



RoHS

# MS8607-02BA01

PHT Combination Sensor

### **SPECIFICATIONS**

- Integrated pressure, humidity and temperature sensor
- QFN package 5 x 3 x 1 mm<sup>3</sup>
- Operating range: 10 to 2000 mbar, 0%RH to 100%RH, -40 to 85 ℃
- High-resolution module: 0.016 mbar, 0.04%RH, 0.01℃
- Supply voltage: 1.5 to 3.6 V
- Fully factory calibrated sensor
- I<sup>2</sup>C interface

The MS8607 is the novel digital combination sensor of MEAS providing 3 environmental physical measurements all-in-one: pressure, humidity and temperature (PHT). This product is optimal for applications in which key requirements such as ultralow power consumption, high PHT accuracy and compactness are critical. High pressure resolution combined with high PHT linearity makes the MS8607 an ideal candidate for environmental monitoring and altimeter in smart phones and tablet PC, as well as PHT applications such as HVAC and weather stations. This new sensor module generation is based on leading MEMS technologies and latest benefits from Measurement Specialties proven experience and know-how in high volume manufacturing of sensor modules, which has been widely used for over a decade.

# FEATURES

### FIELD OF APPLICATION

- Smart phones and Tablet PCs
- HVAC applications
- Weather station
- Printers
- Home Appliance and humidifiers

### **TECHNICAL DATA**

Sensor Performances (V <sub>DD</sub> = 3 V)											
Characteristics	F	Pressure [mbar]			tive Humidity	[%RH]	Temperature [°C]				
	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max		
Max. Operating Range	10		2000	0		100	-40		+85		
		3001100mb	ar		2080%RH			@ 25℃			
Absolute Accuracy @25℃	-2		2	-3		3	-1		1		
Resolution (highest mode)		0.016			0.04			0.01			

# PERFORMANCE SPECIFICATIONS

### **ABSOLUTE MAXIMUM RATINGS**

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply voltage	Vdd		-0.3		3.6	V
Storage temperature	Ts		-20		85	C
Overpressure	Pmax			6		bar
Maximum Soldering Temperature	T <sub>max</sub>	40 sec max			250	ĉ
ESD rating		Human Body Model	-2		2	kV
Latch up		JEDEC standard No 78	-100		100	mA

### **ELECTRICAL CHARACTERISTICS**

Parameter		General	electrical ch	aracteristics		
	Symbol	Condition	Min.	Тур.	Max.	Unit
Operating Supply voltage	Vdd		1.5	3.0	3.6	V
Operating Temperature	Т		-40	+25	+85	C
VDD to GND Capacitor			220	470		nF
Supply current P or T (1 Pressure or temperature conversion per sec.)	Ірт	OSR 8192 4096 2048 1024 512 256		20.09 10.05 5.02 2.51 1.26 0.63		μΑ
Supply current H (1 humidity conversion per sec.)	Ін	OSR 8192 4096 2048 1024		6.22 3.11 1.56 0.78		μΑ
Peak supply current (during P or T conversion)				1.25		mA
Peak supply current (during humidity conversion)				0.45		mA
Standby supply current		@ 25℃, V <sub>DD</sub> = 3V		0.03	0.24	μA

	Press	ure and	temperatu	ire		Relative hu	midity	
	Condition	Min.	Тур.	Max.	Min.	Тур.	Max.	Unit
ADC Output Word			24			16		bit
	OSR 8192		16.44	17.2		13.82	15.89	
	4096		8.22	8.61		6.98	8.03	
ADC Conversion time <sup>(3)</sup>	2048		4.13	4.32		3.55	4.08	ms
	1024		2.08	2.17		1.84	2.12	
	512		1.06	1.10		-	-	
	256		0.54	0.56		-	-	
Heater: power dissipation and temperature increase over humidity sensor		·				2 - 13 0.5 - 1.5		mW ℃
Low battery indicator accuracy				±50 (Ty	/p.)	·		mV

(3): Maximum values must be applied to determine waiting times in I<sup>2</sup>C communication

