[AK5720]

AKM

ΑΚ5720 96kHz 24-Bit ΔΣ ADC

1. General Description

The AK5720 is a low voltage 24-bit A/D converter for digital audio systems. The AK5720 includes an Input Gain Amplifier, making it suitable for microphone applications. The analog signal input of the AK5720 is single-ended, eliminating the need for external filters. The AK5720 is housed in a space-saving 16-pin TSSOP package.

2. Features

- 1. Resolution: 24bits
- 2. Recording Functions
 - Gain Amplifier (0dB / +15dB)
 - Digital HPF for DC-offset cancellation (fc=1.0Hz@fs=48kHz)
- 3. ADC Characteristics
 - Single-ended Input
 - Input Level: 1.8Vpp@VA=3.0V (= 0.6 × VA), 3.0Vpp@VA=5.0V (=0.6 × VA)
 - S/(N+D): 94dB
 - DR, S/N: 102dB
- 4. Master Clock: 256fs/384fs/512fs/768fs
- 5. Sampling Frequency: 8kHz~ 96kHz
- 6. Audio Data Format: MSB First, 2's compliment
 - 24-bit MSB justified, I²S and TDM
- 7. Power Supply
 - VA, VD: 2.7 ~ 5.5V (typ. 3V, 5V)
- 8. Power Supply Current: 6.1mA(VA-VD=5.0V,fs=48kHz)
- 9. Operating Temperature: Ta = -40 \sim 105°C
- 10. Package: 16-pin TSSOP



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4. Pin Configurations and Functions

Ordering Guide

AK5720	$-40 \sim +105^{\circ}C$	16-pin TSSOP (0.65mm pitch)
AKD5720	Evaluation Board for A	AK5720

Pin Layout



Functions

No.	Pin Name	I/O	Function	Power Down Status
1	VCOM	0	ADC Common Voltage Output Pin	Pull-down to VSS with NMOS (0.5kΩ)
2	RIN	Ι	Rch Input Pin	Hi-z
3	LIN	Ι	Lch Input Pin	Hi-z
4	VSS	-	Ground Pin	-
5	VA	-	Analog Power Supply Pin	-
6	VD	-	Digital Power Supply Pin	-
7	GSEL	Ι	Input Gain Select Pin "L": 0dB, "H": +15dB	Hi-z
8	REGO	0	Regulator Output Pin	Pull-down to VSS with 500Ω
9	SDTO	0	Audio Serial Data Output Pin	"L" (VSS)
10	LRCK	I/O	Input/Output Channel Clock Pin	Hi-z
11	MCLK	Ι	Master Clock Input Pin	Hi-z
12	BICK	I/O	Audio Serial Data Clock Pin	Hi-z
13	PDN	Ι	Reset & Power Down Pin "L": Reset & Power down, "H": Normal operation	Hi-z
14	DIF/TDMI	Ι	Audio Data Format Select Pin "L": MSB justified, "H": I ² S	Hi-z
		TDM Data Input Pin		Hi-z
15	FSEL	Ι	Digital Filter select Pin "L": Sharp Roll-Off, "H": Short Delay Sharp Roll-Off	Hi-z
16	CKS	Ι	Mode Select Pin Parasitic capacitance of the pin should be less than 20pF.	Hi-z

Note: All digital input pins must not be allowed to float.

Note: The GSEL pin must be fixed to "H" or "L" when the PDN pin = "H" to avoid starting the test mode.

Handling of Unused Pin

Unused I/O pins must be connected appropriately.

Classification	Pin Name	Setting
Analog	RIN, LIN	This pin should be open.

5. Absolute Maximum Ratings

(VSS=0V; Note 1)					
Parameter	Parameter			max	Unit
Power Supplies:	Analog	VA	-0.3	6.0	V
	Digital	VD	-0.3	6.0	V
Input Current, Any	Input Current, Any Pin Except Supplies		-	±10	mA
Analog Input Volt	age (LIN, RIN pins)	VINA	-0.3	VA+0.3	V
Digital Input Volta	age	VIND	-0.3	VD+0.3	V
Ambient Temperature		Та	-40	105	°C
Storage Temperatu	ıre	Tstg	-65	150	°C

Note 1. All voltages with respect to ground.

