



12-Bit, 125 MSPS Analog-To-Digital Converter

FEATURES

- 12-Bit Resolution
- 125 MSPS Sample Rate
- High SNR: 69.7 dBFS at 100 MHz f_{IN}
- High SFDR: 82 dBc at 100 MHz f_{IN}
- 2.3-V_{PP} Differential Input Voltage
- Internal Voltage Reference
- 3.3-V Single-Supply Voltage
- Analog Power Dissipation: 578 mW
- Serial Programming Interface
- TQFP-64 PowerPAD™ Package
- Recommended Op Amps:
THS3201, THS3202, THS4503, THS4509,

THS9001, OPA695, OPA847
APPLICATIONS

- **Wireless Communication**
 - Communication Receivers
 - Base Station Infrastructure
- **Test and Measurement Instrumentation**
- **Single and Multichannel Digital Receivers**
- **Communication Instrumentation**
 - Radar
 - Infrared
- **Video and Imaging**
- **Medical Equipment**

DESCRIPTION

The ADS5520 is a high-performance, 12-Bit, 125 MSPS analog-to-digital converter (ADC). To provide a complete converter solution, it includes a high-bandwidth linear sample-and-hold stage (S&H) and internal reference. Designed for applications demanding the highest speed and highest dynamic performance in little space, the ADS5520 has excellent power consumption of 578 mW at 3.3-V single-supply voltage. This allows an even higher system integration density. The provided internal reference simplifies system design requirements. Parallel CMOS-compatible output ensures seamless interfacing with common logic.

The ADS5520 is available in a 64-pin TQFP PowerPAD package over the industrial temperature range.

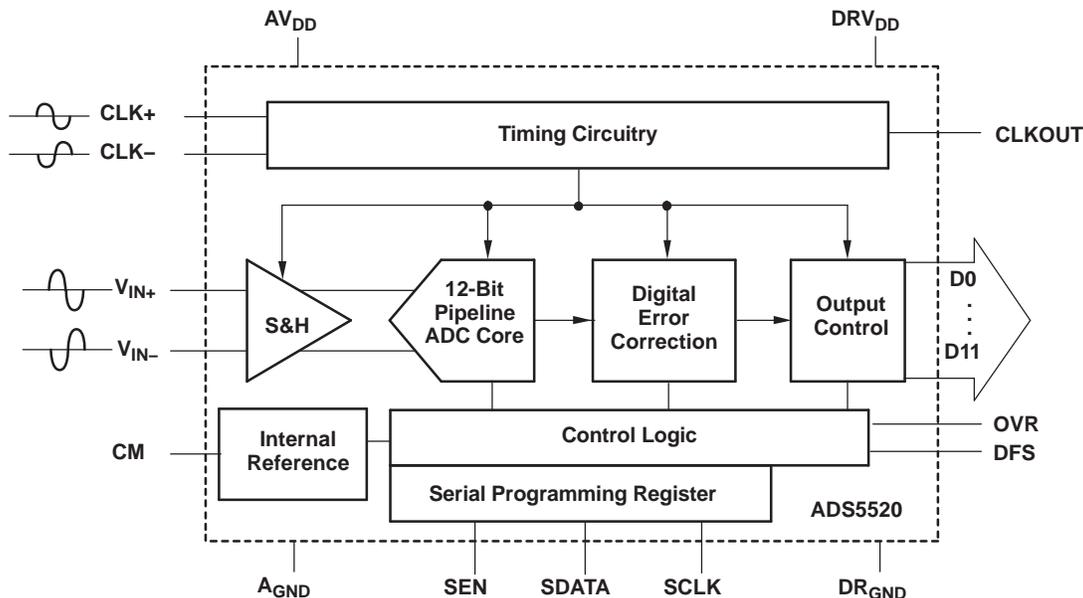
Table 1. ADS5500 Product Family

| | 80 MSPS | 105 MSPS | 125 MSPS |
|--------|----------------|-----------------|-----------------|
| 12 Bit | ADS5522 | ADS5521 | ADS5520 |
| 14 Bit | ADS5542 | ADS5541 | ADS5500 |



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

ORDERING INFORMATION⁽¹⁾

| PRODUCT | PACKAGE-LEAD | PACKAGE DESIGNATOR | SPECIFIED TEMPERATURE RANGE | PACKAGE MARKING | ORDERING NUMBER | TRANSPORT MEDIA, QUANTITY |
|---------|-------------------------------------|--------------------|-----------------------------|-----------------|-----------------|---------------------------|
| ADS5520 | HTQFP-64 ⁽²⁾ PowerPAD | PAP | –40°C to 85°C | ADS5520I | ADS5520IPAP | Tray, 160 |
| | | | | | ADS5520IPAPR | Tape and Reel, 1000 |

- (1) For the most current package and ordering information, see the Package Option Addendum at the end of this data sheet.
- (2) Thermal pad size: 3,5 mm x 3,5 mm (min), 4 mm x 4 mm (max). $\theta_{JA} = 21.47^{\circ}\text{C/W}$ and $\theta_{JC} = 2.99^{\circ}\text{C/W}$, when used with 2 oz. copper trace and pad soldered directly to a JEDEC standard, four-layer, 3 in x 3 in PCB.

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | ADS5520 | UNIT |
|--|---|---|------|
| Supply Voltage | AV _{DD} to A _{GND} , DRV _{DD} to DR _{GND} | –0.3 to 3.7 | V |
| | A _{GND} to DR _{GND} | ±0.1 | V |
| Analog input to A _{GND} ⁽²⁾⁽³⁾ | | –0.3 to minimum (AV _{DD} + 0.3, 3.6) | V |
| Logic input to DR _{GND} | | –0.3 to DRV _{DD} | V |
| Digital data output to DR _{GND} | | –0.3 to DRV _{DD} | V |
| Operating temperature range | | –40 to 85 | °C |
| Junction temperature | | 105 | °C |
| Storage temperature range | | –65 to 150 | °C |

- (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.
- (2) If the input signal can exceed 3.6 V, then a resistor greater than or equal to 25 Ω should be added in series with each of the analog input pins to support input voltages up to 3.8 V. For input voltages above 3.8 V, the device can only handle transients and the duty cycle of the overshoot should be limited to less than 5% for inputs up to 3.9 V.
- (3) The overshoot duty cycle can be defined as the ratio of the total time of overshoot to the total intended device lifetime, expressed as a percentage. The total time of overshoot is the integrated time of all overshoot occurrences over the lifetime of the device.

RECOMMENDED OPERATING CONDITIONS

| PARAMETER | MIN | TYP | MAX | UNIT |
|---|----------|------|------|-----------------|
| Supplies | | | | |
| Analog supply voltage, AV _{DD} | 3 | 3.3 | 3.6 | V |
| Output driver supply voltage, DRV _{DD} | 3 | 3.3 | 3.6 | V |
| Analog input | | | | |
| Differential input range | | 2.3 | | V _{PP} |
| Input common-mode voltage, V _{CM} ⁽¹⁾ | 1.45 | 1.55 | 1.65 | V |
| Digital Output | | | | |
| Maximum output load | | 10 | | pF |
| Clock Input | | | | |
| ADCLK input sample rate (sine wave) 1/t _c | DLL ON | 60 | 125 | MSPS |
| | DLL OFF | 2 | 80 | |
| Clock amplitude, sine wave, differential ⁽²⁾ | 1 | 3 | | V _{PP} |
| Clock duty cycle ⁽³⁾ | | 50% | | |
| Open free-air temperature range | ADS5520I | –40 | 85 | °C |

- (1) Input common-mode should be connected to CM.
- (2) See [Figure 49](#) for more information.
- (3) See [Figure 48](#) for more information.

ELECTRICAL CHARACTERISTICS

Typical values given at T_A = 25°C, min and max specified over the full recommended operating temperature range, AV_{DD} = DRV_{DD} = 3.3 V, sampling rate = 125 MSPS, 50% clock duty cycle, DLL On, 3-V_{PP} differential clock, and –1dBFS differential input, unless otherwise noted

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|--|-------------------------------|-----|-----|-----|-----------------|
| Resolution | | | 12 | | Bits |
| Analog Inputs | | | | | |
| Differential input range | | | 2.3 | | V _{PP} |
| Differential input impedance | See Figure 39 | | 6.6 | | kΩ |
| Differential input capacitance | See Figure 39 | | 4 | | pF |
| Analog input common-mode current (per input) | | | 300 | | μA |
| Analog input bandwidth | Source impedance = 50 Ω | | 750 | | MHz |

ELECTRICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, min and max specified over the full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, sampling rate = 125 MSPS, 50% clock duty cycle, DLL On, 3- V_{PP} differential clock, and -1dBFS differential input, unless otherwise noted

| PARAMETER | CONDITIONS | | MIN | TYP | MAX | UNIT |
|--|--|---------------------|------|--------------------|-----|---------------------------|
| Voltage overload recovery time | | | | 4 | | Clock cycles |
| Internal Reference Voltages | | | | | | |
| Reference bottom voltage, V_{REFM} | | | | 0.95 | | V |
| Reference top voltage, V_{REFP} | | | | 2.1 | | V |
| Reference error | | | -4% | $\pm 0.9\%$ | 4% | |
| Common-mode voltage output, V_{CM} | | | | 1.55 ± 0.05 | | V |
| Dynamic DC Characteristics and Accuracy | | | | | | |
| No missing codes | | | | Tested | | |
| Differential nonlinearity error, DNL | $f_{IN} = 10\text{ MHz}$ | | -0.5 | ± 0.25 | 0.5 | LSB |
| Integral nonlinearity error, INL | $f_{IN} = 10\text{ MHz}$ | | -1.5 | ± 0.8 | 1.5 | LSB |
| Offset error | | | -11 | ± 1.5 | 11 | mV |
| Offset temperature coefficient | | | | 0.01 | | mV/ $^\circ\text{C}$ |
| DC power-supply rejection ratio, DC PSRR | $\Delta\text{offset error}/\Delta AV_{DD}$ from $AV_{DD} = 3\text{ V}$ to $AV_{DD} = 3.6\text{ V}$ | | | 0.25 | | mV/V |
| Gain error ⁽¹⁾ | | | -2 | ± 0.45 | 2 | %FS |
| Gain temperature coefficient | | | | 0.01 | | $\Delta\%/^\circ\text{C}$ |
| Dynamic AC Characteristics | | | | | | |
| Signal-to-noise ratio, SNR | $f_{IN} = 10\text{ MHz}$ | 25 $^\circ\text{C}$ | 68 | 70.2 | | dBFS |
| | | Full temp range | 66 | 69.3 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 70.1 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25 $^\circ\text{C}$ | 68 | 70.1 | | |
| | | Full temp range | 66 | 68.8 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 69.7 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 69.3 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 68.4 | | | |
| RMS idle channel noise | Inputs tied to common-mode | | | 0.32 | | LSB |
| Spurious-free dynamic range, SFDR | $f_{IN} = 10\text{ MHz}$ | 25 $^\circ\text{C}$ | 79 | 85 | | dBc |
| | | Full temp range | 76 | 84 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 79 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25 $^\circ\text{C}$ | 78 | 83 | | |
| | | Full temp range | 75 | 82 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 82 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 78 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 74 | | | |
| Second-harmonic, HD2 | $f_{IN} = 10\text{ MHz}$ | 25 $^\circ\text{C}$ | 79 | 91 | | dBc |
| | | Full temp range | 76 | 86 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 84 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25 $^\circ\text{C}$ | 78 | 87 | | |
| | | Full temp range | 75 | 83 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 84 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 78 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 74 | | | |

(1) Gain error is specified by design and characterization; it is not tested in production.

ELECTRICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, min and max specified over the full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, sampling rate = 125 MSPS, 50% clock duty cycle, DLL On, 3- V_{PP} differential clock, and -1dBFS differential input, unless otherwise noted

| PARAMETER | CONDITIONS | | MIN | TYP | MAX | UNIT |
|--|---|--------------------|------|------|-----|------|
| Third-harmonic, HD3 | $f_{IN} = 10\text{ MHz}$ | 25°C | 79 | 89 | | dBc |
| | | Full temp range | 76 | 88 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 79 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25°C | 78 | 85 | | |
| | | Full temp range | 75 | 82 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 82 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 80 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 78 | | | |
| Worst-harmonic/spur (other than HD2 and HD3) | $f_{IN} = 10\text{ MHz}$ | 25°C | | 88 | | dBc |
| | $f_{IN} = 70\text{ MHz}$ | 25°C | | 86 | | |
| Signal-to-noise + distortion, SINAD | $f_{IN} = 10\text{ MHz}$ | 25°C | 67.5 | 69.8 | | dBFS |
| | | Full temp range | 65.5 | 69 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 69.5 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25°C | 67.5 | 69.9 | | |
| | | Full temp range | 65.5 | 68.6 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 69.5 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 68.5 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 66.7 | | | |
| Total harmonic distortion, THD | $f_{IN} = 10\text{ MHz}$ | 25°C | 78 | 85 | | dBc |
| | | Full temp range | 75 | 83 | | |
| | $f_{IN} = 55\text{ MHz}$ | | | 77 | | |
| | $f_{IN} = 70\text{ MHz}$ | 25°C | 77 | 81 | | |
| | | Full temp range | 74 | 79.5 | | |
| | $f_{IN} = 100\text{ MHz}$ | | | 79 | | |
| | $f_{IN} = 150\text{ MHz}$ | | | 75 | | |
| $f_{IN} = 220\text{ MHz}$ | | | 72 | | | |
| Effective number of bits, ENOB | $f_{IN} = 70\text{ MHz}$ | | | 11.3 | | Bits |
| Two-tone intermodulation distortion, IMD | $f = 10.1\text{ MHz}, 15.1\text{ MHz}$ (-7dBFS each tone) | | | 95 | | dBFS |
| | $f = 50.1\text{ MHz}, 55.1\text{ MHz}$ (-7dBFS each tone) | | | 92 | | |
| | $f = 148.1\text{ MHz}, 153.1\text{ MHz}$ (-7dBFS each tone) | | | 93.5 | | |
| AC power supply rejection ratio, ACPSRR | Supply noise frequency $\leq 100\text{ MHz}$ | | | 35 | | dB |
| Power Supply | | | | | | |
| Total supply current, ICC | $f_{IN} = 70\text{ MHz}$ | | | 236 | 260 | mA |
| Analog supply current, IAVDD | $f_{IN} = 70\text{ MHz}$ | | | 175 | 190 | mA |
| Output buffer supply current, IDRVD | $f_{IN} = 70\text{ MHz}$ | | | 61 | 70 | mA |
| Power dissipation | Analog only | | | 578 | 627 | mW |
| | Output buffer power with 10-pF load on digital output to ground | | | 202 | 231 | |
| Standby power | With Clocks running | | | 180 | 250 | mW |

DIGITAL CHARACTERISTICS

Valid over full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, unless otherwise noted

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------|------------|-----|-----|-----|------|
| Digital Inputs | | | | | |

DIGITAL CHARACTERISTICS (continued)Valid over full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, unless otherwise noted