# PERFORMANCE SPECIFICATIONS (CONTINUED)

### PHT CHARACTERISTICS ( $V_{DD}$ = 3.0 V, T = 25 °C UNLESS OTHERWISE NOTED )

		I	Pressure [mba	r]	Relativ	e Humidity	/ [%RH]	т	emperature [°C]	
		Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.
Operating R Extended Ra	ange ange <sup>(4)</sup>	300 10		1200 2000	0		100	-40		85
Absolute Ac	curacy	;	3001100 mba	ar	2	2080%RI	-		@25℃	
@25℃		-2		2	-3		3	-1		1
Abaaluta Aa		300	.1100mbar, -20	85℃		595%RH			-2085℃	
Absolute Ac	curacy	-4		4	-5		5	-2		2
Relative Acc	uracy	7	001000 mbai	(5)						
@25℃	-		±0.1 <sup>(6)</sup>		1					
Resolution RMS <sup>(7)</sup> Maximum er supply volta			0.016 0.021 0.028 0.039 0.062 0.11 ±0.5			0.04 - - 0.7 ±0.25			0.002 0.003 0.004 0.006 0.009 0.012 ±0.3	
(Condition)	90				(Vdi	o=1.5 V	3.6 V)			
Long-term s	tability		±1 / year			±0.5 / year			±0.3 / year	
Reflow solde	ering impact		-0.6			2				
Recovering reflow <sup>(8)</sup>	time after		5 days			5 days				
Response Time			< 5ms			5 sec.				
(Condition)					From 3	6 of signal re 33%RH to 7 t 3m/s air flo	5%RH,			

(4): Linear range of ADC

(5): Auto-zero at one pressure point

(6): Characterized value performed on qualification devices

(7): Characterization performed sequentially (P&T conversion followed by H conversion)

(8): Recovering time at least 66% of the reflow impact

#### **DIGITAL INPUTS (SDA, SCL)**

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Serial data clock	SCL				400	kHz
Input high voltage	VIH		80% V <sub>DD</sub>		100% V <sub>DD</sub>	V
Input low voltage	VIL		0% V <sub>DD</sub>		20% V <sub>DD</sub>	V

#### DIGITAL OUTPUTS (SDA)

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Output high voltage	Vон	I <sub>source</sub> = 1 mA	80% Vdd		100% V <sub>DD</sub>	V
Output low voltage	Vol	I <sub>sink</sub> = 1 mA	0% V <sub>DD</sub>		20% V <sub>DD</sub>	V
Load Capacitance	CLOAD			16		pF

### PERFORMANCE CHARACTERISTICS

#### PHT ACCURACY AND PHT ERROR VERSUS SUPPLY VOLTAGE (TYPICAL)







### FUNCTIONAL DESCRIPTION

#### GENERAL

The MS8607 includes two sensors with distinctive MEMS technologies to measure pressure, humidity and temperature. The first sensor is a piezo-resistive sensor providing pressure and temperature. The second sensor is a capacitive type humidity sensor providing relative humidity. Each sensor is interfaced to a  $\Delta\Sigma$  ADC integrated circuit for the digital conversion. The MS8607 converts both analog output voltages to a 24-bit digital value for the pressure and temperature measurements, and a 12-bit digital value for the relative humidity measurement.

#### SERIAL I<sup>2</sup>C INTERFACE

The external microcontroller clocks in the data through the input SCL (Serial CLock) and SDA (Serial DAta). Both sensors respond on the same pin SDA which is bidirectional for the I<sup>2</sup>C bus interface. Two distinct I<sup>2</sup>C addresses are used (one for pressure and temperature, the other for relative humidity, see Figure 2).

Module reference	Mode	Pins used
MS860702BA01	I <sup>2</sup> C	SDA, SCL

Sensor type	I <sup>2</sup> C address (binary value)	I <sup>2</sup> C address (hex. value)
Pressure and Temperature P&T	1110110	0x76
Relative Humidity RH	1000000	0x40

Figure 2: I<sup>2</sup>C addresses

#### COMMANDS FOR PRESSURE AND TEMPERATURE

For pressure and temperature sensing, five commands are possible:

- 1. Reset
- 2. Read PROM P&T (112 bit of calibration words)
- 3. D1 conversion
- 4. D2 conversion
- 5. Read ADC (24 bit pressure / temperature)

Each command is represented over 1 byte (8 bits) as described in Figure 3. After ADC read commands, the device will return 24 bit result and after the PROM read 16 bit results. The address of the PROM is embedded inside of the read PROM P&T command using the a2, a1 and a0 bits.

