Compact, Amplifier Built-In Type with Universal Voltage

Features

- Small and power supply built-in type
- Easy installation with LED indicators on product
- Light ON/Dark ON operation mode switch
- Status and output LED indication
- Built-in IC photo diode for disturbing light and electrical noise

Please read "Safety Considerations" in the instruction manual before using





MS-4, MST-□ is sold separately.

Specifications

• Free power, Relay contact output type

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR		
Sensing	type	Through-beam	Retroreflective (standard type)	Retroreflective (built-in polarizing filter)	Diffuse reflective		
Sensing distance		10m	5m ^{*1}	3m ^{*1}	300mm ^{*2}		
Sensing target		Opaque materials of min. Ø16mm	Opaque materials of min. Ø60mm		Translucent, opaque materials		
Hysteresis		Max. 20% at rated distance					
Response time		Max. 20ms					
Power su	upply	24-240VAC~ ±10% 50/60Hz, 24-240VDC== ±10% (ripple P-P: max. 10%)					
Current c	consumption	Max. 4VA					
Light sou	irce	Infrared LED (850nm)		Red LED (660nm)	Infrared LED (940nm)		
Sensitivit	ty adjustment	— Sensitivity adjuster					
Operatio	n mode	Light ON/Dark ON operation mode switch					
Control output		Relay contact output (relay contact capacity: 30VDC 3A of resistive load, 250VAC~ 3A resistive load, relay contact composition: 1c)					
Relay life cycle		Mechanically: min. 50,000,000 operation, electrically: min. 100,000 operation					
Light receiving element		Photo IC					
Indicator		Operation indicator: red LED, stability indicator: green LED (the red lamp on emitter of transmitted beam type is for power indication)					
Insulation resistance		Over 20MΩ (at 500VDC megger)					
Insulation type		Double or strong insulation (mark: , dielectric voltage between the measured input and the power: 1kV)					
Noise immunity		±1,000V the square wave noise (pulse width: 1µs) by the noise simulator					
Dielectric strength		1000VAC 50/60Hz for 1 minute					
Vibration	Mechanical	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours					
vibration	Malfunction	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 minutes					
Chaol	Mechanical	500m/s² (approx. 50G) in each X, Y, Z direction for 3 times					
Shock	Malfunction	100m/s ² (approx. 10G) in each X, Y, Z direction for 3 times					
	Ambient illumination	Sunlight: max. 11,000lx, incandescent lamp: max. 3,000lx (receiver illumination)					
Environ-	Ambient temperature	-20 to 65°C, storage: -25 to 70°C					
ment	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH					
Protection structure		IP50 (IEC standard)					
Material		Case, case cover: heat resistant acrylonitrile butadiene styrene, sensing part: polycarbonate (with polarizing filter: polymethyl methacrylate), bracket: steel plate cold commercial, bolt: steel chromium molybdenum, nut: steel chromium molybdenum					
Cable		Ø5mm, 5-wire, 2m (emitter of through-beam type: Ø5mm, 2-wire, 2m) (AWG22, core diameter: 0.08mm, number of cores: 60, insulator out diameter: Ø1.25mm)					
	Individual		Reflector (MS-2)				
Accessory		Adjustment screwdriver, mounting bracket, M4 bolt: 4, M4 nut: 4		ver, mounting bracket, M4 bolt: 2	2, M4 nut: 2		
Unit weig	jht	Approx. 354g	Approx. 208g		Approx. 195g		

%1: The sensing distance is specified with using the MS-2 reflector and the same as the MS-4 reflector. Sensing distance is the setting range of the reflector. The sensor can detect under 0.1m.

When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the "Reflectivity by Reflective Tape Model" table before using the tapes.

%2: Non-glossy white paper 200×200mm.