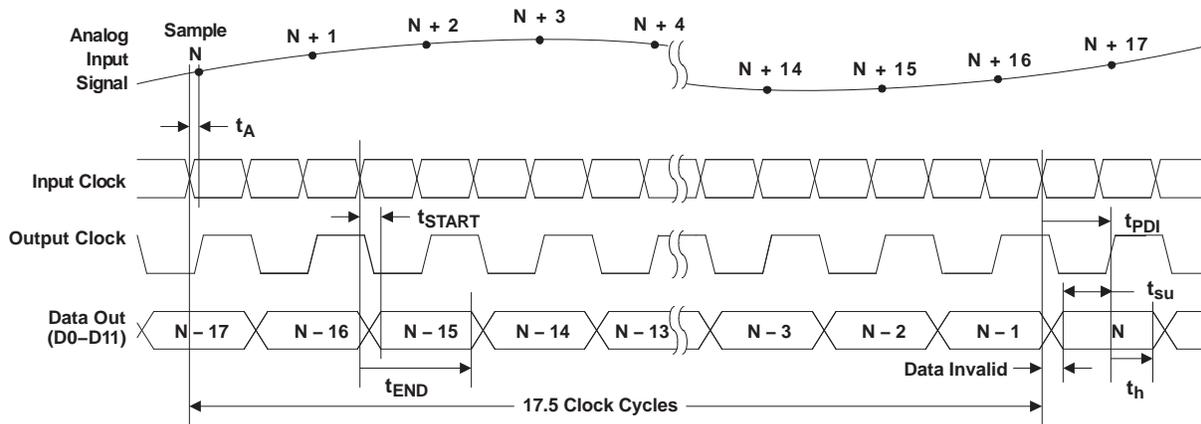
| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------------------------------|---------------------------|-----|-----|-----|---------------|
| High-level input voltage, V_{IH} | | 2.4 | | | V |
| Low-level input voltage, V_{IL} | | | | 0.8 | V |
| High-level input current, I_{IH} | | | | 10 | μA |
| Low-level input current, I_{IL} | | | | -10 | μA |
| Input current for RESET | | | -20 | | μA |
| Input capacitance | | | 4 | | pF |
| Digital Outputs | | | | | |
| Low-level output voltage, V_{OL} | $C_{LOAD} = 10\text{ pF}$ | | 0.3 | 0.4 | V |
| High-level output voltage, V_{OH} | $C_{LOAD} = 10\text{ pF}$ | 2.8 | 3 | | V |
| Output capacitance | | | 3 | | pF |

TIMING CHARACTERISTICS⁽¹⁾⁽²⁾

Typical values given at $T_A = 25^\circ\text{C}$, min and max specified over the full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, sampling rate = 125 MSPS, 50% clock duty cycle, 3- V_{PP} differential clock, and $C_{LOAD} = 10\text{ pF}$, unless otherwise noted

| PARAMETER | DESCRIPTION | MIN | TYP | MAX | UNIT |
|--|--|-----|------|------|------------------|
| Switching Specification | | | | | |
| Aperture delay, t_A | Input CLK falling edge to data sampling point | | 1 | | ns |
| Aperture jitter (uncertainty) | Uncertainty in sampling instant | | 300 | | fs |
| Data setup time, t_{SU} | Data valid ⁽³⁾ to 50% of CLKOUT rising edge | 2.3 | 2.7 | | ns |
| Data hold time, t_H | 50% of CLKOUT rising edge to data becoming invalid ⁽³⁾ | 1.7 | 2 | | ns |
| Input clock to output data valid start, $t_{START}^{(4)(5)}$ | Input clock rising edge to data valid start delay | | 2 | 2.6 | ns |
| Input clock to output data valid end, $t_{END}^{(4)(5)}$ | Input clock rising edge to data valid end delay | 5.8 | 6.9 | | ns |
| Output clock jitter, t_{JIT} | Uncertainty in CLKOUT rising edge, peak-to-peak | | 150 | 210 | ps _{PP} |
| Output clock rise time, t_r | Rise time of CLKOUT from 20% to 80% of DRV_{DD} | | 1.7 | 1.9 | ns |
| Output clock fall time, t_f | Fall time of CLKOUT from 80% to 20% of DRV_{DD} | | 1.5 | 1.7 | ns |
| Input clock to output clock delay, t_{PDI} | Input clock rising edge, zero crossing, to output clock rising edge 50% | 4.2 | 4.8 | 5.5 | ns |
| Data rise time, t_r | Data rise time measured from 20% to 80% of DRV_{DD} | | 3.6 | 4.6 | ns |
| Data fall time, t_f | Data fall time measured from 80% to 20% of DRV_{DD} | | 2.8 | 3.7 | ns |
| Output enable(OE) to data output delay | Time required for outputs to have stable timings with regard to input clock ⁽⁶⁾ after OE is activated | | | 1000 | Clock cycles |
| Wake-up time | Time to valid data after coming out of software power down | | | 1000 | Clock cycles |
| | Time to valid data after stopping and restarting the clock | | | 1000 | |
| Latency | Time for a sample to propagate to the ADC outputs | | 17.5 | | Clock cycles |

- (1) Timing parameters are ensured by design and characterization, and not tested in production.
- (2) See [Table 6](#) through [Table 9](#) in the *Application Information* section for timing information at additional sampling frequencies.
- (3) Data valid refers to 2 V for LOGIC HIGH and 0.8 V for LOGIC LOW.
- (4) See the *Output Information* section for details on using the input clock for data capture.
- (5) These specifications apply when the CLKOUT polarity is set to rising edge (according to [Table 3](#)). Add 1/2 clock period for the valid number for a falling edge CLKOUT polarity.
- (6) Data outputs are available within a clock from assertion of OE; however, it takes 1000 clock cycles to ensure stable timing with respect to input clock.



A. It is recommended that the loading at CLKOUT and all data lines are accurately matched to ensure that the above timing matches closely with the specified values.

Figure 1. Timing Diagram

RESET TIMING CHARACTERISTICS

Typical values given at $T_A = 25^\circ\text{C}$, min and max specified over the full recommended operating temperature range, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, and $3\text{-}V_{PP}$ differential clock, unless otherwise noted

| PARAMETER | DESCRIPTION | MIN | TYP | MAX | UNIT |
|--------------------------------|---|-----|-----|-----|---------------|
| Switching Specification | | | | | |
| Power-on delay, t_1 | Delay from power-on of AV_{DD} and DRV_{DD} to RESET pulse active | 10 | | | ms |
| Reset pulse width, t_2 | Pulse width of active RESET signal | 2 | | | μs |
| Register write delay, t_3 | Delay from RESET disable to SEN active | 2 | | | μs |
| Power-up time | Delay from power-up of AV_{DD} and DRV_{DD} to output stable | | 40 | | ms |

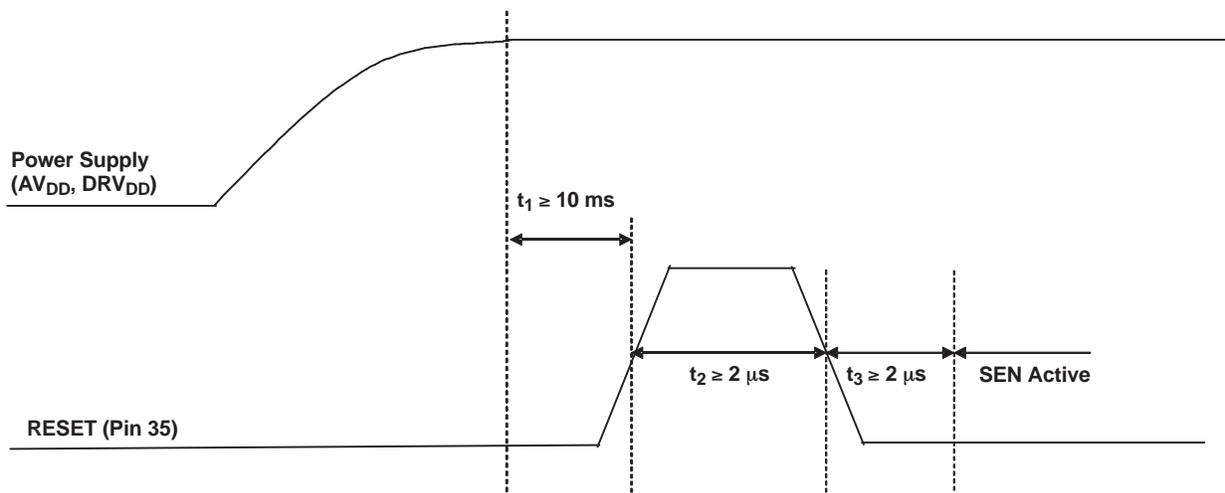


Figure 2. Reset Timing Diagram

SERIAL PROGRAMMING INTERFACE CHARACTERISTICS

The ADS5520 has a three-wire serial interface. The ADS5520 latches serial data SDATA on the falling edge of serial clock SCLK when SEN is active.

- Serial shift of bits is enabled when SEN is low. SCLK shifts serial data at the falling edge.
- Minimum width of data stream for a valid loading is 16 clocks.
- Data is loaded at every 16th SCLK falling edge while SEN is low.
- In case the word length exceeds a multiple of 16 bits, the excess bits are ignored.
- Data can be loaded in multiples of 16-bit words within a single active SEN pulse.
- The first 4-bit nibble is the address of the register while the last 12 bits are the register contents.

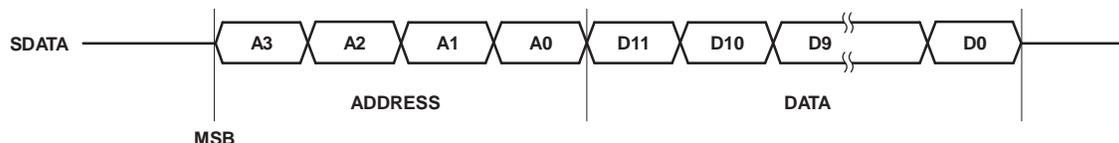


Figure 3. DATA Communication is 2-Byte, MSB First

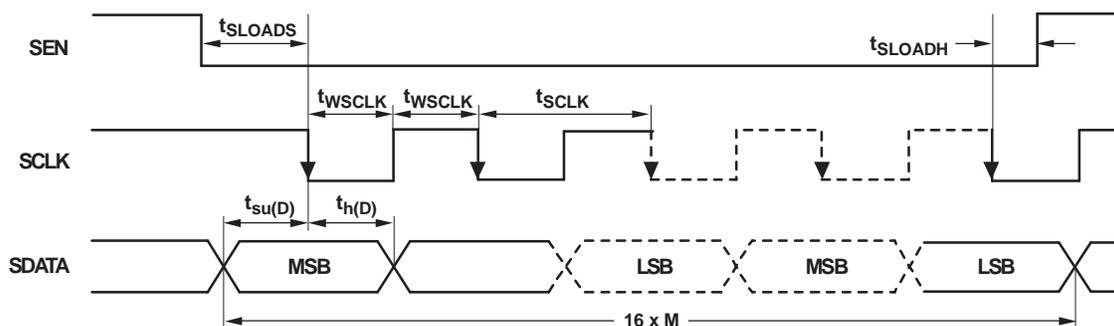


Figure 4. Serial Programming Interface Timing Diagram

Table 2. Serial Programming Interface Timing Characteristics

| SYMBOL | PARAMETER | MIN ⁽¹⁾ | TYP ⁽¹⁾ | MAX ⁽¹⁾ | UNIT |
|--------------|------------------------|--------------------|--------------------|--------------------|------|
| t_{SCLK} | SCLK period | 50 | | | ns |
| t_{WSCLK} | SCLK duty cycle | 25% | 50% | 75% | |
| t_{SLOADS} | SEN to SCLK setup time | 8 | | | ns |
| t_{SLOADH} | SCLK to SEN hold time | 6 | | | ns |
| t_{DS} | Data setup time | 8 | | | ns |
| t_{DH} | Data hold time | 6 | | | ns |

(1) Typ, min, and max values are characterized, but not production tested.

Table 3. Serial Register Table⁽¹⁾

| A3 | A2 | A1 | A0 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | DESCRIPTION | |
|----|----|----|----|-----|-----|----|----|----|----|----|----|----|----|----|--------------------|---|------------------|
| | | | | | | | | | | | | | | | DLL CTRL | Clock DLL | |
| 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Internal DLL is on; recommended for 60 MSPS to 125 MSPS clock speeds. | |
| 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | Internal DLL is off; recommended for 2 MSPS to 80 MSPS clock speeds. | |
| | | | | | | | | | | | | | | | TP<1> | TP<0> | Test Mode |
| 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | Normal mode of operation | |
| 1 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | All outputs forced to 0 | |
| 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | All outputs forced to 1 | |
| 1 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | Each output bit toggles between 0 and 1. ⁽²⁾⁽³⁾ | |
| | | | | | | | | | | | | | | | PDN | Power Down | |
| 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | Normal mode of operation | |
| 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | Device is put in power-down (low-current) mode. | |

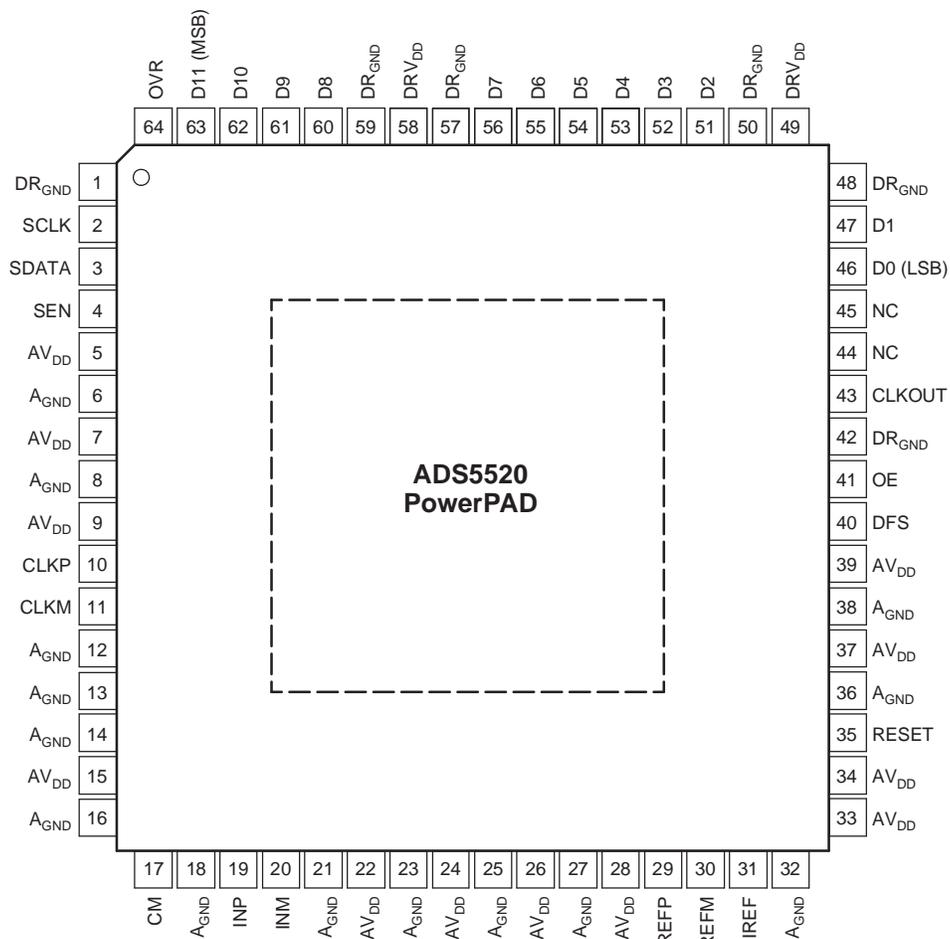
- (1) The register contents default to the appropriate setting for normal operation up on RESET.
- (2) The patterns given are applicable to the straight offset binary output format. If 2's complement output format is selected, the test mode outputs will be the binary two's complement equivalent of these patterns as described in the *Output Information* section.
- (3) While each bit toggles between 1 and 0 in this mode, there is no assured phase relationship between the data bits D0 through D13. For example, when D0 is a 1, D1 is not assured to be a 0, and vice versa.