	Comma	and byte							hex value
Bit number	7	6	5	4	3	2	1	0	
Bit name	PROM	CONV	-	Тур	Ad2/ Os2	Ad1/ Os1	Ad0/ Os0	Stop	
Command									
Reset	0	0	0	1	1	1	1	0	0x1E
Convert D1 (OSR=256)	0	1	0	0	0	0	0	0	0x40
Convert D1 (OSR=512)	0	1	0	0	0	0	1	0	0x42
Convert D1 (OSR=1024)	0	1	0	0	0	1	0	0	0x44
Convert D1 (OSR=2048)	0	1	0	0	0	1	1	0	0x46
Convert D1 (OSR=4096)	0	1	0	0	1	0	0	0	0x48
Convert D1 (OSR=8192)	0	1	0	0	1	0	1	0	0x4A
Convert D2 (OSR=256)	0	1	0	1	0	0	0	0	0x50
Convert D2 (OSR=512)	0	1	0	1	0	0	1	0	0x52
Convert D2 (OSR=1024)	0	1	0	1	0	1	0	0	0x54
Convert D2 (OSR=2048)	0	1	0	1	0	1	1	0	0x56
Convert D2 (OSR=4096)	0	1	0	1	1	0	0	0	0x58
Convert D2 (OSR=8192)	0	1	0	1	1	0	1	0	0x5A
ADC Read	0	0	0	0	0	0	0	0	0x00
PROM Read P&T	1	0	1	0	Ad2	Ad1	Ad0	0	0xA0 to 0xAE

Figure 3: Command structure for pressure and temperature sensing

#### COMMANDS FOR RELATIVE HUMIDITY

For relative humidity sensing, six commands are possible:

- 1. Reset
- 2. Write user register
- 3. Read user register
- 4. Measure RH (Hold master)
- 5. Measure RH (No Hold master)
- 6. PROM read RH

Each I2C communication message starts with the start condition and it is ended with the stop condition. The I<sup>2</sup>C address for humidity sensing is 1000000. The address of the PROM is embedded inside of the PROM read command using the a2, a1 and a0 bits. Figure 4 shows the commands with their respective code:

	8 bi	ts Co	mman	d					hex value
Bit number	7	6	5	4	3	2	1	0	
Command :									
1. Reset	1	1	1	1	1	1	1	0	0xFE
2. Write user register	1	1	1	0	0	1	1	0	0xE6
3. Read user register	1	1	1	0	0	1	1	1	0xE7
4. Measure RH (Hold master)	1	1	1	0	0	1	0	1	0xE5
5. Measure RH (No Hold master)	1	1	1	1	0	1	0	1	0xF5
6. PROM read RH	1	0	1	0	adr2	adr1	adr0	0	0xA0 to 0xAE

Figure 4: command structure for relative humidity sensing

### USER REGISTER

The user register is used to configure several operating modes of the humidity sensor (resolution measurements, heater) and monitor the battery state. The possible configurations of the user register are described in the table below.

User register Bit	Bit Confi	guration/Cod	ing		Default value
bit 7, bit 0	Measure	ment resolution	on		'00'
	Bit 7	Bit 0	OSR	Resolution	
	0	0	4096	Highest	
	0	1	2048		
	1	0	1024		
	1	1	256	Lowest	
bit 6	Battery s				'0'
	'0' VDD>	2.25V			
	'1' VDD<	2.25V			
bit 3,4,5	Reserved	k			·000'
bit 2	on-chip h	eater:			
	'0' heater	disabled			'0'
	'1' heater	enabled			
bit 1	Reserved	k			·0'

Figure 5: description of the user register

- Bit 7 and bit 0 configure the measurement resolution (highest resolution OSR 4096, lowest OSR 256).
- Bit 6 refers to the "Battery state", which can be monitored.
- Bits 1,3,4,5 are reserved bits, which must not be changed and default values of respective reserved bits may change over time without prior notice. Therefore, for any writing to user register, default values of reserved bits must be read first.
- Bit 2 configures the heater. It can be used for functionality diagnosis: relative humidity drops upon rising temperature. The heater consumes about 5.5mW and provides a temperature increase of approximatively 0.5-1.5℃ over the humidity sensor.

### PRESSURE AND TEMPERATURE CALCULATION



	Read calibration data (factory calibrated) from PROM													
Variable	Description   Equation	Recommended	Size [1]	Va	lue	Example /								
Vallable		variable type	[bit]	min	max	Typical								
C1	Pressure sensitivity   SENS T1	unsigned int 16	16	0	65535	46372								
C2	Pressure offset   OFF T1	unsigned int 16	16	0	65535	43981								
C3	Temperature coefficient of pressure sensitivity   TCS	unsigned int 16	16	0	65535	29059								
C4	Temperature coefficient of pressure offset   TCO	unsigned int 16	16	0	65535	27842								
C5	Reference temperature   T REF	unsigned int 16	16	0	65535	31553								
C6	Temperature coefficient of the temperature   TEMPSENS	unsigned int 16	16	0	65535	28165								

