicates
Off	The power is off
On red	The target is weak or is outside of the sensing range
On green	The sensor is operating normally, target is good

Output/Teach LED State Indicates	
Off	The target is outside of the window limits
On yellow	The target is within the window limits
On red	The sensor is in TEACH mode and is waiting for the first limit
Flashing red	The sensor is in TEACH mode and is waiting for the second limit

Sensor Programming

Use one of two TEACH methods to program the sensor:

- Teach individual minimum and maximum limits
- Use Auto-Window feature to center a sensing window around the taught position

The sensor may be programmed either via its push button, or via a remote switch. Remote programming also may be used to disable the push button, preventing unauthorized personnel from adjusting the programming settings. To access this feature, connect the gray wire of the sensor to 0 V dc to 2 V dc, with a remote programming switch between the sensor and the voltage.

Note: The impedance of the Remote Teach input is $12 \text{ k}\Omega$.

Programming is accomplished by following the sequence of input pulses. The duration of each pulse (corresponding to a push button "click"), and the period between multiple pulses, are defined as "T": **0.04 seconds** < **T** < **0.8 seconds**.



Figure 1. TEACH Interface

Analog Output Slope

The U-GAGE S18U sensor may be programmed for either a positive or a negative output slope, based on which limit is taught first. If the Near limit is taught first, the slope will be positive. If the Far limit is taught first, the slope will be negative. Banner's scalable output automatically distributes the output signal over the width of the programmed sensing window.

In the event of signal loss, the analog output goes to 3.6 mA or 0 V dc, which may be used to trigger an alarm.

Figure 2. Analog Output Slope-Current-Sourcing Models

Figure 3. Analog Output Slope-Voltage-Sourcing Models





Teach Minimum and Maximum Limits

Note:

- The sensor returns to Run mode if the first Teach condition is not registered within 120 seconds
- After the first limit is taught, the sensor remains in Program mode until the Teach sequence is finished
- To exit Program mode without saving any changes, press and hold the programming push button > 2 seconds (before teaching the second limit). The sensor reverts to the last saved limits
- 1. Enter Programming mode.

Method	Action	Result
Push Button ²	Press and hold the TEACH button	Output LED: On red Power LED: On green (good signal) or
Remote Input ³	No action required; the sensor is ready for the first limit	On red (no signal)

- 2. Present the target for the first limit. The Power LED must be On green.
- 3. Teach the first limit.

Method	Action		Result
Push Button	Press the TEACH button one time.	ţ •	Teach Accepted (The sensor learns the 0 V dc or 4 mA limit)
Remote Input	Single-pulse the remote line.	T	Output LED: Flashes Red Teach Not Accepted Output LED: On Red

- 4. Present the target for the second limit. The Power LED must be On green.
- 5. Teach the second limit.

Method	Action		Result
Push Button	Press the TEACH button one time.	ţ •	Teach Accepted (The sensor learns the 10 V dc or 20 mA limit)
Remote Input	Single-pulse the remote line.		Output LED: Yellow or OFF Teach Not Accepted Output LED: Flashes Red

Teaching Limits Using the Auto-Window Feature

Teaching the same limit twice for the same output automatically centers a 10 mm window on the taught position.

2 0.04 s < "click" < 0.8 s

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3 0.04 s < T < 0.8 s
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Note:

- The sensor returns to Run mode if the first Teach condition is not registered within 120 seconds
- After the first limit is taught, the sensor remains in Program mode until the Teach sequence is finished
- To exit Program mode without saving any changes, press and hold the programming push button > 2 seconds (before teaching the second limit). The sensor reverts to the last saved limits
- Using this procedure, the analog output is centered on the taught position at approximately 5 V dc or 12 mA

1. Enter Programming mode.

Method	Action	Result		
Push Button ⁴	Press and hold the TEACH button	Output LED: On red Power LED: On green (good signal) or		
Remote Input ⁵	No action required; the sensor is ready for the first limit	Power LED: On green (good signal) or On red (no signal)		

- 2. Position the target for the center of the window. The Power LED must be On green.
- 3. Teach the limit.

Method	Action		Result
Push Button	Press the TEACH button one time.	ţ.	Teach Accepted Output LED: Flashing Red
Remote Input	Single-pulse the remote line.		Teach Not Accepted Output LED: ON Red

4. Teach the limit a second time.

Method	Action		Result
Push Button	Without moving the target, press the TEACH button one time.	ţ •	Teach Accepted Output LED: Yellow or OFF
Remote Input	Without moving the target, single-pulse the remote line.		Teach Not Accepted Output LED: Flashing Red

Lock the Buttons

Enable or disable the buttons to prevent unauthorized adjustment of the program settings.