Table 4. Data Format Select (DFS) Table

| DFS-PIN VOLTAGE (V _{DFS}) | DATA FORMAT | CLOCK OUTPUT POLARITY |
|---|-----------------|----------------------------|
| $V_{DFS} < \frac{2}{12} \times AV_{DD}$ | Straight Binary | Data valid on rising edge |
| $\frac{4}{12} \times AV_{DD} < V_{DFS} < \frac{5}{12} \times AV_{DD}$ | 2's complement | Data valid on rising edge |
| $\frac{7}{12} \times AV_{DD} < V_{DFS} < \frac{8}{12} \times AV_{DD}$ | Straight Binary | Data valid on falling edge |
| $V_{DFS} > \frac{10}{12} \times AV_{DD}$ | 2's complement | Data valid on falling edge |

PIN CONFIGURATION

**PAP PACKAGE
HTQFP-64
(TOP VIEW)**



PIN ASSIGNMENTS⁽¹⁾

| TERMINAL | | NO. OF PINS | I/O | DESCRIPTION |
|-----------------------|--|-------------|-----|---|
| NAME | NO. | | | |
| AV _{DD} | 5, 7, 9, 15, 22, 24, 26, 28, 33, 34, 37, 39 | 12 | I | Analog power supply |
| A _{GND} | 6, 8, 12, 13, 14, 16, 18, 21, 23, 25, 27, 32, 36, 38 | 14 | I | Analog ground |
| DRV _{DD} | 49, 58 | 2 | I | Output driver power supply |
| DR _{GND} | 1, 42, 48, 50, 57, 59 | 6 | I | Output driver ground |
| NC | 44, 45 | 2 | — | Not connected |
| INP | 19 | 1 | I | Differential analog input (positive) |
| INM | 20 | 1 | I | Differential analog input (negative) |
| REFP | 29 | 1 | O | Reference voltage (positive); 1- μ F capacitor in series with a 1- Ω resistor to GND |
| REFM | 30 | 1 | O | Reference voltage (negative); 1- μ F capacitor in series with a 1- Ω resistor to GND |
| IREF | 31 | 1 | I | Current set; 56-k Ω resistor to GND; do not connect capacitors |
| CM | 17 | 1 | O | Common-mode output voltage |
| RESET | 35 | 1 | I | Reset (active high), Internal 200-k Ω resistor to AV _{DD} ⁽²⁾ |
| OE | 41 | 1 | I | Output enable (active high) ⁽³⁾ |
| DFS | 40 | 1 | I | Data format and clock out polarity select ⁽⁴⁾⁽³⁾ |
| CLKP | 10 | 1 | I | Data converter differential input clock (positive) |
| CLKM | 11 | 1 | I | Data converter differential input clock (negative) |
| SEN | 4 | 1 | I | Serial interface chip select ⁽³⁾ |
| SDATA | 3 | 1 | I | Serial interface data ⁽³⁾ |
| SCLK | 2 | 1 | I | Serial interface clock ⁽³⁾ |
| D0 (LSB) to D11 (MSB) | 46, 47, 51-56, 60-63 | 14 | O | Parallel data output |
| OVR | 64 | 1 | O | Over-range indicator bit |
| CLKOUT | 43 | 1 | O | CMOS clock out in sync with data |

(1) PowerPAD is connected to analog ground.

(2) If RESET pin is unused, it must be tied to AGND and serial interface should be used to reset the device. See the serial programming interface section for details.

(3) Pins OE, DFS, SEN, SDATA, and SCLK have internal clamping diodes to the DRVDD supply. Any external circuit driving these pins must also run off the same supply voltage as DRVDD.

(4) [Table 4](#) defines the voltage levels for each mode selectable via the DFS pin.

DEFINITION OF SPECIFICATIONS

Analog Bandwidth

The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

Aperture Delay

The delay in time between the falling edge of the input sampling clock and the actual time at which the sampling occurs.

Aperture Uncertainty (Jitter)

The sample-to-sample variation in aperture delay.

Clock Pulse Width/Duty Cycle

The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine wave clock results in a 50% duty cycle.

Maximum Conversion Rate

The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

Minimum Conversion Rate

The minimum sampling rate at which the ADC functions.

Differential Nonlinearity (DNL)

An ideal ADC exhibits code transitions at analog input values spaced exactly 1LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

Integral Nonlinearity (INL)

The INL is the deviation of the ADC's transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.

Gain Error

The gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range. Gain error does not account for variations in the internal reference voltages (see the *Electrical Specifications* section for limits on the variation of V_{REFP} and V_{REFM}).

Offset Error

The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV.

Temperature Drift

The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from T_{MIN} to T_{MAX} . It is calculated by dividing the maximum deviation of the parameter across the T_{MIN} to T_{MAX} range by the difference ($T_{MAX} - T_{MIN}$).

Signal-to-Noise Ratio (SNR)

SNR is the ratio of the power of the fundamental (P_S) to the noise floor power (P_N), excluding the power at dc and the first eight harmonics.

$$SNR = 10\text{Log}_{10} \frac{P_S}{P_N}$$

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference or dBFS (dB to Full-Scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

Signal-to-Noise and Distortion (SINAD)

SINAD is the ratio of the power of the fundamental (P_S) to the power of all the other spectral components including noise (P_N) and distortion (P_D), but excluding dc.

$$SINAD = 10\text{Log}_{10} \frac{P_S}{P_N + P_D}$$

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

Effective Number of Bits (ENOB)

The ENOB is a measure of a converter's performance as compared to the theoretical limit based on quantization noise.

$$ENOB = \frac{SINAD - 1.76}{6.02}$$

Total Harmonic Distortion (THD)

THD is the ratio of the power of the fundamental (P_S) to the power of the first eight harmonics (P_D).

$$\text{THD} = 10\text{Log}_{10} \frac{P_S}{P_D}$$

THD is typically given in units of dBc (dB to carrier).

Spurious-Free Dynamic Range (SFDR)

The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).

Two-Tone Intermodulation Distortion (IMD3)

IMD3 is the ratio of the power of the fundamental (at frequencies f_1 and f_2) to the power of the worst spectral component at either frequency $2f_1 - f_2$ or $2f_2 - f_1$. IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to Full-Scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

DC Power Supply Rejection Ration (DC PSRR)

The DC PSRR is the ratio of the change in offset error to a change in analog supply voltage. The DC PSRR is typically given in units of mV/V.

Reference Error

The reference error is the variation of the actual reference voltage ($V_{REFP} - V_{REFM}$) from its ideal value. The reference error is typically given as a percentage.

Voltage Overload Recovery Time

The voltage overload recovery time is defined as the time required for the ADC to recover to within 1% of the full-scale range in response to an input voltage overload of 10% beyond the full-scale range.

TYPICAL CHARACTERISTICS

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS, sampling rate = 125 MSPS, DLL On, and 3-V differential clock, unless otherwise noted

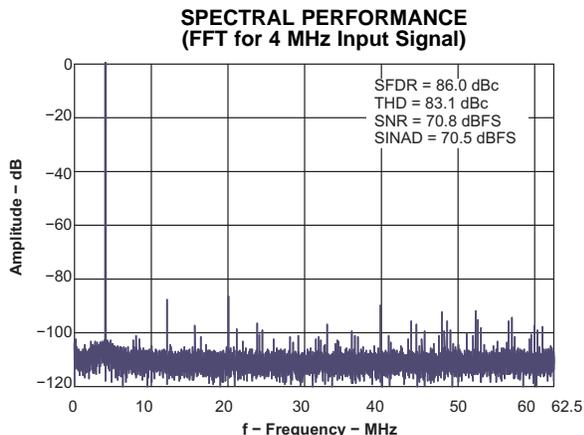


Figure 5.

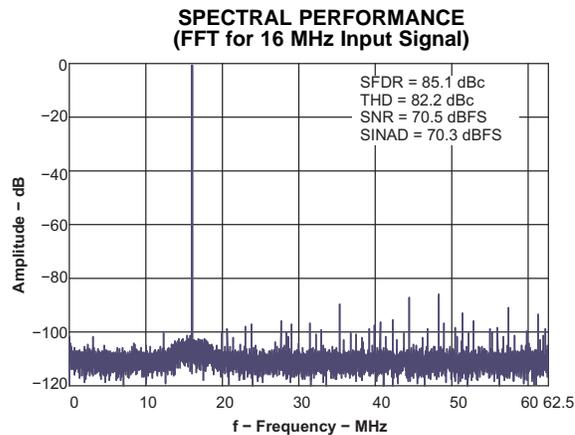


Figure 6.

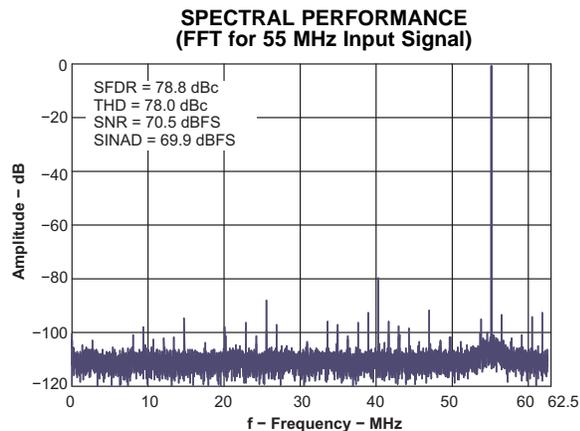


Figure 7.

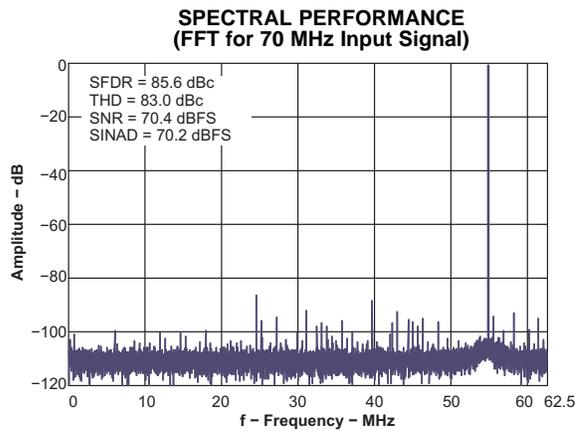


Figure 8.

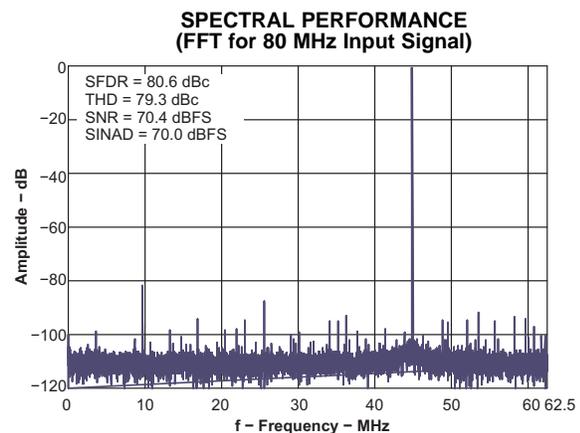


Figure 9.

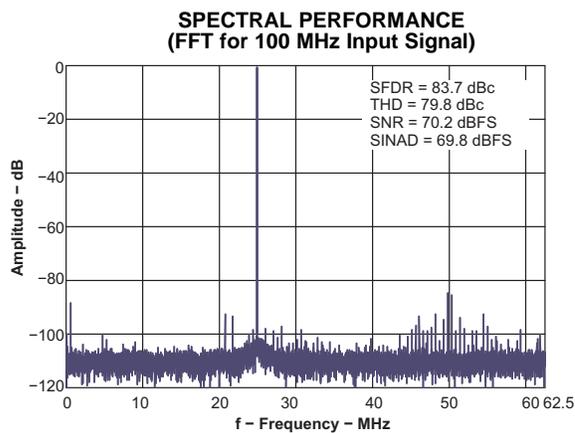


Figure 10.

TYPICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1 dBFS , sampling rate = 125 MSPS , DLL On, and 3-V differential clock, unless otherwise noted

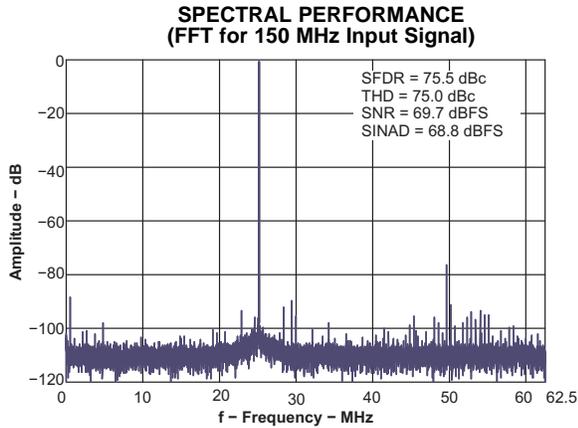


Figure 11.

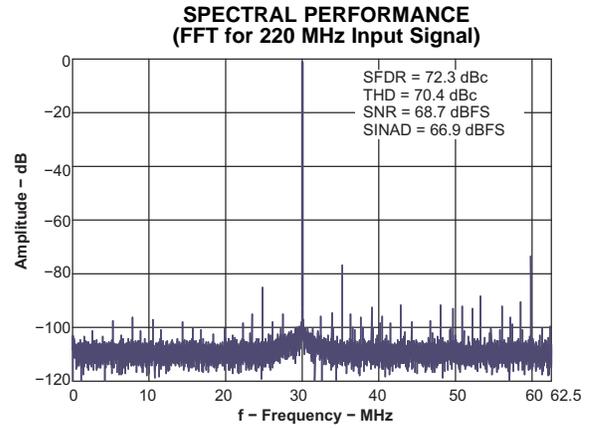


Figure 12.

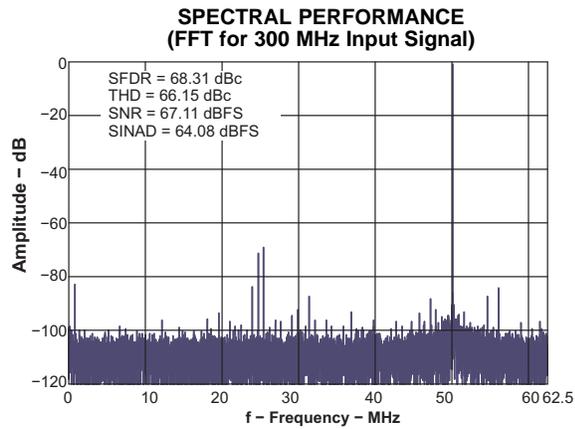


Figure 13.

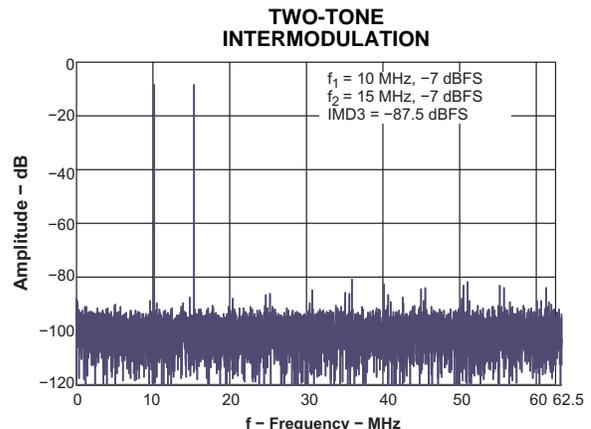


Figure 14.

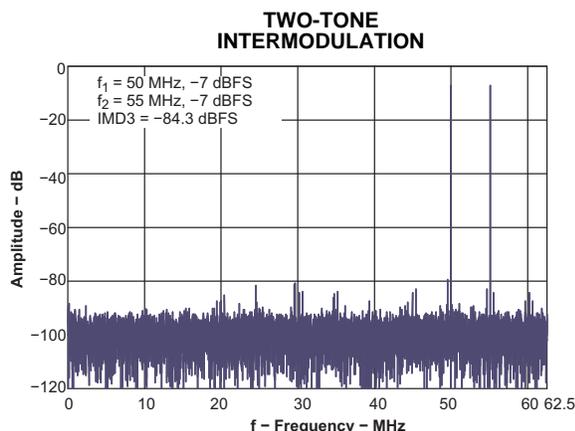


Figure 15.