	Rea	d digital pressure and temper	ature d	ata		
D1	Digital pressure value	unsigned int 32	24	0	16777215	6465444
D2	Digital temperature value	unsigned int 32	24	0	16777215	8077636

	Calcu	ilate temperature	)			
dT	Difference between actual and reference temperature $^{[2]}$ $dT = D2 - T_{REF} = D2 - C5 * 2^8$	signed int 32	25	-16776960	16777215	68
TEMP	Actual temperature (-4085°C with 0.01°C resolution) $TEMP = 20°C + dT *TEMPSENS = 2000 + dT * C6 / 2^{23}$	signed int 32	41	-4000	8500	2000 = 20.00 ℃

	Calculate tempera	ture compensate	ed pres	sure		
OFF	Offset at actual temperature <sup>[3]</sup> $OFF = OFF_{T1} + TCO^* dT = C2^* 2^{17} + (C4^* dT)/2^6$	signed int 64	41	-17179344900	25769410560	5764707214
SENS	Sensitivity at actual temperature <sup>[4]</sup> SENS = SENS <sub>T1</sub> + TCS * dT = C1 * 2 <sup>16</sup> + (C3 * dT)/2 <sup>7</sup>	signed int 64	41	-8589672450	12884705280	3039050829
Ρ	Temperature compensated pressure (101200mbar with 0.01mbar resolution) $P = D1 * SENS - OFF = (D1 * SENS / 2^{21} - OFF) / 2^{15}$	signed int 32	58	1000	120000	110002 = 1100.02 mbar

Pressure and temperature value first order

Notes Maximal size of intermediate result during evaluation of variable min and max have to be defined [1] [2] [3] [4]

min and max have to be defined

min and max have to be defined

Figure 6: Flow chart for pressure and temperature reading and software compensation.

#### PRESSURE COMPENSATION (SECOND ORDER OVER TEMPERATURE)

In order to optimize the accuracy over temperature range at low temperature, it is recommended to compensate the pressure non-linearity over the temperature. This can be achieved by correcting the calculated temperature, offset and sensitivity by a second-order correction factor. The second-order factors are calculated as follows:



Figure 7: Flow chart for pressure and temperature to the optimum accuracy.

### **RELATIVE HUMIDITY CALCULATION**



Notes [1]

Maximal size of intermediate result during evaluation of variable

#### Figure 8: Flow chart for humidity reading.

To accommodate any process variation (nominal capacitance value of the humidity sensor), tolerances of the sensor above 100%RH and below 0%RH must be considered. As a consequence:

- 118%RH corresponds to 0xFF which is the maximum RH digital output that can be sent out from the ASIC. RH output can reach 118%RH and above this value, there will have a clamp of the RH output to this value.
- -6%RH corresponds to 0x00 which is the minimum RH digital output that can be sent out from the ASIC. RH output can reach -6%RH and below this value, there will have a clamp of the RH output to this value.

The relative humidity is obtained by the following formula (result in %RH):

$$RH = \left(-6 + 125 \cdot \frac{D3}{2^{16}}\right)$$

As example, the transferred 16-bit relative humidity data 0x7C80: 31872 corresponds to a relative humidity of 54.8%RH.

Finally, 1st order temperature compensation is computed for optimal accuracy over [0...+85°C] temperature range. The final compensated relative humidity value RH<sub>compensated</sub> is calculated as:

$$RH_{compensated} = RH + (20 - TEMP) \cdot T_{coeff}$$

TEMP	Temperature calculated on p.9	unit [℃]
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unit [%RH / ℃]

Temperature correction coefficient Optimal relative humidity accuracy over  $[0...+85^{\circ}]$  t emperature range is obtained with  $T_{coeff}$  = -0.18

Tcoeff

### **APPLICATION CIRCUIT**

The MS8607 is a circuit that can be used in conjunction with a microcontroller by I2C protocol interface. It is designed for low-voltage systems with a supply voltage of 3 V and can be used in industrial pressure / humidity / temperature applications.

### I<sup>2</sup>C protocol communication



Figure 9: Typical application circuit

# I<sup>2</sup>C INTERFACE: PRESSURE AND TEMPERATURE

#### COMMANDS

Each I<sup>2</sup>C communication message starts with the start condition and it is ended with the stop condition. The I<sup>2</sup>C address for pressure and temperature sensing is 1110110. The description of the commands related to pressure and temperature sensing is detailed on p. 5.