WARNING: Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes. The AK5720 will be damaged if a voltage higher than 2.5V is input to the REGO pin.

	6. Recommended Operating Conditions								
(VSS=0V; Note 1)									
Parameter		Symbol	min	typ	max	Unit			
Power Supplies	Analog (VA pin)	VA	2.7	3 or 5	5.5	V			
	Digital (VD pin)	VD	2.7	3 or 5	VA	V			

Note 1. All voltages with respect to ground.

WARNING: AKM assumes no responsibility for the usage beyond the conditions in this datasheet.

7. Analog Characteristics (VA=VD=5.0V)

(Ta=25°C; VA=VD=5.0V; fs=48kHz, 96kHz; BICK=64fs; Signal Frequency=1kHz; 24bit Data; Measurement frequency=20Hz ~ 20kHz at fs=48kHz, 40Hz ~ 40kHz at fs=96kHz; unless otherwise specified)

Parameter			min	typ	max	Unit
ADC Analog I	nput Characteristi	cs:				
Resolution					24	Bits
Input Voltage Gain = 0dB			2.7	3.0	3.3	Van
(Note 2)	Gain = +15dB		0.48	0.53	0.58	Vpp
	VA=5V	fs=48kHz,	84	94		dB
S/(N+D) (-1.0dBFS)	Gain = 0dB	fs=96kHz	-	92		dB
(-1.00DFS)	VA=5V	fs=48kHz	74	84		dB
	Gain = +15 dB	fs=96kHz	-	80		dB
DR	VA=5V	fs=48kHz, A-weighted	94	102		dB
(-60dBFS)	Gain = 0dB	fs=96kHz	-	99		dB
(-000BFS)	VA=5V	fs=48kHz, A-weighted	83	91		dB
	Gain = +15 dB	fs=96kHz	-	86		dB
S/N	VA=5V	fs=48kHz, A-weighted	94	102		dB
	Gain = 0dB	fs=96kHz	-	99		dB
	VA=5V	fs=48kHz, A-weighted	83	91		dB
	Gain = +15dB	fs=96kHz	-	86		dB
	Gain = 0dB	fs=48kHz	29	41		kΩ
Input	Guin – Gui	fs=96kHz	-	28		kΩ
Resistance	Gain = +15dB	fs=48kHz	15	22		kΩ
		fs=96kHz	-	13 110		kΩ dD
Interchannel Iso	olation (RIN, LIN)	Gain = 0dB $Gain = +15dB$	90	90		dB dB
Interchannel Go	ain Mismatch (RIN,			90	0.5	dB
Gain Drift				100	-	ppm/°C
Power Supply F	Rejection	(Note 3)	_	50		dB
Power Supplie	0			00		42
Power Supply C						
·		= "H")				
Normal Operation (PDN pin = "H") VA				3.8	5.7	mA
					3.5	mA
	VD (fs=48kHz) VD (fs=96kHz)				5.3 6.7	mA
	(,		4.4	0.7	IIIA
	wn mode (PDN pin	= "L") (Note 4)		10	100	
VA	A+VD			10	100	μA

Note 2. This value is the full scale (0dB) of the input voltage. Input voltage is proportional to VA voltage. Vin = $0.6 \times VA$ (Vpp).

Note 3. PSR is applied to VA and VD with 1kHz, 50mVpp.

Note 4. All digital input pins and CKS1 pin are held VD or VSS.

8. Analog Characteristics (VA=VD=3.0V)

(Ta=25°C; VA=VD=5.0V; fs=48kHz, 96kHz; BICK=64fs; Signal Frequency=1kHz; 24bit Data; Measurement frequency=20Hz ~ 20kHz at fs=48kHz, 40Hz ~ 40kHz at fs=96kHz; unless otherwise specified)