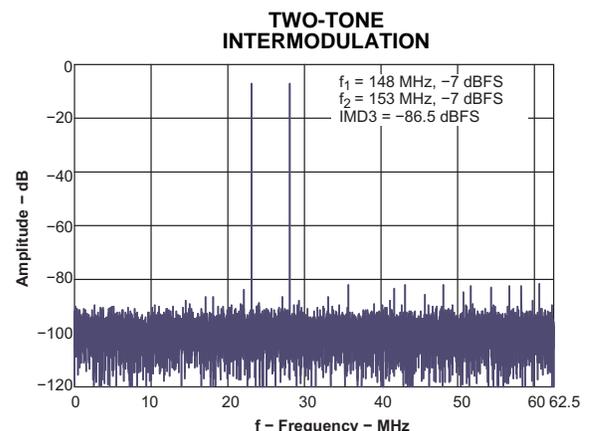


Figure 16.

TYPICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS, sampling rate = 125 MSPS, DLL On, and 3-V differential clock, unless otherwise noted

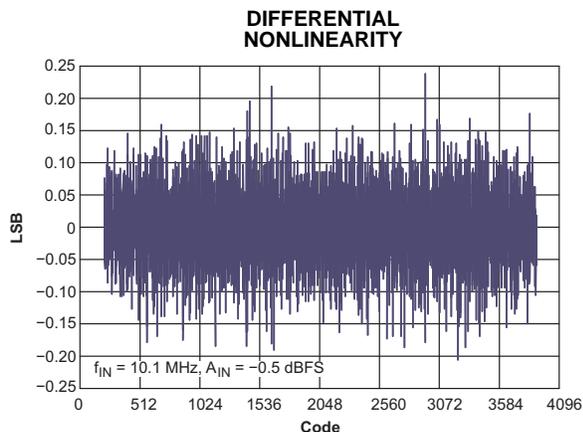


Figure 17.

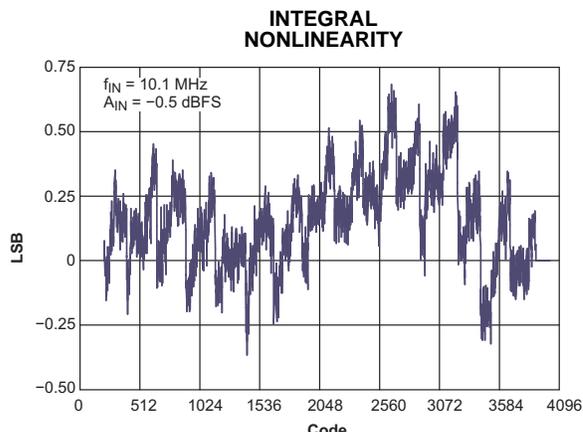


Figure 18.

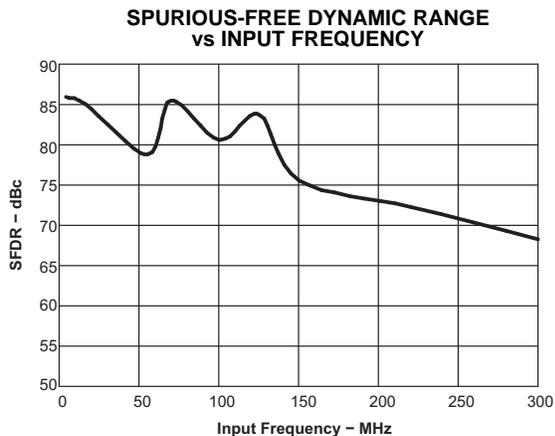


Figure 19.

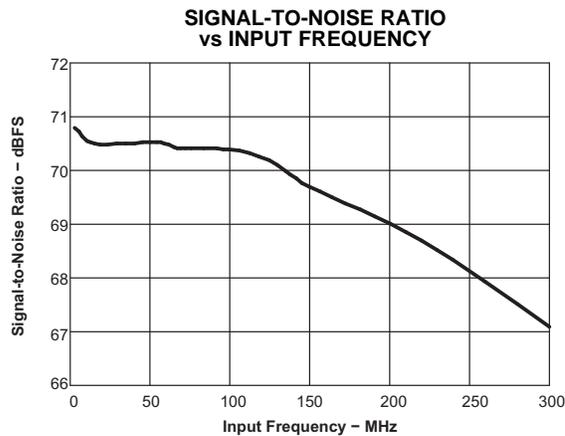


Figure 20.

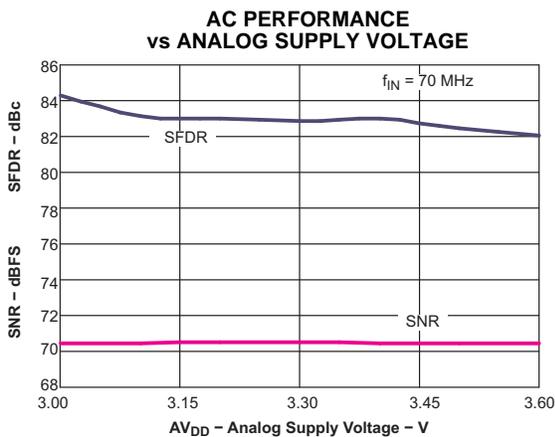


Figure 21.

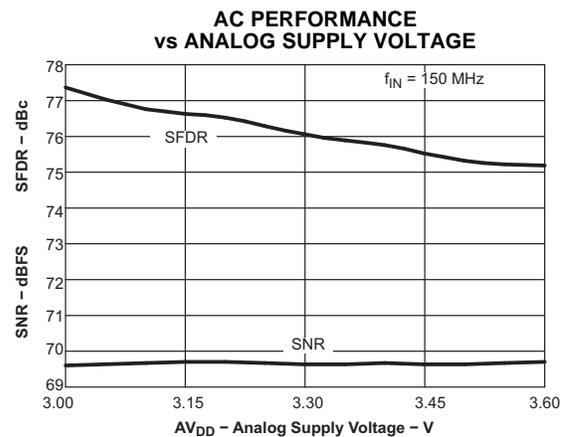


Figure 22.

TYPICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS, sampling rate = 125 MSPS, DLL On, and 3-V differential clock, unless otherwise noted

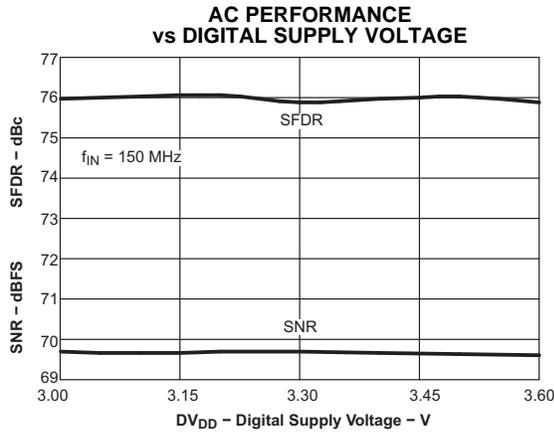


Figure 23.

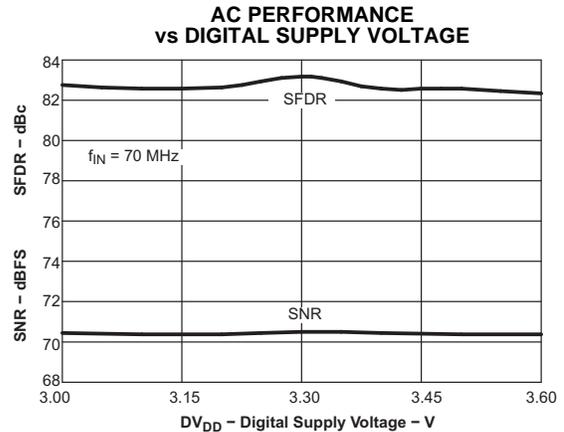


Figure 24.

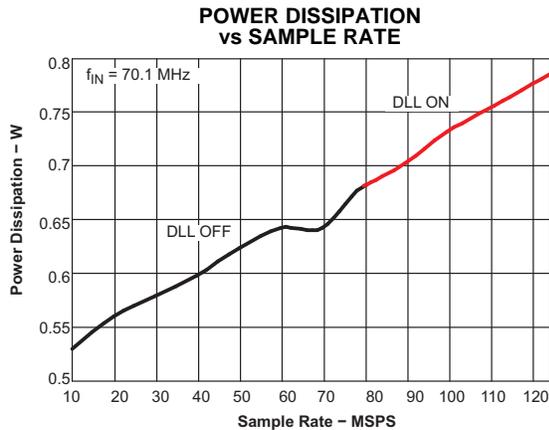


Figure 25.

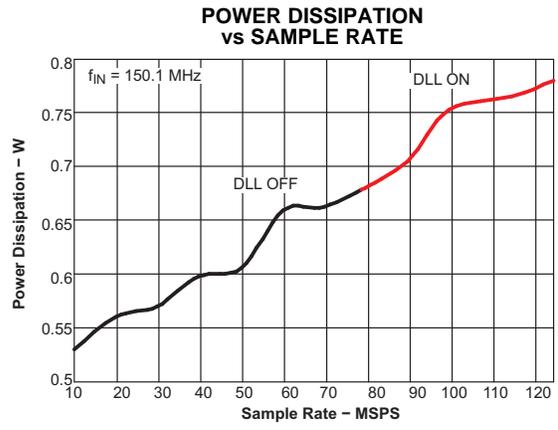


Figure 26.

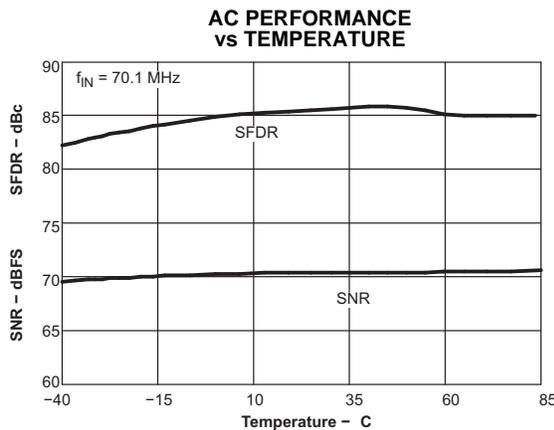


Figure 27.

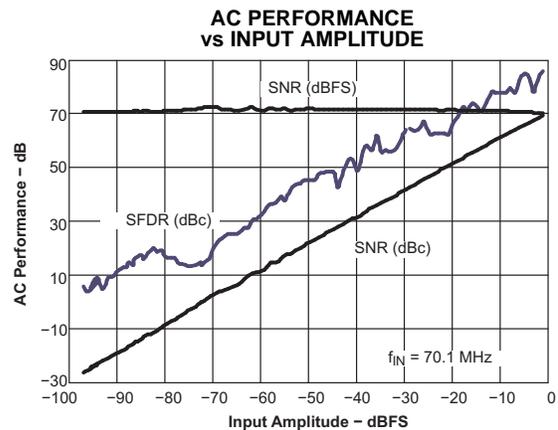


Figure 28.

TYPICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS, sampling rate = 125 MSPS, DLL On, and 3-V differential clock, unless otherwise noted

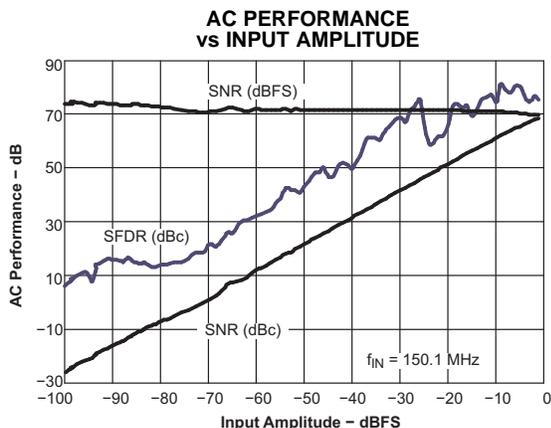


Figure 29.

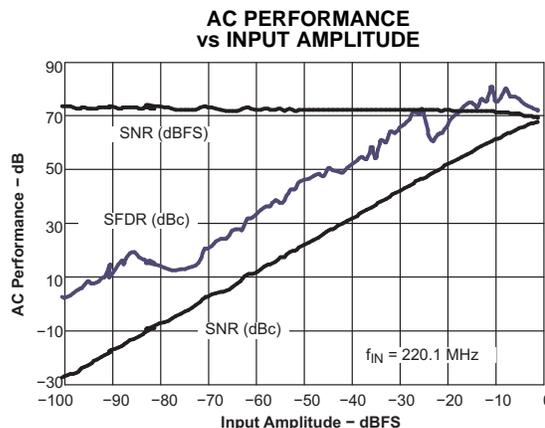


Figure 30.

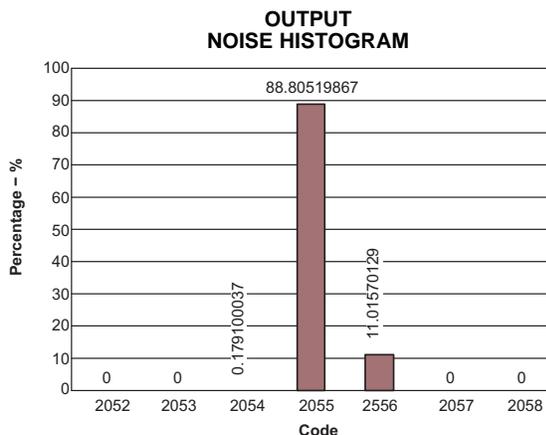


Figure 31.

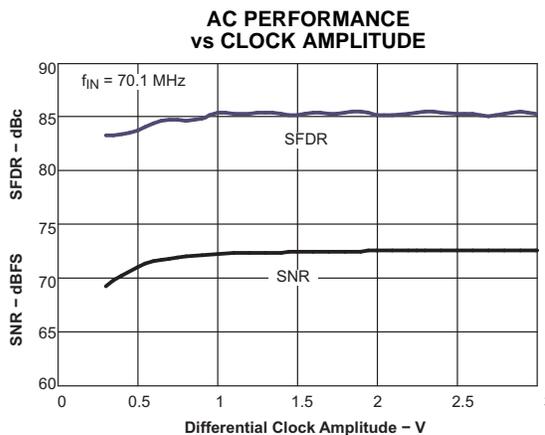


Figure 32.

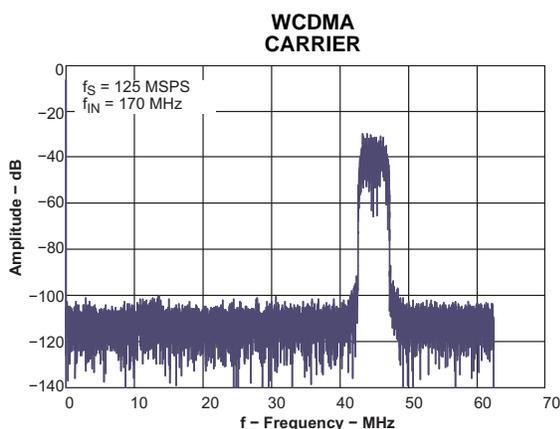


Figure 33.

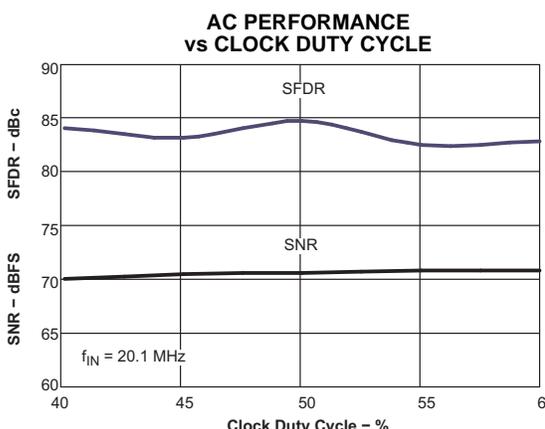


Figure 34.