#### **RESET SEQUENCE**

The Reset sequence shall be sent once after power-on to make sure that the calibration PROM gets loaded into the internal register. It can be also used to reset the device PROM from an unknown condition.

The reset can be sent at any time. In the event that there is not a successful power on reset this may be caused by the SDA being blocked by the module in the acknowledge state. The only way to get the ASIC to function is to send several SCLs followed by a reset sequence or to repeat power on reset.





#### PROM READ P&T SEQUENCE

The read command for PROM shall be executed once after reset by the user to read the content of the calibration PROM and to calculate the calibration coefficients. There are in total 7 addresses resulting in a total memory of 112 bit. The addresses contain factory data and the setup, calibration coefficients, the serial code and CRC (see details on p. 15, Figure 22). The command sequence is 8 bits long with a 16 bit result which is clocked with the MSB first. The PROM Read command consists of two parts. First command sets up the system into PROM read mode (Figure 11). The second part gets the data from the system (Figure 12).

	1					1 ess		0	0	1	0			0 nar		1	0	0						
S		De	evic	e A	ddr	ess		W	Α			С	md	byt	e			Α	Ρ	)				
	Fro Fro	om om	Mas Slav	ster ve			S = P =									W R =		Nrit .eac			A = N =			je

Figure 11: I<sup>2</sup>C Command to read P&T memory PROM address 0xA6

1 1 1 0 1 1 Device Address		XXXX ata	X X X X X X X X X data	0
S Device Address	R A Memory	bit 15 - 8 A	Memory bit 7 - 0	ΝP
From Master From Slave	S = Start Condition P = Stop Condition	W = Write R = Read		lage



#### **CONVERSION SEQUENCE**

The conversion command is used to initiate uncompensated pressure (D1) or uncompensated temperature (D2) conversion. After the conversion, using ADC read command the result is clocked out with the MSB first. If the conversion is not executed before the ADC read command, or the ADC read command is repeated, it will give 0 as the output result. If the ADC read command is sent during conversion the result will be 0, the conversion will not stop and the final result will be wrong. Conversion sequence sent during the already started conversion process will yield incorrect result as well. A conversion can be started by sending the command to the ASIC. When the command is sent to the system it stays busy until conversion is done. When conversion is finished, the data can be accessed by sending a Read command. When the Acknowledge bit is sent from the ASIC, 24 SCL cycles may be sent to receive all result bits. Every 8 bits the system waits for the Acknowledge bit.

	1	1	1	0	1	1	0	0	0	0	1	0	0	1	0	0	0	0									
		De	vic	e A	ddr	ess						C	omr	nar	nd					_							
S		De	vice	e A	ddr	ess		W	Α			C	md	byt	e			Α	Ρ								
Г	Fro	-m	Mag	ter			S =	St	art	Cor	ndit	ion				w	= V	Nrit	ē	_	Δ	=	Ack	no	wle	dqe	
	Fro						P =									R =										owle	e

Figure 13: I<sup>2</sup>C command to initiate a pressure conversion (OSR=4096, typ=D1)

	1					1 ess		0	0	0	0			0 nar		0	0	0							
S		De	evic	e A	ddr	ess		W	А			C	md	byt	e			Α	Ρ	]					
	Fro Fro	om om	Ma: Slav	ster ve			S = P =									W R=	-				4 = N =			ge	

Figure 14: I<sup>2</sup>C ADC read sequence

	1	1	1	0	1	1	0	1	0	Х	Х	Х	Х	Х	Х	Х	Х	0	Х	Х	Х	Х	Х	Х	Х	Х	0	Х	Х	Х	Х	Х	Х	Х	Х	0	
		Dev	ice	e Ao	ddro	ess	;																														
S		Dev	ice	e Ao	ddro	ess	;	R	А			Dat	ia 2	3 -	16			А			Da	ata	15	- 8			А			D	ata	7 -	0			Ν	Р
	<b>-</b>						~	~		~			_				,																				
		om I			ſ		-	-	tar									Vrit							led	0											
	Fro	m \$	Sla	ve			<b>P</b> :	= S	top	Cc	ndi	tio	٦			R :	= R	ead	b		N :	= N	ot i	Ack	no	wle	dge	•									

Figure 15: I<sup>2</sup>C answer from the ASIC

### I<sup>2</sup>C INTERFACE: RELATIVE HUMIDITY

#### COMMANDS

Each I2C communication message starts with the start condition and it is ended with the stop condition. The I2C address for humidity sensing is 1000000. The description of the commands related to humidity sensing is detailed on p. 6.