Parameter		min	typ	max	Unit	
ADC Analog Input	Characteristics:					
Resolution					24	Bits
Input Voltage	Gain = 0dB		1.65	1.8	1.95	V
(Note 2)	Gain = +15dB		0.29	0.32	0.35	Vpp
	VA=3V	fs=48kHz,	84	94		dB
S/(N+D)	Gain = 0dB	fs=96kHz	-	92		dB
(-1.0dBFS)	VA=3V	fs=48kHz	71	81		dB
	Gain = +15 dB	fs=96kHz	-	77		dB
	VA=3V	fs=48kHz, A-weighted	90	98		dB
DR (-60dBFS)	Gain = 0dB	fs=96kHz	-	95		dB
	VA=3V	fs=48kHz, A-weighted	-	86		dB
	Gain = +15 dB	fs=96kHz	-	81		dB
S/N	VA=3V	fs=48kHz, A-weighted	90	98		dB
	Gain = 0dB	fs=96kHz	-	95		dB
	VA=3V	fs=48kHz, A-weighted	-	86		dB
	Gain = +15 dB	fs=96kHz	-	81		dB
	Gain = 0dB	fs=48kHz	29	41		kΩ
Input Resistance		fs=96kHz	-	28		kΩ
1	Gain = +15dB	fs=48kHz	15	22 13		kΩ
		fs=96kHz Gain = 0dB	- 90	13		kΩ dB
Interchannel Isolatio	on	Gain = +15dB	90	90		dB
Interchannel Gain M	lismatch	Gain – +13ab		0	0.5	dB
Gain Drift	Instituten			100	-	ppm/°C
Power Supply Reject	ction	(Note 3)	_	50		dB
Power Supplies						1
Power Supply Curre	ent					
Normal Opera	ation (PDN pin = "					
VA		,		3.4	5.1	mA
VD	(fs=48kHz)			1.9	2.9	mA
VD					5.6	mA
	mode (PDN pin = $^{\circ}$	"(Note 4)		3.7	210	
VA+VI	· •			10	100	μA
, 11, 11	_				100	P

Note 2. This value is the full scale (0dB) of the input voltage. Input voltage is proportional to VA voltage. Vin = $0.6 \times VA$ (Vpp).

Note 3. PSR is applied to VA and VD with 1kHz, 50mVpp.

Note 4. All digital input pins and CKS1 pin are held VD or VSS.

	9. Filter Characteristics (fs=48kHz)								
$Ta=25^{\circ}C; VA=VD=2.7 \sim 5.5V, fs=48kHz)$									
Parameter		Symbol	min	typ	max	Unit			
ADC Digital Filter (Decimation LPF): SHARP ROLL-OFF(FSEL pin="L")									
Passband (Note 5)	±0.16dB	PB	0	-	18.8	kHz			
	-0.28dB		-	20.0	-	kHz			
	-3.0dB		-	22.8	-	kHz			
Stopband (Note 5)		SB	28.4	-	-	kHz			
Stopband Attenuation		SA	71	-	-	dB			
Group Delay Distort	tion 0 ~ 20.0kHz	ΔGD	-	0	-	1/fs			
Group Delay (Note	e 6)	GD	-	15.5	-	1/fs			
ADC Digital Filter pin="H")	(Decimation LPF):	SHORT DEL	AY SHAR	P ROLL-OFI	F FILTER(F	SEL			
Passband (Note 5)	±0.16dB	PB	0	-	18.8	kHz			
	-0.28dB		-	20.0	-	kHz			
	-3.0dB		-	22.8	-	kHz			
Stopband (Note 5)		SB	28.4		-	kHz			
Stopband Attenuation	on	SA	72		-	dB			
Group Delay Distort	tion 0 ~ 20.0kHz	ΔGD	-	-	2.4	1/fs			
Group Delay (Note	e 6)	GD	-	5.5	-	1/fs			
ADC Digital Filter	(HPF):								
Frequency Response	e -3.0dB	FR	-	1.0	-	Hz			
	-0.5dB		-	2.5	-	Hz			
(Note 5)	-0.1dB		-	6.5	-	Hz			

Note 5. The passband and stopband frequencies scale with fs.

For example, PB= $0.45 \times fs(@-0.1dB)$.

Note 6. The calculated delay time induced by digital filtering. This time is from the input of an analog signal to the setting of 24bit data both channels to the output register.