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Autonics

• DC power, Solid state output type

Model		BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN300-DDT			
Sensing t	type	Through-beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective	SENSORS		
Sensing distance		10m	5m ^{*1}	3m ^{*1}	300mm ^{*2}			
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of min. Ø60mm		Translucent, opaque materials	CONTROLLERS		
Hysteresis					Max. 20% at rated setting distance	MOTION DEVICES		
Response	e time	Max. 1ms						
Power su	upply	12-24VDC==±10% (ripple F	P-P: max. 10%)					
Current c	consumption	Max. 50mA				SOFTWARE		
Light sou	irce	Infrared LED (850nm)		Red LED (660nm)	Infrared LED (940nm)			
Sensitivit	y adjustment	·	Sensitivity adjuster	- I · ·				
Operation		Light ON/Dark ON operation						
Control o		NPN open collector / PNP •Load voltage: max. 30VDC=	open collector simultaneou = •Load current: max. 200m	A •Residual voltage - NPN: n	nax. 1VDC, PNP: max. 2.5VDC			
Protection	n circuit	Reverse polarity protection circuit, output short overcurrent protection circuit						
Light rece	eiving element	Photo IC	· · ·					
La diaatar		Operation indicator: red, stability indicator: green				_		
Indicator		(the red lamp on Emitter of transmitted beam type is for power indication)				(A) Photoelectric		
Insulation	n resistance	Over 20MΩ (at 500VDC megger)				Photoelectric Sensors		
Noise imr	munity	±240V the square wave noise (pulse width: 1μs) by the noise simulator						
Dielectric	strength	1000VAC 50/60Hz for 1 minute				(B)		
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				Fiber Optic Sensors		
Shock		500m/s ² (approx. 50G) in e				00		
	Ambient illumination							
Environ-		e -20 to 65°C, storage: -25 to 70°C				(C) LIDAR		
ment	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH						
Protection	n structure	IP50 (IEC standard)				(D)		
		case, case cover: heat resistant acrylonitrile butadiene styrene,			Door/Area Sensors			
Material		sensing part: polycarbonate (with polarizing filter: polymethyl methacrylate),						
		bracket: steel plate cold commercial, bolt: steel chromium molybdenum,				(E) Vision Sensors		
		nut: steel chromium molybdenum						
Cable		Ø5mm, 4-wire, 2m (emitter of through-beam type: Ø5mm, 2-wire, 2m) (AWG22, core diameter: 0.08mm, number of cores: 60, insulator diameter: Ø1.25mm)			00			
	Level delivert	(AWG22, core diameter: U.		50, insulator diameter: 1.2	(5mm)	(F)		
i I	Individual		Reflector (MS-2)			Proximity Sensors		
Accessory	Common	Adjustment screwdriver,	Adjustment screwdriver, mounting bracket, M4 bolt: 2, M4 nut: 2			(G)		
		mounting bracket,						
		M4 bolt: 4, M4 nut: 4			Pressure			
Approval				Sensors				
Unit weight		Approx. 342g	Approx. 200g		Approx. 187g			
		specified with using the MS- e sensor can detect under (as the MS-4 reflector. Sensi	ng distance is the setting	(H) Rotary Encoders		

range of the reflector. The sensor can detect under 0.1m.

When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the "IReflectivity by Reflective Tape Model" table before using the tapes

%2: Non-glossy white paper 100×100mm.

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Feature data

O Through-beam type

• BEN10M-TFR • BEN10M-TDT



Autonics

(I) Connectors/ Connector Cables/ Sensor Distribution

Boxes/ Sockets

Feature Data

Retroreflective type (standard type)

• BEN5M-MFR • BEN5M-MDT



• BEN5M-MFR • BEN5M-MDT



• BEN5M-MFR • BEN5M-MDT



Retroreflective type (built-in polarizing filter) BEN3M-PFR • BEN3M-PDT



• BEN3M-PFR • BEN3M-PDT



• BEN3M-PFR • BEN3M-PDT



Autonics

◎ Diffuse reflective type

• BEN300-DFR • BEN300-DDT



Control Output Diagram

DC voltage (NPN/PNP synchronous output)



※If short-circuit the control output terminal or supply current over the rated specification, normal control signal is not output due to the output short over current protection circuit.