#### **RESET SEQUENCE**

This command is used for rebooting the humidity sensor by switching the power off and on again. Upon reception of this command, the humidity sensor system reinitializes and starts operation according to the default settings with the exception of the heater bit in the user register. The reset takes less than 15ms.

100000	0 0 0 1 1	1 1 1 1 1 0 0	
Device Address	s	command	
S Device Address	s W A	cmd byte A	ס
From Master From Slave	S = Start Condi P = Stop Condi		A = Acknowledge N = Not Acknowledge

Figure 16: I<sup>2</sup>C Reset Command

#### READ AND WRITE USER REGISTER SEQUENCE

The following sequence illustrates how to read and write the user register. First, it reads the content of the user register. Then it writes the user register for configuring the humidity sensor to 8 bits measurement resolution from the default configuration.

	1	0	0	0 e A	0	0	0	0	0	1	1	1	0	0	1	1	1	0										
_				• • •										mar														
S		De	vic	e A	ddr	ess		W	А			С	md	by	te			А										
	1	0	0	0	0	0	0	1	0	X	X	Х	X	X	X	X	X	0										
	•	0	0	0	•	0	0	•	U	~	~	~	~	~	~	~	~	U										
		De	NC	e A	ddr	ess																						
S		De	vic	e A	ddr	ess		R	Α	Us	er	Reg	gist	er [	Data	a 7	- 0	Ν										
-													,	_														
	1	0	0	0	0	0	0	0	0	1	1	1	0	0	1	1	0	0	0	0	0	0	0	0	0	1	0	
			vic	e A	ddr	000	-	-				~	- 	mar	ha		-		-	-	-	-	-	-	-			
_				• • •																								
S		De	vic	e A	ddr	ess		W	Α			С	md	by	te			Α	Us	er I	Reg	gist	er [	Data	a 7	- 0	A	P
-																												
	From Master S =							= S	tar	C	ond	itio	n			w	= \	N rit	e		A :	= A	cki	าดพ	led	ae		
	From Master S = From Slave P =						= S	top	Co	ond	itio	n			R	= R	ead	ł					Ack		0	dge	)	



#### MEASURE RH HOLD/NO HOLD SEQUENCE

MS8607 has two different operation modes to measure relative humidity (RH): Hold Master mode and No Hold Master mode.

No Hold Master mode allows for processing other I<sup>2</sup>C communication tasks on a bus while the humidity sensor is measuring. Figure 18 and 19 illustrate the communication sequence of both modes. In the Hold Master mode, the humidity sensor pulls down the SCK line while measuring to force the master into a wait state. By releasing the SCK line, the humidity sensor indicates that internal processing is completed and that transmission may be continued.

In the No Hold Master mode, the MCU has to poll for the termination of the internal processing of the humidity sensor. This is done by sending a start condition followed by the I<sup>2</sup>C header (0x81) as shown below. If the internal processing is finished, the humidity sensor acknowledges the poll of the MCU and data can be read by the MCU. If the measurement processing is not finished, the humidity sensor answers the Not Acknowledge bit and start condition must be issued once more.

For both modes, the measurement is stored into 14 bits. The two remaining least significant bits (LSBs) are used for transmitting status information. Bit1 of the two LSBs must be set to '1'. Bit0 is currently not assigned.

1       0       0       0       0       0       1       1       1       0       1	0
1 0 0 0 0 0 1 0 Device Address Hold during measurement	X X X X X X X X 0 X X X X X X 1 0 0 Data 15 - 8 A Data 7 - 2 Status A
1     0     1     0     1     1     1     0       From Master     From Slave       Checksum     N     P     On hold	S = Start Condition W = Write A = Acknowledge P = Stop Condition R = Read N = Not Acknowledge
Figure 18: I <sup>2</sup> C Measure RH Hole	d Master communication sequence

1	0	0	0	0 0	0	0	0	0	1	1	1	1	0	1	0	1	0																			
	Dev	ice	Ad	dres	ss						СС	omi	mar	nd																						
S	Dev	ice	Ad	dres	SS		W	А			CI	md	by	te			А																			
1	0	0	0	0 (	0	0	1	0	Х	Х	Х	Х	Х	Х	Х	Х	0	Х	Х	Х	Х	Х	Х	1	0	0	1	0	0	1	0	1	1	1	0	
	Dev	ice	Ad	dres	ss																															
S	Device Address         R         A         Data 15 - 8         A         Data 7 - 2         Status A         Checksum         N         P																																			
	rom N																		now		0															

From Slave P = Stop Condition R = Read N = Not Acknowledge

Figure 19: I<sup>2</sup>C Measure RH No Hold Master communication sequence

For Hold Master sequence, the Acknowledge bit that follows the Status bit may be changed to Not Acknowledge bit followed by a stop condition to omit checksum transmission.