10. Filter Characteristics (fs=96kHz)								
(Ta=25°C; VA=VD=2.	.7 ~ 5.5V; fs=96kH	Iz)						
Parameter		Symbol	min	typ	max	Unit		
ADC Digital Filter (I	Decimation LPF):	SHARP ROI	LL-OFF(FS	EL pin="L")				
Passband (Note 5)	±0.16dB	PB	0	-	37.6	kHz		
	-0.28dB		-	40.0	-	kHz		
	-3.0dB		-	45.6	-	kHz		
Stopband (Note 5)		SB	56.8	-	-	kHz		
Stopband Attenuation		SA	71	-	-	dB		
Group Delay Distortion	on 0 ~ 20.0kHz	ΔGD	-	0	-	1/fs		
Group Delay (Note 6	5)	GD	-	15.5	-	1/fs		
ADC Digital Filter (I	Decimation LPF):	SHORT DEI	LAY SHAR	P ROLL-OFI	F FILTER(F	SEL		
pin="H")								
Passband (Note 5)	±0.16dB	PB	0	-	37.6	kHz		
	-0.28dB		-	40.0	-	kHz		
	-3.0dB		-	45.6	-	kHz		
Stopband (Note 5)		SB	56.8		-	kHz		
Stopband Attenuation		SA	72		-	dB		
Group Delay Distortion	on 0 ~ 20.0kHz	ΔGD	-	-	2.4	1/fs		
Group Delay (Note 6	5)	GD	-	5.5	-	1/fs		
ADC Digital Filter (l	HPF):	·			•	-		
Frequency Response	-3.0dB	FR	-	2.0	-	Hz		
	-0.5dB		-	5.0	-	Hz		
(Note 5)	-0.1dB		-	13.0	-	Hz		

Note 5. The passband and stopband frequencies scale with fs.

For example, $PB=0.45 \times fs(@-0.1dB)$.

Note 6. The calculated delay time induced by digital filtering. This time is from the input of an analog signal to the setting of 24bit data both channels to the output register.

11. DC Characteristics

$(Ta=25^{\circ}C, VA=VD=2.7 \sim 5.5V)$								
Parameter		Symbol	min	typ	max	Unit		
High-Level Input Voltage		VIH	75%VD	-	-	V		
Low-Level Input Voltage		VIL	-	-	25%VD	V		
High-Level Output Voltage (Io	out= $-80\mu A$)	VOH	VD-0.4	-	-	V		
Low-Level Output Voltage (Io	ut=80µA)	VOL	-	-	0.4	V		
Input Leakage Current		Iin	-	-	±10	μA		

12. Switching Characteristics									
(Ta=-40°C ~ 105°C; VA=VD=2.7 ~ 5.5V; C _L	Ta= -40° C ~ 105°C; VA=VD=2.7 ~ 5.5V; C _L =20pF, unless otherwise specified)								
Parameter	Symbol	min	typ	max	Unit				
Master Clock Timing									
Master Clock 256fs:	fCLK	2.048	12.288	24.576	MHz				
Pulse Width Low	tCLKL	16			ns				
Pulse Width High	tCLKH	16			ns				
384fs:	fCLK	3.072	18.432	36.864	MHz				
Pulse Width Low	tCLKL	11			ns				
Pulse Width High	tCLKH	11			ns				
512fs:	fCLK	4.096	24.576	24.576	MHz				
Pulse Width Low	tCLKL	16			ns				
Pulse Width High	tCLKH	16			ns				
768fs:	fCLK	6.144	36.864	36.864	MHz				
Pulse Width Low	tCLKL	11			ns				
Pulse Width High	tCLKH	11			ns				
LRCK Timing (Slave Mode)									
Normal mode									
LRCK Frequency	fs	8		96	kHz				
Duty Cycle	Duty	45		55	%				
TDM256 MODE									
LRCK Frequency	fs	8		96	kHz				
"H" time	tLRH	1/256fs			ns				
"L" time	tLRL	1/256fs			ns				
LRCK Timing (Master Mode)									
Normal mode									
LRCK Frequency	fs	8		96	kHz				
Duty Cycle	Duty		50		%				
TDM256 MODE									
LRCK Frequency	fs	8		96	kHz				
"H" time (Note 7)	tLRH		1/8fs		ns				

Note 7. It will be "L" time in I^2S format.