TYPICAL CHARACTERISTICS

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS, and 3-V differential clock, unless otherwise noted

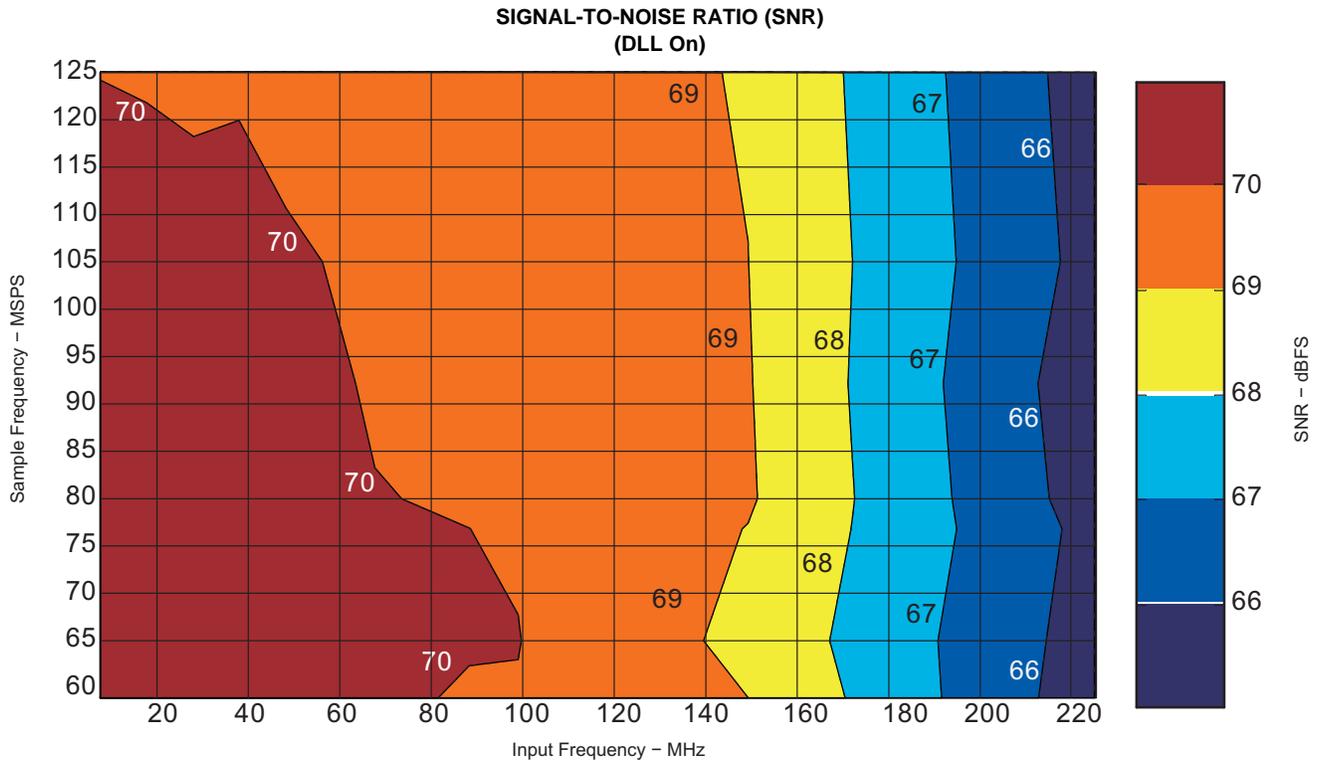


Figure 35.

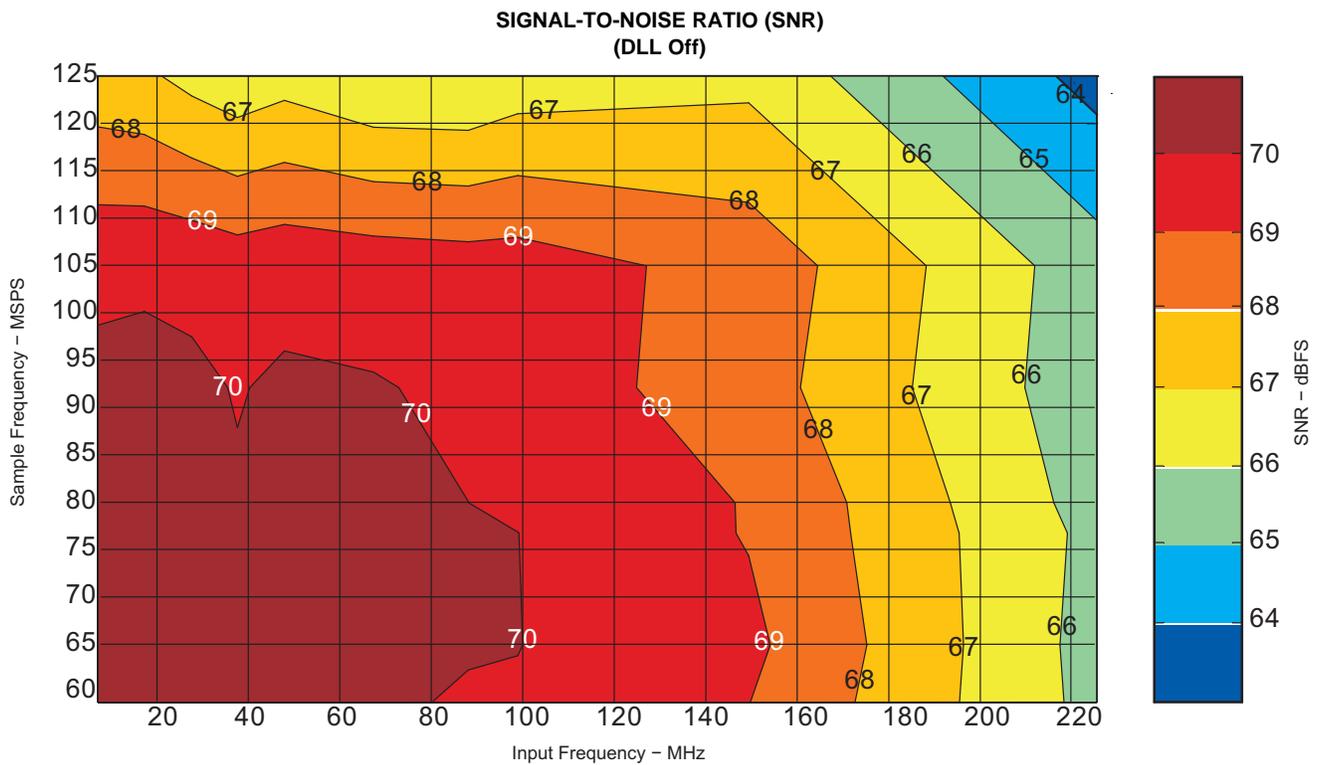
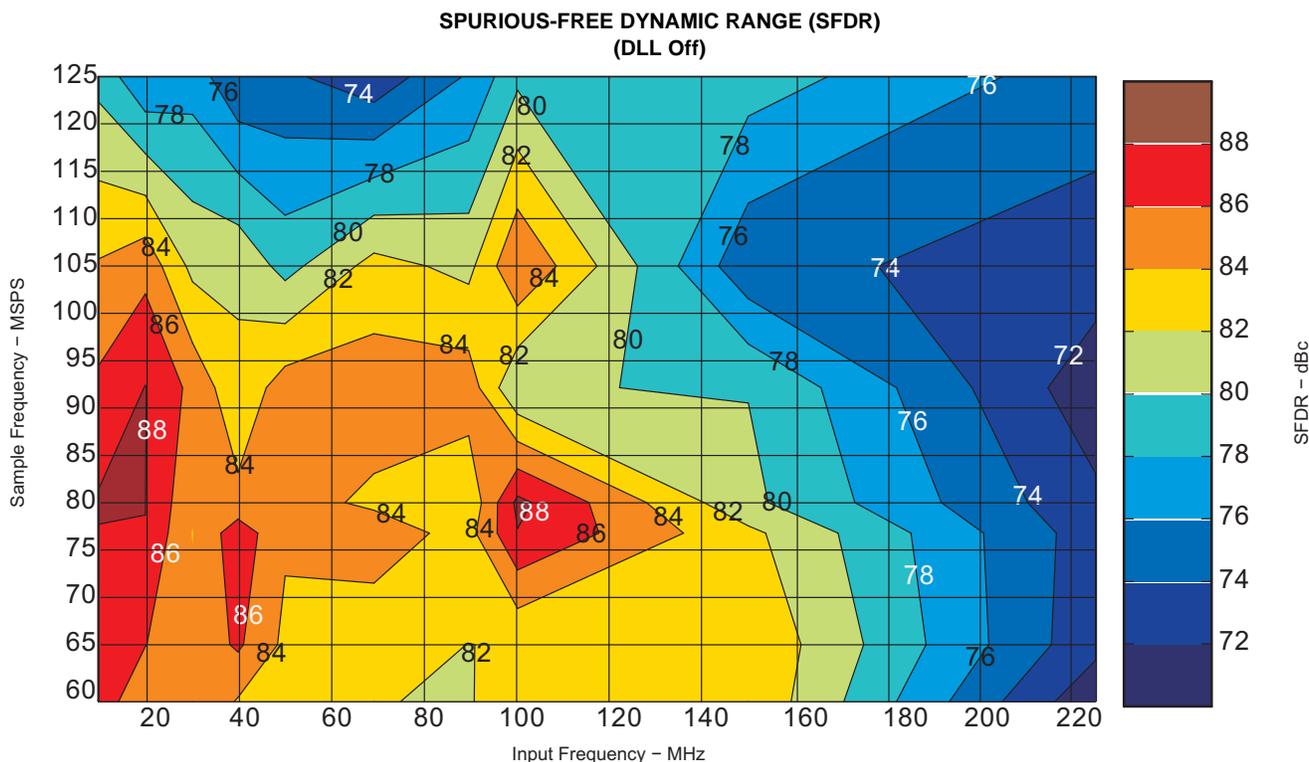
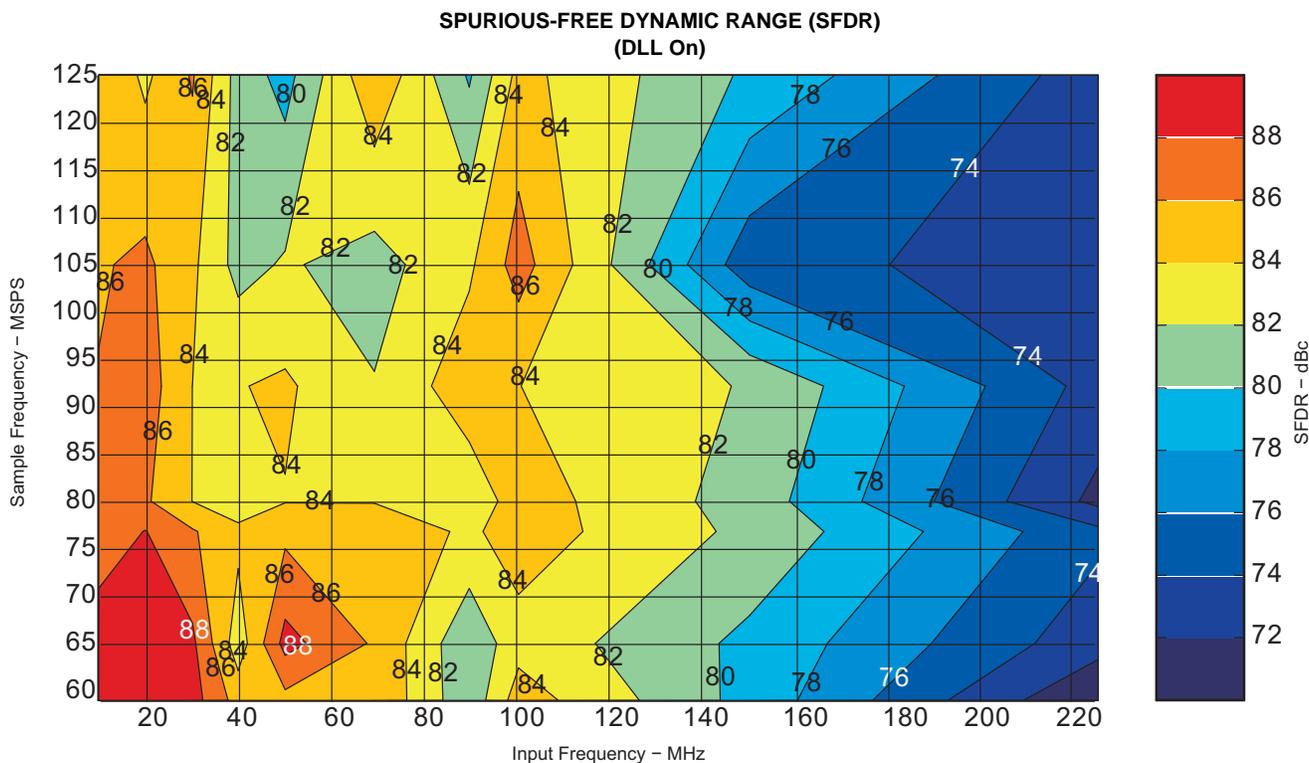


Figure 36.

TYPICAL CHARACTERISTICS (continued)

Typical values given at $T_A = 25^\circ\text{C}$, $AV_{DD} = DRV_{DD} = 3.3\text{ V}$, differential input amplitude = -1dBFS , and 3-V differential clock, unless otherwise noted



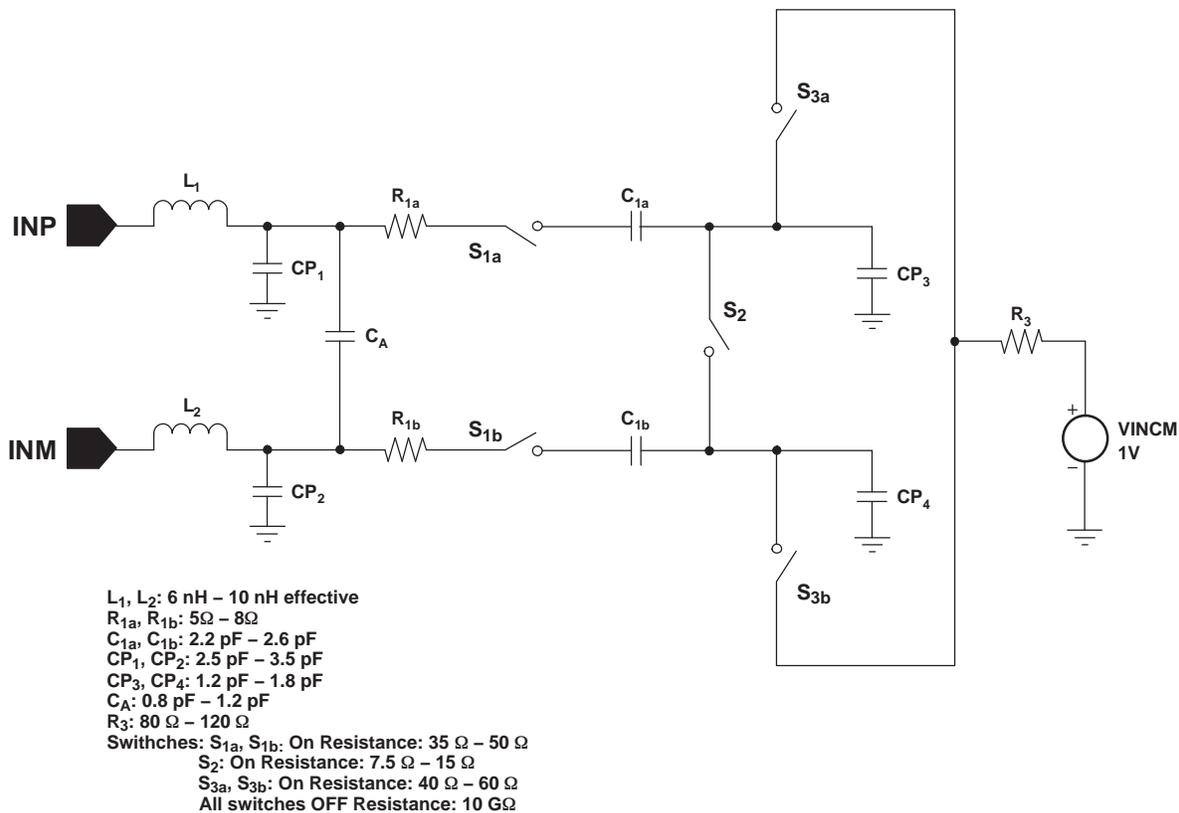
APPLICATION INFORMATION

THEORY OF OPERATION

The ADS5520 is a low-power, 12-Bit, 125 MSPS, CMOS, switched capacitor, pipeline ADC that operates from a single 3.3-V supply. The conversion process is initiated by a falling edge of the external input clock. Once the signal is captured by the input S&H, the input sample is sequentially converted by a series of small resolution stages, with the outputs combined in a digital correction logic block. Both the rising and the falling clock edges are used to propagate the sample through the pipeline every half clock cycle. This process results in a data latency of 17.5 clock cycles, after which the output data is available as a 12-bit parallel word, coded in either straight offset binary or binary 2's complement format.