For No Hold Master sequence, if measurement is not completed upon "read" command, sensor does not provide ACK on bit 27 (more of these iterations are possible). If bit 45 is changed to NACK followed by stop condition, checksum transmission is omitted.

Regarding the calculation of the relative humidity value, the Status bits must be set to '0'. Refer to "Conversion of signal outputs" section p. 10. The maximum duration for measurement depends on the type of measurement and resolution chosen. Maximum values shall be chosen for the communication planning of the MCU.

I<sup>2</sup>C communication allows for repeated start conditions without closing prior sequence with stop condition.

	Bit															
PROM READ RH	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	SEQUENCE

The RH PROM memory contains 7 addresses resulting in a total memory of 112 bit. The addresses contain factory defined data and CRC (see details on p. 17, Figure 23). The command sequence is 8 bits long with a 16 bit result which is clocked with the MSB first. The RH PROM Read command consists of two parts. First command sets up the system into PROM read mode (Figure 20). The second part gets the data from the system (Figure 21).

1 1 1 0 1 1 0	0 0	1 0 1 0 0 1	1 0 0	
Device Address		command		
S Device Address	WA	cmd byte	A P	
		t Condition Condition	W = Write R = Read	A = Acknowledge N = Not Acknowledge

Figure 20: I<sup>2</sup>C Command to read memory address 0xA6

	1		1 evic			0	1	0	Х	Х	Х	X ata	Х	Х	Х	0	Х	Х	Х	X ata	Х	Х	Х	0	
S		_	evic	-	 		R	Α		Me	emo	 bit	15	- 8		А		Μ	em	 bit	7 -	0		Ν	Ρ
	Fro Fro	om om	Mas Slav	ster ve		S = P =								W R =	-	Vrit eac	-					lede		lag	e

Figure 21: I<sup>2</sup>C answer from ASIC (Pressure and temperature)

### CYCLIC REDUNDANCY CHECK (CRC)

MS8607 contains two separate PROM memories with identical size (112-Bit): one for pressure and temperature P&T (Figure 22), the other for relative humidity RH (Figure 23). Each PROM memory can be accessed using the I<sup>2</sup>C commands PROM Read P&T and PROM Read RH (p. 6).

Address (Hex.)	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xA0		CF	RC						Fa	ctory	defir	ned				
0xA2								С	:1							
0xA4								С	2							
0xA6								С	3							
0xA8								С	4							
0xAA								С	5							
0xAC								С	6							

Figure 22: P&T Memory PROM mapping for pressure and temperature

Address (Hex.)	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xA0							Fa	ctory	defir	ned						
0xA2							Fa	ctory	defir	ned						
0xA4							Fa	ctory	defir	ned						
0xA6							Fa	ctory	defir	ned						
0xA8							Fa	ctory	defir	ned						
0xAA							Fa	ctory	defir	ned						
0xAC							Fa	ctory	defir	ned				CF	RC	

Figure 23: RH Memory PROM mapping for relative humidity

A 4-bit CRC has been implemented to check the data integrity in both PROM memories. The C code below describes the CRC calculation for P&T Memory PROM and for RH Memory PROM.

#### C CODE EXAMPLE FOR CRC-4 CALCULATION (P&T MEMORY PROM)

```
unsigned char crc4_PT(unsigned int n_prom[])
                                                                      // n prom defined as 8x unsigned int (n prom[8])
int cnt;
                                                                      // simple counter
unsigned int n_rem=0;
                                                                      // crc remainder
unsigned char n_bit;
          n_prom[0]=((n_prom[0]) & 0x0FFF);
                                                                      // CRC byte is replaced by 0
          n_prom[7]=0;
                                                                      // Subsidiary value, set to 0
          for (cnt = 0; cnt < 16; cnt++)
                                                                      // operation is performed on bytes
                                                                      // choose LSB or MSB
                    if (cnt%2==1)
                                        n_rem ^= (unsigned short) ((n_prom[cnt>>1]) & 0x00FF);
                                        n_rem ^= (unsigned short) (n_prom[cnt>>1]>>8);
                    else
                    for (n_bit = 8; n_bit > 0; n_bit--)
                              if (n_rem & (0x8000))
                                                            n_rem = (n_rem << 1) ^ 0x3000;
                              else
                                                            n_{rem} = (n_{rem} << 1);
                              }
                    }
          n_rem= ((n_rem >> 12) & 0x000F);
                                                                      // final 4-bit remainder is CRC code
          return (n_rem ^ 0x00);
}
```