Operation Mode

Operation mode	Light ON	SENSORS
Receiver operation	Received light	
	Interrupted light	CONTROLLERS
Operation indicator	ON	
(red LED)	OFF	MOTION DEVICES
Transistar autout	ON	
Transistor output	OFF	
		SOFTWARE
Operation mode	Dark ON	
Receiver operation	Received light	
Receiver operation	Interrupted light	
Operation indicator	ON	
(red LED)	OFF	
Transistar autout	ON	(A)
Transistor output	OFF	Photoelectric Sensors

Free power (Relay contact output)

🔆 (Gray)Tb

🔆 (black)Ta

ḋ(white)To

(brown)

(blue)

current protection circuit. If short-circuit the control output

terminal or supply current over the rated specification, it

%The product is not equipped with the output short over

Contact output (1c)

Power

24-240VAC

24-240VDC

Photoelectric sensor circuit Connection

C

Relay

Free power

circuit

may result in product damage.

circuit

Main

Fiber Optic Sensors

(B)

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

Proximity Sensors

(F)

(G)

(1)

Pressure Sensors

(H) Rotary Encoders

Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Operation Timing Diagram



%The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation. They are opposite operation for Dark ON operation.

Connections



X Unused line must be insulated.

Dimensions



•Retroreflective type

•Diffuse reflective type







Ø5, 2m

Amplifier Built-in Type with Universal Voltage

• Reflector



• Reflective tape (sold separately)



Bracket



	(unit: mm)
Model	А
MST-50-10	□50
MST-100-5	□100
MST-200-2	□200

Mounting and sensitivity adjustment

When using photoelectric sensors closely over two units, it may result in malfunction due to mutual interference. When installing the product, tighten the screw with a tightening torque of 1.2N·m.

O Through-beam type

- 1. Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the stability range of indicator by adjusting the receiver or the emitter right and left, up and down.
- 3. After the adjustment, check the stability of operation by putting the object at the optical axis.
- %If the sensing target is translucent body or smaller than Ø16mm, it can be missed by sensor because light penetrate it.



◎ Diffuse reflective type

- 1. The sensitivity should be adjusted depending on a sensing target or mounting place.
- Set the target at a position to be detected by the beam, then turn the sensitivity adjuster until position (a) where the operation indicator turns ON from min. position of the sensitivity adjuster.
- Take the target out of the sensing area, then turn the sensitivity adjuster until position
 where the operation indicator turns ON. If the indicator dose not turn ON, max. position is
 .
- 4. Set the sensitivity adjuster at the center of two switching position (a), (b).
- %The sensing distance indicated on specification chart is for 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.





SENSORS

SOFTWARE

(A) Photoelectric Sensors (B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distributior Boxes/ Sockets

◎ Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector or reflective tape face to face.
- 2. Set the photoelectric sensor in the position which indicator turns on, by adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.



XIf using more than 2 photoelectric sensors in parallel, the space among them should be more than 30cm.

※If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis. (When a sensing target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)

XSensitivity adjustment: Refer to the diffuse reflective type's.



- %If the mounting place is too narrow, please use MS-4 instead of MS-2.
- %Please use reflective tape (MST series) for where a reflector is not installed.



© Retroreflective type with polarizing filter

The light passed through the polarizing filter of the emitter reaches to the MS-2 reflector or reflective tape converting as horizontal direction. It reaches to the receiver element of polarizing filter converting as vertical by the MS-2 reflector or reflective tape. Therefore, this type can also detect reflective mirror.



%Please use reflective tape (MST Series) for where a reflector is not installed.

Reflectivity by Reflective Tape Model

	Standard	Built-in polarizing filter
MST-50-10 (50×50mm)	90%	70%
MST-100-5 (100×100mm)	130%	90%
MST-200-2 (200×200mm)	140%	120%

"This reflectivity is based on the reflector (MS-2).

※Reflectivity may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases. Please check the reflectivity before using reflective

tapes.

%For using reflective tape, installation distance should be min. 20mm.