_____T ___ T ___ T ___ T ___ T ___

To lock or unlock the buttons, four-pulse	Ţ	Ţ	ŢĹ	the remote line. The buttons are enabled or disabled, depending	
on the previous condition.				the remote line. The buttons are chabled of disabled, depending	

Installation

Principles of Operation

Ultrasonic sensors emit one or multiple pulses of ultrasonic energy, which travel through the air at the speed of sound. A portion of this energy reflects off the target and travels back to the sensor. The sensor measures the total time required for the energy to reach the target and return to the sensor. The distance to the object is then calculated using the following formula: $D = ct \div 2$

D = distance from the sensor to the target

 \mathbf{c} = speed of sound in air

 \mathbf{t} = transit time for the ultrasonic pulse

To improve accuracy, an ultrasonic sensor may average the results of several pulses before outputting a new value.

Temperature Effects

The speed of sound is dependent upon the composition, pressure and temperature of the gas in which it is traveling. For most ultrasonic applications, the composition and pressure of the gas are relatively fixed, while the temperature may fluctuate. In air, the speed of sound varies with temperature according to the following approximation:

4 0.04 s < "click" < 0.8 s

5 0.04 s < T < 0.8 s

In metric units: $C_{m/s} = 20 \sqrt{273 + T_{C}}$

In English units:

 $C_{m/s}$ = speed of sound in meters per second

T_C = temperature in °C

 $C_{ft/s}$ = speed of sound in feet per second T_F = temperature in °F

 $C_{ff/s} = 49 \sqrt{460 + T_F}$

Temperature Compensation

Changes in air temperature affect the speed of sound, which in turn affects the distance reading measured by the sensor. An increase in air temperature shifts both sensing window limits closer to the sensor. Conversely, a decrease in air temperature shifts both limits farther away from the sensor. This shift is approximately 3.5% of the limit distance for a 20° C change in temperature.

The S18U series ultrasonic sensors are temperature compensated. This reduces the error due to temperature by about 90%. The sensor will maintain its window limits to within 1.8% over the -20° to +60° C (-4° to +140° F) range.

Note:

- Exposure to direct sunlight can affect the sensor's ability to accurately compensate for changes in temperature.
- If the sensor is measuring across a temperature gradient, the compensation will be less effective.
- The temperature warmup drift upon power-up is less than 1.7% of the sensing distance. After 10
 minutes, the apparent distance will be within 0.3% of the actual position. After 25 minutes, the sensing
 position will be stable.

Wiring Diagrams





Note: It is recommended that the shield wire be connected to earth ground or DC common.

Specifications

Sensing Range

30 to 300 mm (1.2 in to 11.8 in)

Supply Voltage

10 V DC to 30 V DC (10% maximum ripple); 20 mA max. (exclusive of load), 40 mA typical @ 25V input

Ultrasonic Frequency

300 kHz, rep. rate 2.5 ms

Supply Protection Circuitry

Protected against reverse polarity and transient voltages

Output Configuration

Analog Output: 0 to 10 V DC or 4 to 20 mA, depending on model

Output Protection

Protected against short circuit conditions

Delay at Power-Up

300 milliseconds

Temperature Effect

0.02% of distance/ °C

Connections

2 m (6.5 ft) or 9 m (30 ft) shielded 5-conductor (with drain) PVC jacketed attached cable or 5-pin Euro-style quick-disconnect

Remote TEACH Input Impedance: 12 kΩ

Construction

Threaded Barrel: Thermoplastic polyester Push Button: Santoprene Push Button Housing: ABS/PC Lightbipes: Acrvlic

Minimum Window Size

5 mm

Adjustments

Sensing window limits: TEACH-Mode programming of near and far window limits may be set using the push button or remotely via TEACH input

Indicators

Range Indicator (Red/Green) Green—Target is within sensing range Red—Target is outside sensing range OFF—Sensing power is OFF

Teach/Output Indicator (Amber/Red)

Yellow—Target is within taught limits OFF—Target is outside taught window limits Red—Sensor is in TEACH mode