#### C CODE EXAMPLE FOR CRC-4 CALCULATION (RH MEMORY PROM)

```
unsigned char crc4_RH(unsigned int n_prom[])
                                                                      // n_prom defined as 8x unsigned int (n_prom[8])
{
int cnt;
                                                                      // simple counter
unsigned int n_rem=0;
                                                                      // crc remainder
unsigned char n_bit;
          n_prom[6]=((n_prom[6]) & 0xFFF0);
                                                                      // CRC byte is replaced by 0
          n_prom[7]=0;
                                                                      // Subsidiary value, set to 0
          for (cnt = 0; cnt < 16; cnt++)
                                                                      // operation is performed on bytes
                                                                      // choose LSB or MSB
                    if (cnt%2==1)
                                        n_rem ^= (unsigned short) ((n_prom[cnt>>1]) & 0x00FF);
                                        n_rem ^= (unsigned short) (n_prom[cnt>>1]>>8);
                    else
                    for (n_bit = 8; n_bit > 0; n_bit--)
                              if (n_rem & (0x8000))
                                                            n_{rem} = (n_{rem} << 1) ^ 0x3000;
                              else
                                                            n_rem = (n_rem << 1);
                              }
                    }
          n_rem= ((n_rem >> 12) & 0x000F);
                                                                      // final 4-bit remainder is CRC code
          return (n_rem ^ 0x00);
}
```

# **PIN CONFIGURATION**

Pin	Nam	Туре	Function
1	VDD	Р	Positive supply voltage
3	GND	G	Ground
7	SDA	ю	I²C data IO
8	SCL	I	Serial data clock
2,4,5,6	NC		



# DEVICE PACKAGE OUTLINE



### **RECOMMENDED PAD LAYOUT**

Pad layout for bottom side of the MS8607-02BA01 soldered onto printed circuit board.



### SHIPPING PACKAGE



### MOUNTING AND ASSEMBLY CONSIDERATIONS

#### SOLDERING

Please refer to the application note AN808 available on our website for all soldering issues.

#### MOUNTING

The MS8607 can be placed with automatic Pick & Place equipment using vacuum nozzles. It will not be damaged by the vacuum. Due to the low stress assembly the sensor does not show pressure hysteresis effects. It is important to solder all contact pads.

#### CONNECTION TO PCB

The package outline of the module allows the use of a flexible PCB for interconnection. This can be important for applications in watches and other special devices.

#### CLEANING

The MS8607 has been manufactured under cleanroom conditions. It is therefore recommended to assemble the sensor under class 10'000 or better conditions. Should this not be possible, it is recommended to protect the sensor opening during assembly from entering particles and dust. To avoid cleaning of the PCB, solder paste of type "no-clean" shall be used. Cleaning might damage the sensor!

#### ESD PRECAUTIONS

The electrical contact pads are protected against ESD up to 2 kV HBM (human body model). It is therefore essential to ground machines and personnel properly during assembly and handling of the device. The MS8607 is shipped in antistatic transport boxes. Any test adapters or production transport boxes used during the assembly of the sensor shall be of an equivalent antistatic material.

#### DECOUPLING CAPACITOR

Particular care must be taken when connecting the device to the power supply. A minimum 220nF ceramic capacitor must be placed as close as possible to the MS8607 VDD pin. This capacitor will stabilize the power supply during data conversion and thus, provide the highest possible accuracy.

### ORDERING INFORMATION

Part Number / Art. Number	Product	Delivery Form
MS860702BA01-50	PHT Combination Sensor Module 5x3mm	Tape & Reel

#### **NORTH AMERICA**

Measurement Specialties, Inc., a TE Connectivity company Tel: 800-522-6752 Email: customercare.frmt@te.com

#### EUROPE

Measurement Specialties (Europe), Ltd., a TE Connectivity Company Tel: 800-440-5100 Email: <u>customercare.bevx@te.com</u>

#### ASIA

Measurement Specialties (China) Ltd., a TE Connectivity company Tel: 0400-820-6015 Email: <u>customercare.shzn@te.com</u>

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