Parameter	Symbol	min	typ	max	Unit	
Audio Interface Timing (Slave m	ode)					
Normal mode						
BICK Period		(DCW	1.60			
BICK Pulse Width Low		tBCK	160			ns
Pulse Width High		tBCKL	65			ns
LRCK Edge to BICK " [↑] "	(Note 8)	tBCKH	65 20			ns
BICK " [↑] " to LRCK Edge	(Note 8)	tLRB	30 20			ns
LRCK to SDTO (MSB) (Exce	ept I ² S	tBLR	30		25	ns
mode)		tLRS			35	ns
BICK " \downarrow " to SDTO		tBSD			35	ns
TDM256 mode						
BICK Period		tBCK	40			ns
BICK Pulse Width Low		tBCKL	16			ns
Pulse Width High		tBCKH	16			ns
LRCK Edge to BICK "↑"	(Note 8)	tLRB	10			ns
BICK "↑" to LRCK Edge	(Note 8)	tBLR	10			ns
SDTO Setup time BICK "↑"		tBSS	7			ns
SDTO Hold BICK "↑"		tBSH	6			ns
TDMI Hold Time		tSDH	4			ns
TDMI Setup Time		tSDS	5			ns
Audio Interface Timing (Master	mode)					
Normal mode						
BICK Frequency		fBCK		64fs		Hz
BICK Duty		dBCK		50		%
BICK " \downarrow " to LRCK		tMBLR	-20		20	ns
BICK " \downarrow " to SDTO		tBSD	-40		40	ns
TDM256 mode						
BICK Frequency		fBCK		256fs		Hz
BICK Duty	(Note 9)	dBCK		50		%
BICK " \downarrow " to LRCK		tMBLR	-10		10	ns
SDTO Setup time BICK "↑"		tBSS	7			ns
SDTO Hold BICK "↑"		tBSH	6			ns
TDMI Hold Time		tSDH	4			ns
TDMI Setup Time		tSDS	5			ns
Power-Down & Reset Timing						
PDN Pulse Width	(Note 10)	tPD	150		30	ns
PDN Reject Pulse Width (Note 10)		tRPD		4129	50	ns
PDN " [↑] " to SDTO valid (Note 11)		tPDV		7127		1/fs

Note 8. BICK rising edge must not occur at the same time as LRCK edge.

Note 9. In the case of MCLK duty cycle is 50%.

Note 10. The AK5720 can be reset by setting the PDN pin to "L" upon power-up. The PDN pin must held "L" for more han 150ns for a certain reset. The AK5720 is not reset by the "L" pulse less than 30ns.

Note 11. This is the count of LRCK " \uparrow " from the PDN pin = "H".

■ Timing Diagram







Figure 2. Clock Timing (Master mode)

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Figure 3. Audio Interface Timing (Normal mode & Slave mode)



Figure 4. Audio Interface Timing (TDM mode & Slave mode)

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Figure 5. Audio Interface Timing (Normal mode & Master mode)



Figure 6. Audio Interface Timing (TDM mode & Master mode)



Figure 7. Power-down & Reset Timing

13. Functional Descriptions

System Clock

MCLK, BICK and LRCK (fs) clocks are required in slave mode. The LRCK clock input must be synchronized with MCLK, however the phase is not critical. Table 1 shows the relationship of typical sampling frequency and the system clock frequency. All external clocks (MCLK, BICK and LRCK) must be present unless PDN pin = "L". If the external clocks are not present, place the AK5720 in power-down mode (PDN pin = "L"). In master mode, the master clock (MCLK) must be provided unless PDN pin = "L".

fs	MCLK					
18	128fs	192fs	256fs	384fs	512fs	768fs
32kHz	N/A	N/A	8.192MHz	12.288MHz	16.384MHz	24.576MHz
44.1kHz	N/A	N/A	11.2896MHz	16.9344MHz	22.5792MHz	33.8688MHz
48kHz	N/A	N/A	12.288MHz	18.432MHz	24.576MHz	36.864MHz
96kHz	N/A	N/A	24.576MHz	36.864MHz	N/A	N/A

Table 1. System Clock Example

Audio Interface Format

MCLK frequency, the relationship of BICK frequency and fs, and master/slave mode are set by external resistance value of the CKS pin and the CKS pin connection as shown in Table 2.

When the CKS pin is connected to GND or VA directly, or via an external $4.7k\Omega$ resistor (Normal mode), the DIF/TDMI pin becomes an audio data format select pin. Two kinds of data formats: 24bit MSB justified and I²S formats can be chosen by the DIF pin. The audio data is output on the falling edge of BICK from the SDTO pin. The audio interface supports both master and slave modes. In master mode, BICK and LRCK are output and they are input in slave mode. In master mode, LRCK frequency is fixed to 1fs and the BICK frequency is fixed to 64fs.