INPUT CONFIGURATION

The analog input for the ADS5520 consists of a differential sample-and-hold architecture implemented using the switched capacitor technique shown in [Figure 39](#).



- A. All Switches are ON in sampling phase which is approximately one half of a clock period.

Figure 39. Analog Input Stage

This differential input topology produces a high level of ac-performance for high sampling rates. It also results in a very high usable input bandwidth, especially important for high intermediate-frequency (IF) or undersampling applications. The ADS5520 requires each of the analog inputs (INP, INM) to be externally biased around the common-mode level of the internal circuitry (CM, pin 17). For a full-scale differential input, each of the differential lines of the input signal (pins 19 and 20) swings symmetrically between $CM + 0.575\text{ V}$ and $CM - 0.575\text{ V}$. This means that each input is driven with a signal of up to $CM \pm 0.575\text{ V}$, so that each input has a maximum differential signal of 1.15 V_{PP} for a total differential input signal swing of 2.3 V_{PP} . The maximum swing is determined by the two reference voltages, the top reference (REFP, pin 29), and the bottom reference (REFM, pin 30).

The ADS5520 obtains optimum performance when the analog inputs are driven differentially. The circuit shown in [Figure 40](#) illustrates one possible configuration using an RF transformer.

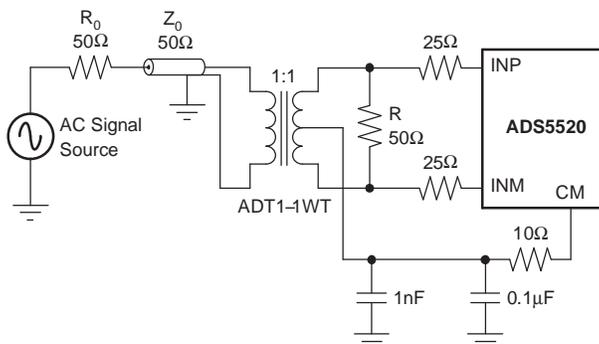


Figure 40. Transformer Input to Convert Single-Ended Signal to Differential Signal

The single-ended signal is fed to the primary winding of an RF transformer. Placing a $25\text{-}\Omega$ resistor in series with INP and INM is recommended to dampen ringing due to ADC kickback.

Since the input signal must be biased around the common-mode voltage of the internal circuitry, the common-mode voltage (V_{CM}) from the ADS5520 is connected to the center-tap of the secondary winding.

To ensure a steady low-noise V_{CM} reference, best performance is attained when the CM output (pin 17) is filtered to ground with a $10\text{-}\Omega$ series resistor and parallel $0.1\text{-}\mu\text{F}$ and $0.001\text{-}\mu\text{F}$ low-inductance capacitors, as illustrated in [Figure 39](#).

Output V_{CM} (pin 17) is designed to directly drive the ADC input. When providing a custom CM level, be aware that the input structure of the ADC sinks a common-mode current in the order of $600\text{ }\mu\text{A}$ ($300\text{ }\mu\text{A}$ per input). [Equation 1](#) describes the dependency of the common-mode current and the sampling frequency:

$$\frac{600\mu\text{A} \times f_s \text{ (in MSPS)}}{125 \text{ MSPS}} \quad (1)$$

Where:

$$f_s > 2\text{MSPS.}$$

This equation helps to design the output capability and impedance of the driving circuit accordingly.

When it is necessary to buffer or apply a gain to the incoming analog signal, it is possible to combine single-ended operational amplifiers with an RF transformer, or to use a differential input/output amplifier without a transformer, to drive the input of the ADS5520. Texas Instruments offers a wide selection of single-ended operational amplifiers (including the THS3201, THS3202, OPA695, and OPA847) that can be selected depending on the application. An RF gain block amplifier, such as Texas Instruments THS9001, can also be used with an RF transformer for high input frequency applications. The THS4503 is a recommended differential input/output amplifier. [Table 5](#) lists the recommended amplifiers.

Table 5. Recommended Amplifiers to Drive the Input of the ADS5520

| INPUT SIGNAL FREQUENCY | RECOMMENDED AMPLIFIER | TYPE OF AMPLIFIER | USE WITH TRANSFORMER? |
|------------------------|-----------------------|-------------------------|-----------------------|
| DC to 20 MHz | THS4503 | Differential In/Out Amp | No |
| DC to 50 MHz | OPA847 | Operational Amp | Yes |
| DC to 100 MHz | THS4509 | Differential In/Out Amp | No |
| 10 MHz to 120 MHz | OPA695 | Operational Amp | Yes |
| | THS3201 | Operational Amp | Yes |
| | THS3202 | Operational Amp | Yes |
| Over 100 MHz | THS9001 | RF Gain Block | Yes |

When using single-ended operational amplifiers (such as the THS3201, THS3202, OPA695, or OPA847) to provide gain, a three-amplifier circuit is recommended with one amplifier driving the primary of an RF transformer and one amplifier in each of the legs of the secondary driving the two differential inputs of the ADS5520. These three amplifier circuits minimize even-order harmonics. For high frequency inputs, an RF gain block amplifier can be used to drive a transformer primary; in this case, the transformer secondary connections can drive the input of the ADS5520 directly, as shown in Figure 40, or with the addition of the filter circuit shown in Figure 41.

Figure 41 illustrates how R_{IN} and C_{IN} can be placed to isolate the signal source from the switching inputs of the ADC and to implement a low-pass RC filter to limit the input noise in the ADC. It is recommended that these components be included in the ADS5520 circuit layout when any of the amplifier circuits discussed previously are used. The components allow fine-tuning of the circuit performance. Any mismatch between the differential lines of the ADS5520 input produces a degradation in performance at high input frequencies, mainly characterized by an increase in the even-order harmonics. In this case, special care should be taken to keep as much electrical symmetry as possible between both inputs.

Another possible configuration for lower-frequency signals is the use of differential input/output amplifiers that can simplify the driver circuit for applications requiring dc-coupling of the input. Flexible in their configurations (see Figure 42), such amplifiers can be used for single-ended-to-differential conversion signal amplification.

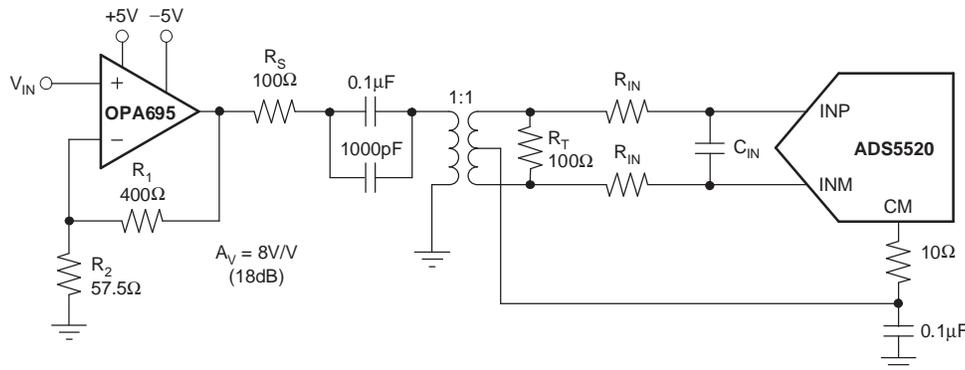
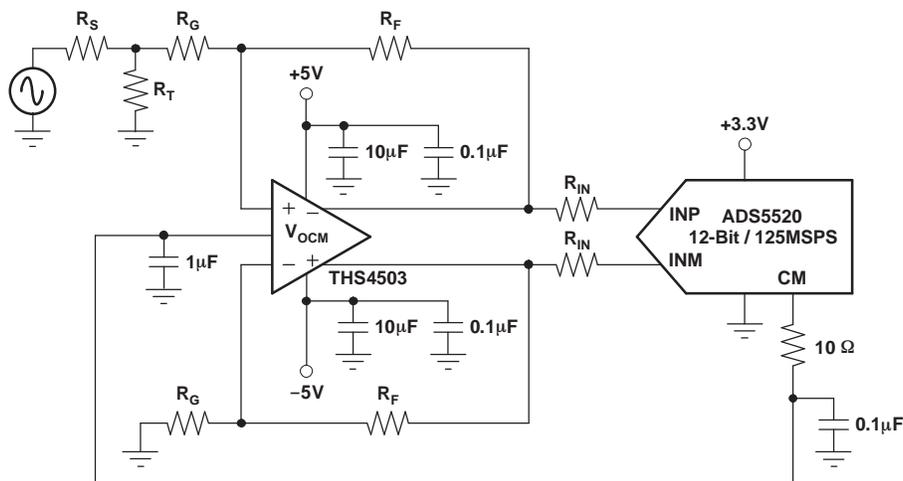
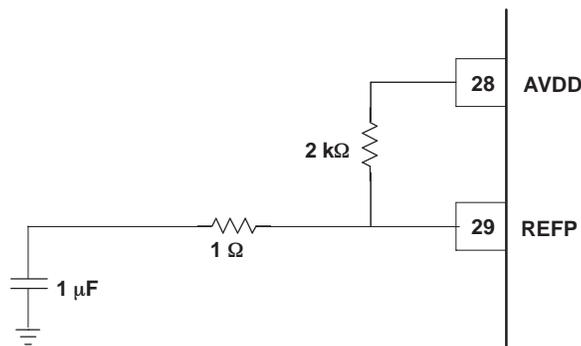


Figure 41. Converting a Single-Ended Input Signal to a Differential Signal Using an RF Transformer


Figure 42. Using the THS4503 with the ADS5520

POWER-SUPPLY SEQUENCE

The preferred power-up sequence is to ramp AV_{DD} first, followed by DRV_{DD} , including a simultaneous ramp of AV_{DD} and DRV_{DD} . In the event that DRV_{DD} ramps up first in the system, care must be taken to ensure that AV_{DD} ramps up within 10 ms. Optionally, it is recommended to put a 2-k Ω resistor from REFP (pin 29) to AV_{DD} as shown in [Figure 43](#). This helps to make the device more robust to power supply ramp-up timings.


Figure 43.

POWER-DOWN

The device enters power-down in one of two ways: either by reducing the clock speed or by setting the PDN bit through the serial programming interface. Using the reduced clock speed, power-down may be initiated for clock frequency below 2 MSPS. The exact frequency at which the power down occurs varies from device to device.

Using the serial interface PDN bit to power down the device places the outputs in a high-impedance state and only the internal reference remains on to reduce the power-up time. The power-down mode reduces power dissipation to approximately 180 mW.

REFERENCE CIRCUIT

The ADS5520 has built-in internal reference generation, requiring no external circuitry on the printed circuit board (PCB). For optimum performance, it is best to connect both REFP and REFM to ground with a 1- μ F decoupling capacitor (the 1- Ω resistor shown in [Figure 44](#) is optional). In addition, an external 56.2-k Ω resistor should be connected from IREF (pin 31) to AGND to set the proper current for the operation of the ADC, as shown in [Figure 44](#). No capacitor should be connected between pin 31 and ground; only the 56.2-k Ω resistor should be used.

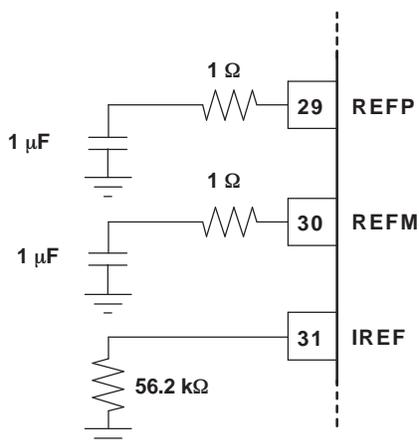


Figure 44. REFP, REFM, and IREF Connections for Optimum Performance

CLOCK INPUT

The ADS5520 clock input can be driven with either a differential clock signal or a single-ended clock input, with little or no difference in performance between both configurations. The common-mode voltage of the clock inputs is set internally to CM (pin 17) using internal 5-kΩ resistors that connect CLKP (pin 10) and CLKM (pin 11) to CM (pin 17), as shown in Figure 45.

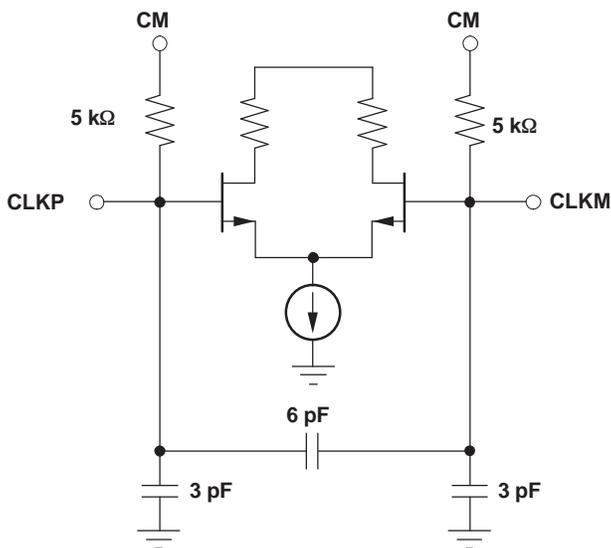


Figure 45. Clock Inputs

When driven with a single-ended CMOS clock input, it is best to connect CLKM (pin 11) to ground with a 0.01-μF capacitor, while CLKP is ac-coupled with a 0.01-μF capacitor to the clock source, as shown in Figure 46.

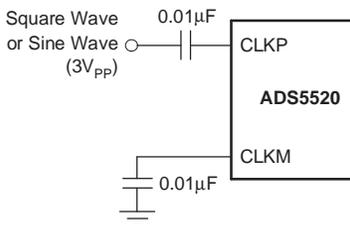


Figure 46. AC-Coupled, Single-Ended Clock Input

The ADS5520 clock input can also be driven differentially, reducing susceptibility to common-mode noise. In this case, it is best to connect both clock inputs to the differential input clock signal with 0.01-µF capacitors, as shown in Figure 47.

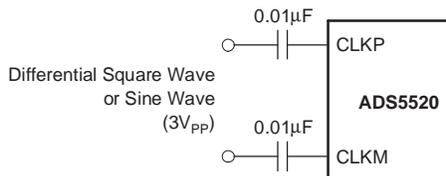


Figure 47. AC-Coupled, Differential Clock Input

For high input frequency sampling, it is recommended to use a clock source with low jitter. Additionally, the internal ADC core uses both edges of the clock for the conversion process. This means that, ideally, a 50% duty cycle should be provided. Figure 48 shows the performance variation of the ADC versus clock duty cycle.