Figure 5. QD Models

Linearity⁶

2.5 ms response: ±1 mm 30 ms response: ± 0.5 mm

Resolution 6

2.5 ms response: 1 mm 30 ms response: 0.5 mm

Output Response Time (for a 95% step change)

2.5 milliseconds: Black wire at 5 to 30 V DC
 30 milliseconds: Black wire at 0 to 2 V DC (or open)
 Contact Banner Engineering for other response speed options

Operating Conditions

Temperature: -20 °C to +60 °C (-4 °F to +140 °F)

Temperature Warmup Drift

Less than 1.7% of sensing distance upon power-up (see Temperature Compensation)

Environmental Rating

Leakproof design is rated IEC IP67; NEMA 6P

Vibration and Mechanical Shock

All models meet MIL-STD-202F, Method 201A (Vibration: 10 Hz to 60 Hz maximum, 0.06 inch (1.52 mm) double amplitude, 10G maximum acceleration) requirements. Also meets IEC 60947-5-2 (Shock: 30G 11 ms duration, half sine wave) requirements.

Application Notes

Objects passing inside the specified near limit may produce a false response.

Certifications



Output Ratings

Analog Voltage Output:

2.5 kΩ minimum load resistance Minimum supply for a full 10V output is 12V DC (for supply voltages between 10 and 12, V out max is at least V supply -2)
Analog Current Output: 1 kΩ max @ 24V input

Max load resistance = (Vcc-4)/0.02 ohms

For current output (4-20 mÅ) models, ideal results are achieved when the total load resistance R = [(Vin – 3)/0.020] Ω . Example, at Vin = 24 V DC, R \approx 1 k Ω (1 watt). A worst-case shift of 1% of sensing distance is caused by operating the sensor at Vin = 30 V DC and R = 0 Ω .

Required Overcurrent Protection



WARNING: Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table. Overcurrent protection may be provided with external fusing or via Current

Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced. For additional product support, go to www.bannerengineering.com.

 Supply Wiring (AWG)
 Required Overcurrent Protection (Amps)

 20
 5.0

 22
 3.0

 24
 2.0

 26
 1.0

 28
 0.8

 30
 0.5

Dimensions





[🧯] Linearity and resolution are specified using a 50 mm x 50 mm (2" x 2") aluminum plate at 22°C under fixed sensing conditions

Right-Angle Housing



Response Curves



Figure 6. Effective Beam Pattern (Typical)

Figure 7. Maximum Target Rotation Angle



Accessories

Quick-Disconnect Cables

5-Pin Threaded M12/Euro-Style Cordsets with Shield-Single Ended							
Model	Length	Style	Dimensions	Pinout (Female)			
MQDEC2-506	2 m (6.56 ft)						
MQDEC2-515	5 m (16.4 ft)		 44 Typ 	1 1000			
MQDEC2-530	9 m (29.5 ft)	Straight		4			
MQDEC2-550	15 m (49.2 ft)	- a gri	M12 x 1	1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray			

5-Pin Threaded M12/Euro-Style Cordsets with Shield—Single Ended						
Model	Length	Style	Dimensions	Pinout (Female)		
MQDEC2-506RA	2 m (6.56 ft)		, 32 Тур.			
MQDEC2-515RA	5 m (16.4 ft)		[1.26"]			
MQDEC2-530RA	9 m (29.5 ft)					
MQDEC2-550RA	15 m (49.2 ft)	Right-Angle	30 Typ. [1.18"] μ μ μ μ μ μ μ σ 14.5 [0.57"] ↓ − ↓			

Brackets

SMB18A

- Right-angle mounting bracket with a curved slot for versatile orientation
- 12-ga. stainless steel
- 18 mm sensor mounting hole
- Clearance for M4 (#8)
 hardware

Hole center spacing: A to B = 24.2 Hole size: A = Ø 4.6, B = 17.0 × 4.6, C = Ø 18.5

SMB18UR

- 2-piece universal swivel
 bracket
- 300 series stainless steel Stainless steel swivel
- locking hardware included
- Mounting hole for 18 mm sensor



SMB18SF

- 18 mm swivel bracket with
- M18 \times 1 internal thread
- Black thermoplastic polyester
 Stainless steel swivel locking hardware included



Hole center spacing: A = 36.0Hole size: $A = \emptyset 5.3$, $B = \emptyset 18.0$

Hole center spacing: A = 25.4, B = 46.7Hole size: $B = 6.9 \times 32.0$, C = ø 18.3



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