When the CKS pin is connected to GND or the VA pin via an external resistor of $18k\Omega$ or $82k\Omega$ (TDM mode), the DIF/TDMI pin becomes a TDM data input pin. In TDM mode, the audio data is output on a rising edge of BICK from the SDTO pin. When inputting the SDTO output data to the TDMI pin, this SDTO data has a delay which fills set-up or hold time of BICK rising .

I	Mode	CKS	DIF /TDMI	SDTO	Master /Slave	MCLK	LRCK	BICK
0		$< 10\Omega$ to GND	L	MSB	Slave	256/384fs (8k≤fs≤96k)	H/L	\geq 48fs or
1		(Short to GND)	Н	I^2S	Slave	512/768fs (8k≤fs≤48k)	L/H	32fs
2		$< 10\Omega$ to VA	L	MSB	Master	256fs (8k≤fs≤96k)	H/L	64fs
3	Normal	(Short to VA)	Н	I^2S	Wiaster	23018 (8K≤18≤90K)	L/H	0415
4	Normai	4.7kΩ±10% to	L	MSB	Master	384fs (8k≤fs≤96k)	H/L	64fs
5		GND	Н	I^2S	Wiaster		L/H	0415
6		4.7kΩ±10% to VA	L	MSB	Master	512fs (8k≤fs≤48k)	H/L	64fs
7		$4.7K2 \pm 10\%$ to VA	Н	I^2S	Wiaster	J1218 (8K≥18≥48K)	L/H	
8		$18k\Omega \pm 10\%$ to GND	TDMI	MSB	Master	256fs (8k≤fs≤96k)	\leftarrow	256fs
9	TDM	$18k\Omega \pm 10\%$ to VA	TDMI	MSB	Slave	256fs (8k≤fs≤96k)	\leftarrow	256fs
10	IDM	$82k\Omega \pm 10\%$ to GND	TDMI	I^2S	Master	256fs (8k≤fs≤96k)	\rightarrow	256fs
11		$82k\Omega \pm 10\%$ to VA	TDMI	I ² S	Slave	256fs (8k≤fs≤96k)	\rightarrow	256fs

Table 2. Operation Mode Select

Note 12. SDTO outputs 16-bit data when BICK=32fs.



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Digital High Pass Filter

The ADC has a digital high pass filter for DC offset cancellation. The cut-off frequency of the HPF is 1.0Hz (@fs=48kHz) and scales with sampling rate (fs).

Power Down

The AK5720 is placed in the power-down mode by bringing the PDN pin to "L". The digital filter is also reset at the same time. This reset should always be executed upon power-up. In power-down mode, VCOM becomes VSS level. The AK5720 will be in analog initialization cycle after exiting the power-down mode. Therefore, the SDTO output data becomes valid after 4129 cycles of LRCK clock in master mode or 4132 cycles of LRCK clock in slave mode when power up the AK5720. During initialization, both L and R channels of ADC digital data outputs are forced to "0" in 2's complement. The ADC outputs settle as a data corresponding to the input signals after the end of initialization (this settling takes approximately group delay time).



Figure 12. Power-down/up Timing Example

Notes:

- (1) The PDN pin must be "L" when power up the AK5720 and set to "H" after all poweres are supplied.
- (2) The internal power-down state is released after 147456/ MCLK cycles.
- (3) There is a delay about 3~4fs from internal power-up to the start of initialization cycle.
- (4) Digital block of the ADC is initialized after internal power-down is released.

When start-up the AK5720, ADC input voltage should be operation common voltage.

- A charge-up time of DC cut capacitor is necessary to wait until the RIN and LIN pins settle to the common voltage. When the external capacitor is 10μ F, the status of these pin settles in τ = 400ms (typ).
- (5) Click noise occurs at the end of initialization in the digital part. Mute the ADC output externally if the click noise influences system applications.
- (6) Digital output corresponds to analog input has group delay (GD).
- (7) ADC outputs "0" data in power-down state.

System Reset

The AK5720 should be reset once by bringing the PDN pin to "L" after power-up. In slave mode, reset and power-down are released on the rising edge (falling edge in I^2C compatible mode) of LRCK after setting the PDN pin = "H". In master mode, reset and power-down are released by MCLK input after setting the PDN pin = "H".