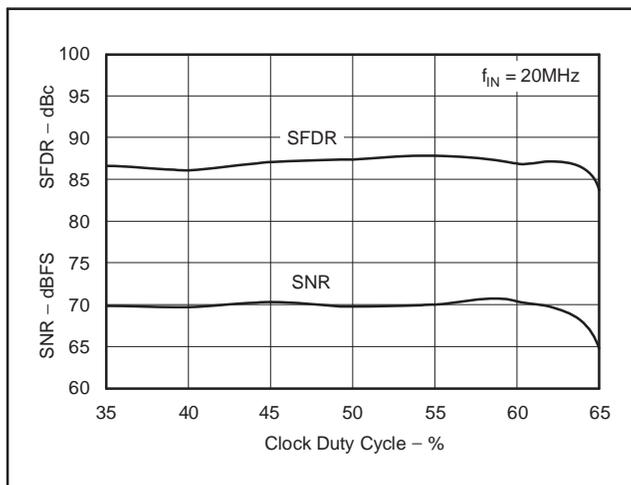


Figure 48. AC Performance vs Clock Duty Cycle

Bandpass filtering of the source can help produce a 50% duty cycle clock and reduce the effect of jitter. When using a sinusoidal clock, the clock jitter further improves as the amplitude is increased. In that sense, using a differential clock allows for the use of larger amplitudes without exceeding the supply rails and absolute maximum ratings of the ADC clock input. Figure 49 shows the performance variation of the device versus input clock amplitude. For detailed clocking schemes based on transformer or PECL-level clocks, see the ADS55xxEVM User's Guide (SLWU010), available for download from www.ti.com.

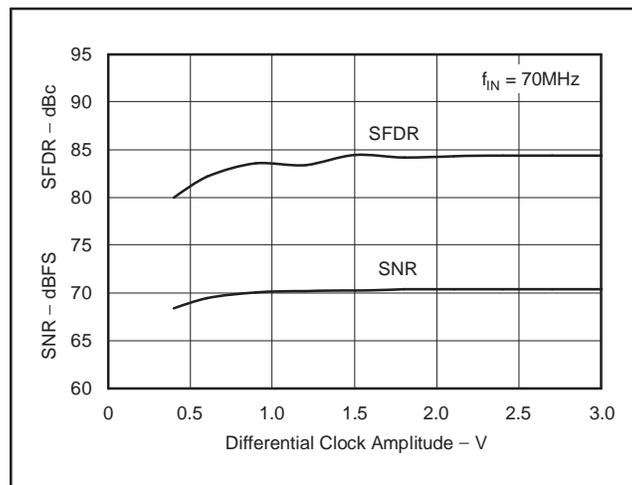


Figure 49. AC Performance vs Clock Amplitude

INTERNAL DLL

In order to obtain the fastest sampling rates achievable with the ADS5520, the device uses an internal digital delay lock loop (DLL). Nevertheless, the limited frequency range of operation of DLL degrades the performance at clock frequencies below 60 MSPS. In order to operate the device below 60 MSPS, the internal DLL must be shut off using the DLL OFF mode described in the *Serial Interface Programming* section. The *Typical Performance Curves* show the performance obtained in both modes of operation: DLL ON (default) and DLL OFF. In either of the two modes, the device enters power-down mode if no clock or slow clock is provided. The limit of the clock frequency where the device functions properly with default settings is ensured to be over 2 MHz.

OUTPUT INFORMATION

The ADC provides 12 data outputs (D11 to D0, with D11 being the MSB and D0 the LSB), a data-ready signal (CLKOUT, pin 43), and an out-of-range indicator (OVR, pin 64) that equals 1 when the output reaches the full-scale limits.

Two different output formats (straight offset binary or 2's complement) and two different output clock polarities (latching output data on rising or falling edge of the output clock) can be selected by setting DFS (pin 40) to one of four different voltages. [Table 4](#) details the four modes. In addition, output enable control (OE, pin 41, active high) is provided to put the outputs into a high-impedance state.

In the event of an input voltage overdrive, the digital outputs go to the appropriate full-scale level. For a positive overdrive, the output code is 0xFFFF in straight offset binary output format and 0x7FF in 2's complement output format. For a negative input overdrive, the output code is 0x000 in straight offset binary output format and 0x800 in 2's complement output format. These outputs to an overdrive signal are ensured through design and characterization.

The output circuitry of the ADS5520, by design, minimizes the noise produced by the data switching transients, and, in particular, its coupling to the ADC analog circuitry. Output D4 (pin 51) senses the load capacitance and adjusts the drive capability of all the output pins of the ADC to maintain the same output slew rate described in the timing diagram of [Figure 1](#). Care should be taken to ensure that all output lines (including CLKOUT) have nearly the same load as D4 (pin 51). This circuit also reduces the sensitivity of the output timing versus supply voltage or temperature. Placing external resistors in series with the outputs is **not** recommended.

The timing characteristics of the digital outputs change for sampling rates below the 125 MSPS maximum sampling frequency. [Table 6](#) and [Table 7](#) show the setup, hold, input clock to output data delays, and rise and fall times for different sampling frequencies with the DLL on and off, respectively.

[Table 8](#) and [Table 9](#) show the rise and fall times at additional sampling frequencies with DLL on and off, respectively.

To use the input clock as the data capture clock, it is necessary to delay the input clock by a delay, t_d , that results in the desired setup or hold time. Use either of the following equations to calculate the value of t_d .

$$\text{Desired setup time} = t_d - t_{\text{START}}$$

$$\text{Desired hold time} = t_{\text{END}} - t_d$$

Table 6. Timing Characteristics at Additional Sampling Frequencies (DLL ON)

| f_s (MSPS) | t_{SETUP} (ns) | | | t_{HOLD} (ns) | | | t_{START} (ns) | | | t_{END} (ns) | | | Data Rise time t_r (ns) | | | Data Fall time t_f (ns) | | |
|-----------------|-------------------------|-----|-----|------------------------|-----|-----|-------------------------|------|-----|-----------------------|-----|-----|------------------------------|-----|-----|------------------------------|-----|-----|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |
| 105 | 2.4 | 3.1 | | 2.2 | 2.6 | | | 1.7 | 2.6 | 5.8 | 7.3 | | | 4.4 | 5.1 | | 3.3 | 3.8 |
| 80 | 3.3 | 4.1 | | 3 | 3.4 | | | 0.3 | 1.5 | 5.3 | 8 | | | 5.8 | 6.6 | | 4.4 | 5.3 |
| 65 | 4.1 | 5 | | 3.7 | 4.2 | | | -0.8 | 0.4 | 5.3 | 8.7 | | | 6.7 | 7.2 | | 5.5 | 6.4 |

Table 7. Timing Characteristics at Additional Sampling Frequencies (DLL OFF)

| f_s (MSPS) | t_{SETUP} (ns) | | | t_{HOLD} (ns) | | | t_{START} (ns) | | | t_{END} (ns) | | | Data Rise time t_r (ns) | | | Data Fall time t_f (ns) | | |
|-----------------|-------------------------|------|-----|------------------------|-----|-----|-------------------------|------|-----|-----------------------|------|-----|------------------------------|-----|-----|------------------------------|-----|-----|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX |
| 80 | 3.6 | 4.7 | | 1.8 | 3.1 | | | 3.3 | 4.7 | 8.2 | 11.1 | | | 5.6 | 6.1 | | 4.4 | 5.1 |
| 65 | 4.7 | 6 | | 2.1 | 3.1 | | | 2.4 | 4.2 | 8.3 | 12 | | | 6.6 | 7.2 | | 5.5 | 6.4 |
| 40 | 8.5 | 11 | | 2.8 | 3.5 | | | -1 | 1.5 | 8.9 | 14.5 | | | 7.5 | 8 | | 7.3 | 7.8 |
| 20 | 17 | 25.7 | | 2.5 | 4.7 | | | -9.8 | 2 | 9.5 | 21.6 | | | 7.5 | 8 | | 7.6 | 8 |
| 10 | 27 | 51 | | 4 | 6.5 | | | -30 | -3 | 11.5 | 31 | | | | | | | |
| 2 | 284 | 370 | | 4 | 13 | | | 185 | 320 | 515 | 576 | | | 50 | 82 | | 75 | 150 |

Table 8. Timing Characteristics at Additional Sampling Frequencies (DLL ON)

| f_s (MSPS) | CLKOUT Rise Time t_r (ns) | | | CLKOUT Fall Time t_f (ns) | | | CLKOUT Jitter, Peak-to-Peak t_{JIT} (ps) | | | Input-to-Output Clock Delay t_{PDI} (ns) | | | | |
|-----------------|--------------------------------|-----|-----|--------------------------------|-----|-----|---|-----|-----|--|-----|-----|-----|-----|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| 105 | | 2 | 2.2 | | 1.7 | 1.8 | | | | 175 | 250 | 4 | 4.7 | 5.5 |
| 80 | | 2.5 | 2.8 | | 2.1 | 2.3 | | | | 210 | 315 | 3.7 | 4.3 | 5.1 |
| 65 | | 3.1 | 3.5 | | 2.6 | 2.9 | | | | 260 | 380 | 3.5 | 4.1 | 4.8 |

Table 9. Timing Characteristics at Additional Sampling Frequencies (DLL OFF)

| f_s (MSPS) | CLKOUT Rise Time t_r (ns) | | | CLKOUT Fall Time t_f (ns) | | | CLKOUT Jitter, Peak-to-Peak t_{JIT} (ps) | | | Input-to-Output Clock Delay t_{PDI} (ns) | | | | |
|-----------------|--------------------------------|-----|-----|--------------------------------|-----|-----|---|-----|-----|--|------|-----|------|------|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | | |
| 80 | | 2.5 | 2.8 | | 2.1 | 2.3 | | | | 210 | 315 | 7.1 | 8 | 8.9 |
| 65 | | 3.1 | 3.5 | | 2.6 | 2.9 | | | | 260 | 380 | 7.8 | 8.5 | 9.4 |
| 40 | | 4.8 | 5.3 | | 4 | 4.4 | | | | 445 | 650 | 9.5 | 10.4 | 11.4 |
| 20 | | 8.3 | 9.5 | | 7.6 | 8.2 | | | | 800 | 1200 | 13 | 15.5 | 18 |
| 10 | | | | | | | | | | | | 16 | 20.7 | 25.5 |
| 2 | | 31 | 52 | | 36 | 65 | | | | 2610 | 4400 | 537 | 551 | 567 |

SERIAL PROGRAMMING INTERFACE

The ADS5520 has internal registers for the programming of some of the modes described in the previous sections. The registers should be reset after power-up by applying a 2 μ s (minimum) high pulse on RESET (pin 35); this also resets the entire ADC and sets the data outputs to low. This pin has a 200-k Ω internal pullup resistor to AVDD. The programming is done through a three-wire interface. The timing diagram and serial register setting in the *Serial Programming Interface* section describe the programming of this register.

Table 3 shows the different modes and the bit values to be written to the register to enable them.

Note that some of these modes may modify the standard operation of the device and possibly vary the performance with respect to the typical data shown in this data sheet.

Applying a RESET signal is absolutely essential to set the internal registers to their default states for normal operation. If the hardware RESET function is not used in the system, the RESET pin must be tied to ground and it is necessary to write the default values to the internal registers through the serial programming interface. The registers must be written in the following order.

- Write 9000h (Address 9, Data 000)
- Write A000h (Address A, Data 000)
- Write B000h (Address B, Data 000)
- Write C000h (Address C, Data 000)
- Write D000h (Address D, Data 000)
- Write E000h (Address E, Data 804)
- Write 0000h (Address 0, Data 000)
- Write 1000h (Address 1, Data 000)
- Write F000h (Address F, Data 000)

NOTE:

This procedure is only required if a RESET pulse is not provided to the device.

PowerPAD PACKAGE

The PowerPAD package is a thermally enhanced standard size IC package designed to eliminate the use of bulky heatsinks and slugs traditionally used in thermal packages. This package can be easily mounted using standard printed circuit board (PCB) assembly techniques and can be removed and replaced using standard repair procedures.

The PowerPAD package is designed so that the lead frame die pad (or thermal pad) is exposed on the bottom of the IC. This provides a low thermal resistance path between the die and the exterior of the package. The thermal pad on the bottom of the IC can then be soldered directly to the printed circuit board (PCB), using the PCB as a heatsink.

Assembly Process

1. Prepare the PCB top-side etch pattern including etch for the leads as well as the thermal pad as illustrated in the *Mechanical Data* section. The recommended thermal pad dimension is 8 mm x 8 mm.
2. Place a 5-by-5 array of thermal vias in the thermal pad area. These holes should be 13 mils in diameter. The small size prevents wicking of the solder through the holes.
3. It is recommended to place a small number of 25 mil diameter holes under the package, but outside the thermal pad area to provide an additional heat path.
4. Connect all holes (both those inside and outside the thermal pad area) to an internal copper plane (such as a ground plane).
5. Do not use the typical web or spoke via connection pattern when connecting the thermal vias to the ground plane. The spoke pattern increases the thermal resistance to the ground plane.
6. The top-side solder mask should leave exposed the terminals of the package and the thermal pad area.
7. Cover the entire bottom side of the PowerPAD vias to prevent solder wicking.
8. Apply solder paste to the exposed thermal pad area and all of the package terminals.

For more detailed information regarding the PowerPAD package and its thermal properties, see either the application brief [SLMA004B](#) (*PowerPAD Made Easy*) or technical brief [SLMA002](#) (*PowerPAD Thermally Enhanced Package*).

Table 10. Revision History

| |
|--|
| Added notes regarding the input voltage overstress requirements. |
| Changed minimum recommended sampling rate to 2 MSPS. |
| Clarified the Electrical Characteristics measurement conditions. |
| Changed power dissipation reporting to separate analog and digital power dissipation. |
| Clarified the Digital Characteristics measurement conditions. |
| Added timing parameters - output clock jitter, wakeup time, output clock rise and fall time, T_{pdj} and timings across F_s . |
| Clarified the Timing Characteristics measurement conditions. |
| Clarified output capture test modes. |
| Pin table info added - RESET pin, note on OE, SEN, SDATA and SCLK pins |
| Updated the definitions section. |
| Clarified measurement conditions for the specifications plots. |
| Updated Equation 1 to match the new definition of common-mode input current and minimum sample rate. |
| Removed the input voltage stress section - notes added in absolute max table |
| Updated the Power Down section to reflect the newly specified 2 MSPS minimum sampling rate. |
| Text in internal DLL section added about 2 MSPS |
| Note on mandatory RESET added |
| Rev D |
| Added min/max spec for Offset error and Gain error |
| Rev F |
| Output Information Section, p. 28. Changed - From: binary output format and 0x4FFF To: binary output format and 0x7FF. Changed From: binary output format and 0x2000 To: binary output format and 0x800. |

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead finish/ Ball material (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|--------------------|------|----------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|---------|
| ADS5520IPAP | ACTIVE | HTQFP | PAP | 64 | 160 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | ADS5520I | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

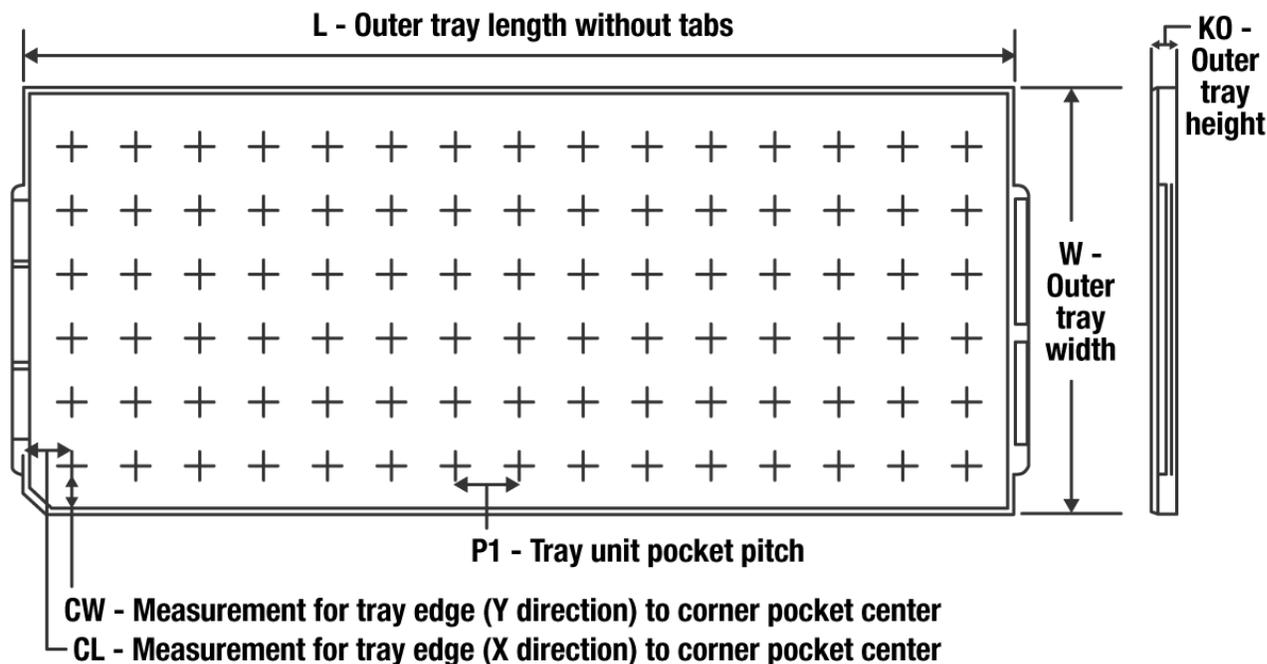
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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TRAY


Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

| Device | Package Name | Package Type | Pins | SPQ | Unit array matrix | Max temperature (°C) | L (mm) | W (mm) | K0 (µm) | P1 (mm) | CL (mm) | CW (mm) |
|-------------|--------------|--------------|------|-----|-------------------|----------------------|--------|--------|---------|---------|---------|---------|
| ADS5520IPAP | PAP | HTQFP | 64 | 160 | 8 x 20 | 150 | 315 | 135.9 | 7620 | 15.2 | 13.1 | 13 |

GENERIC PACKAGE VIEW

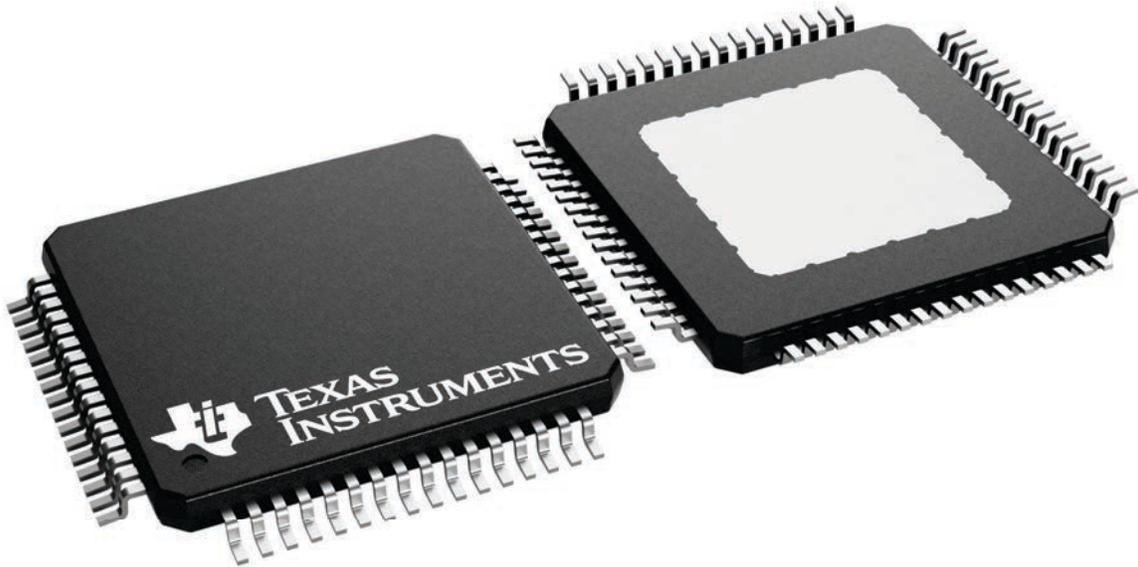
PAP 64

HTQFP - 1.2 mm max height

10 x 10, 0.5 mm pitch

QUAD FLATPACK

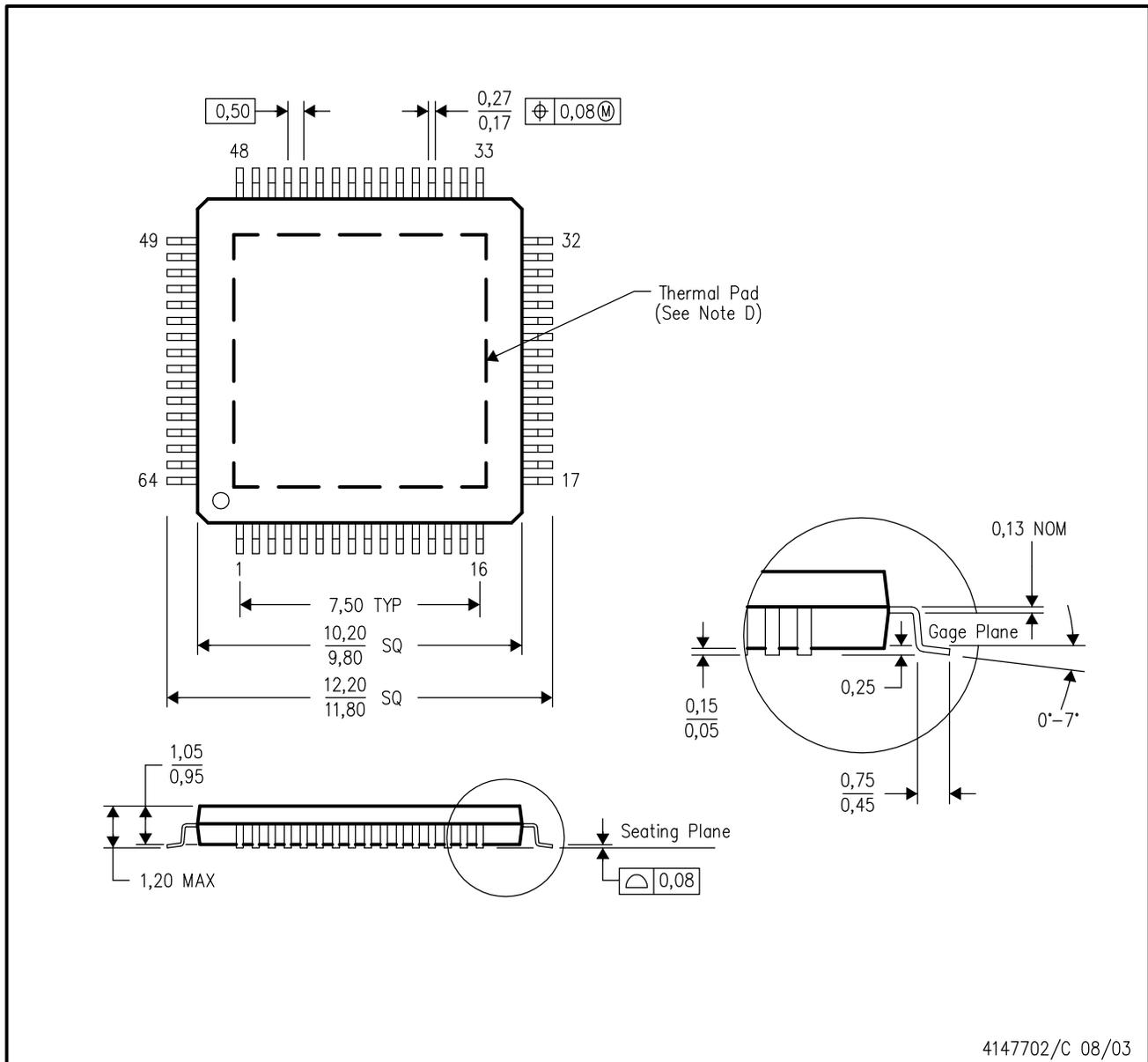
This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



4226442/A

PAP (S-PQFP-G64)

PowerPAD™ PLASTIC QUAD FLATPACK



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Body dimensions do not include mold flash or protrusion
 - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <<http://www.ti.com>>.
 - E. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.

THERMAL PAD MECHANICAL DATA

PAP (S-PQFP-G64)

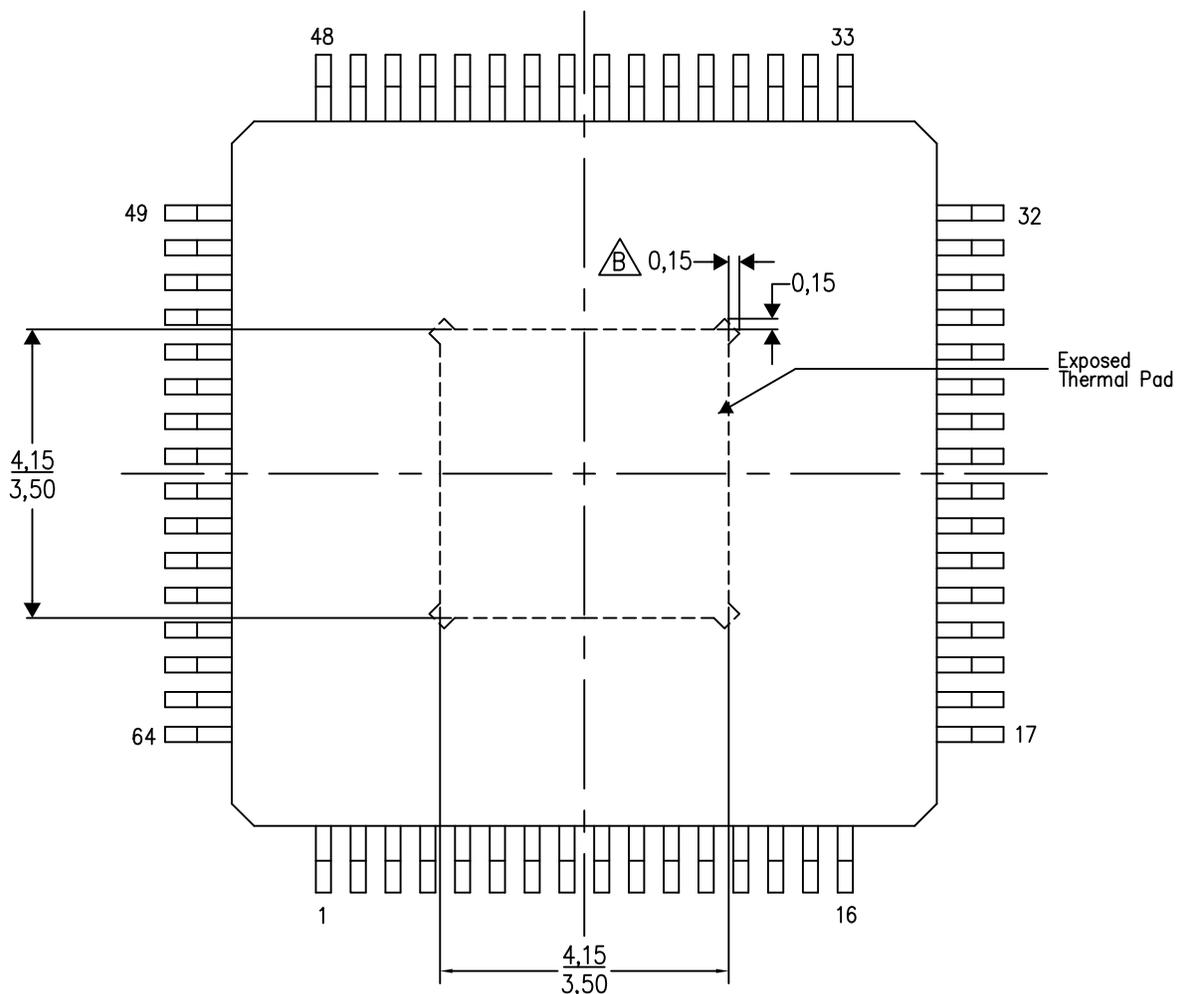
PowerPAD™ PLASTIC QUAD FLATPACK

THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Top View
Exposed Thermal Pad Dimensions

4206326-2/P 05/14

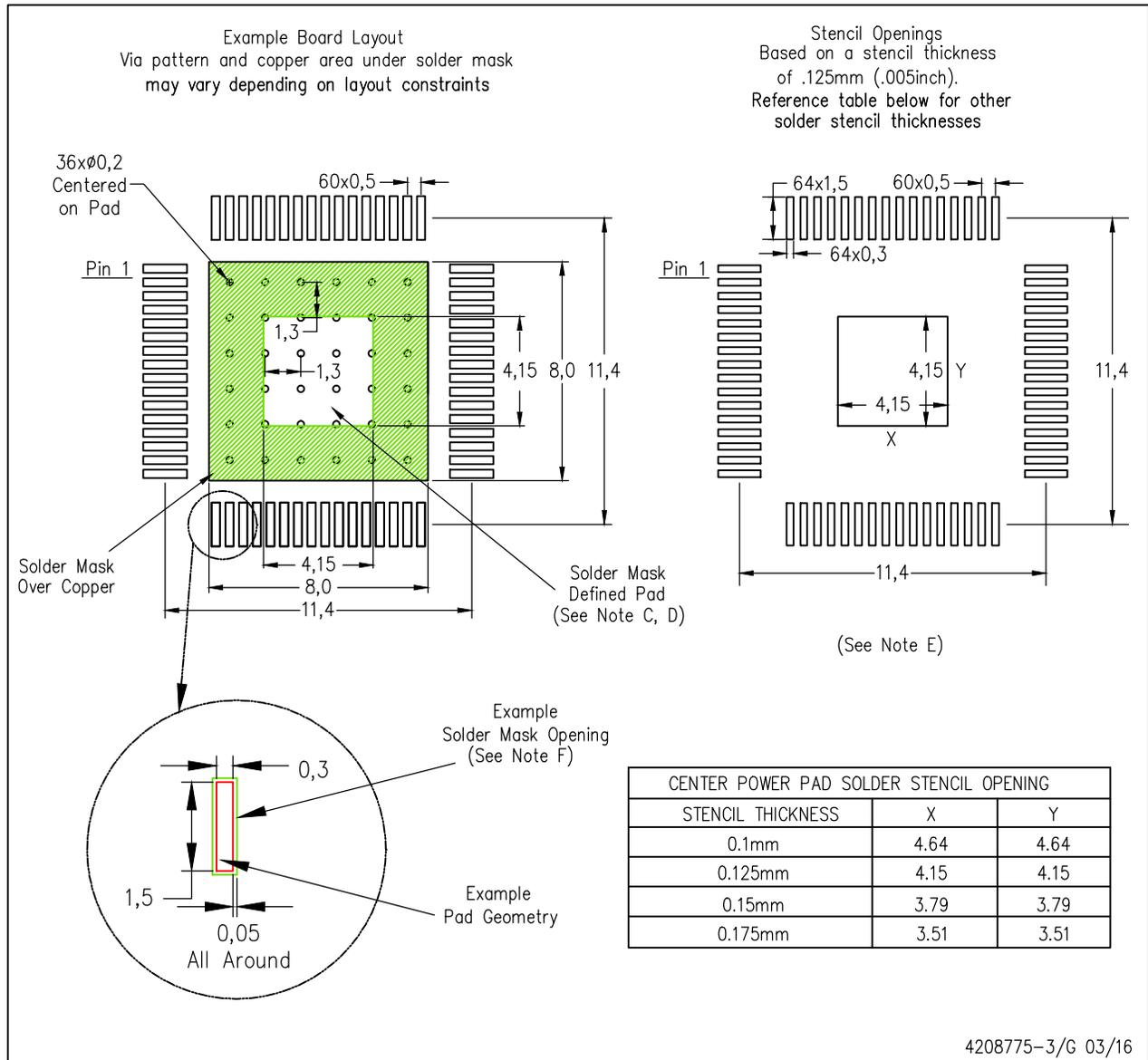
NOTES: A. All linear dimensions are in millimeters

 Tie strap features may not be present.

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PAP (S-PQFP-G64)

PowerPAD™ PLASTIC QUAD FLATPACK



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
 - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
 - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
 - F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.
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