■ TDM Cascade Mode

TDM256mode

Four or less devices can be connected in cascades at the TDM256 mode. In Figure 13, the SDTO pin of device $\frac{1}{2}\frac{3}{44}$. It is possible to output 8 channel TDM data from the SDTO pin of device $\frac{4}{4}$ as shown in Figure 14.



Figure 13. Cascade TDM Connection Diagram

	<u>لم</u>	256 BICK						4	
LRCK (Master)]						-	
LRCK (Slave)	t 📖								İ 🔳
BICK(256fs)		בער בארב						בער בארוב br>בארוב בארוב בארו	Įl.
#1 SDTO(o)	23 22 0	23 22 0							23 22
	L-#1 32 BICK	R-#1 32 BICK							
#4 TDMIN(i)	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0			
	L-#3 32 BICK	R-#3 32 BICK	L-#2 32 BICK	R-#2 32 BICK	L-#1 32 BICK	R-#1 32 BICK			
#4 SDTO(o)	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0	23 22 0	23 22
	L-#4 32 BICK	R-#4 32 BICK	L-#3 32 BICK	R-#3 32 BICK	L-#2 32 BICK	R-#2 32 BICK	L-#1 32 BICK	R-#1 32 BICK	
	-	1		i I	1	1		1	i I

Figure 14. Cascade TDM Timing (TDM256 Mode (Left Justified))

14. Recommended External Circuits

Figure 15 shows the system connection diagram. An evaluation board (AKD5720) is available which demonstrates application circuits, the optimum layout, power supply arrangements and measurement results.



Note:

- All digital input pins should not be left floating.



1. Grounding and Power Supply Decoupling

The AK5720 requires careful attention to power supply and grounding arrangements. Alternatively if VA and VD are supplied separately, the power up sequence is not critical. VSS of the AK5720 must be connected to analog ground plane. System analog ground and digital ground should be connected together near to where the supplies are brought onto the printed circuit board. Decoupling capacitors should be as near to the AK5720 as possible, with the small value ceramic capacitor being the nearest.

2. Voltage Reference

The voltage input to VA sets the analog input range. VCOM is 50% VA and used as the common voltage of analog signals. The VCOM pin is connected to VSS. A 0.47μ F ceramic capacitor should be connected as close to the VCOM pin as possible between VSS and the VCOM pin. No load current may be drawn from these pins. All signals, especially clocks, should be kept away from the VCOM pin in order to avoid unwanted coupling into the AK5720.

3. Analog Inputs

The ADC inputs are single-ended and internally biased to the common voltage (50% VA) with 41k Ω (typ@fs=48kHz) resistance. The input signal range scales with the supply voltage and nominally 0.6×VA Vpp (typ). The ADC output data format is 2's complement. The internal HPF removes the DC offset (includes the DC offset that is caused by the ADC).

The AK5720 samples the analog inputs at 64fs. The digital filter rejects noise above the stop band except for multiples of 64fs. The AK5720 includes an anti-aliasing filter (RC filter) to attenuate a noise around 64fs.

4. External Resistor of the CKS pin

The external resistor of the CKS pin should be close as possible to the pin and kept away from the signal lines to prevent noises into the CKS pin.

15. Package

Outline Dimensions





Material & Lead Finish

Package molding compound:	Epoxy
Lead frame material:	Cu
Lead frame surface treatment:	Solder (Pb free) plate

Marking



- 1) Pin #1 indication
- 2) Date Code: XXXYY (5 digits) XXX: Week Code YY: Factory Control Code
- 3) Marketing Code : 5720VT
- 4) Asahi Kasei Logo

16. Revision History

Date (Y/M/D)	Revision	Reason	Page	Contents
14/04/17	00	First Edition		
14/10/17	01	Error	22	3. Analog Inputs
		Correction		The AK5720 samples the analog inputs at
				64fs(@fs=48kHz).
				\rightarrow The AK5720 samples the analog inputs at 64fs.
14/12/18	02	Error	16	Table 2 Mode 8-11
		Correction		The tolerances of resisters were corrected.
				$\pm 5\% \rightarrow \pm 10\%$
		Description	16	Table 2 and Table 3 were combined.
		Change		

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