Enabling the Electronics Revolution



PSCM Absolute Hall-Effect Multiturn Sensor



KEY FEATURES



True, contactless operation

Without any gears or mechanical interfaces the sensor is easily assembled and calibrated and subject to limited wear and tear over lifetime



Up to 32 turn absolute position feedback Keeps the last position on power loss with configurable electrical angles from

Made for harsh environments

The rugged package protects the sensor from dust, moisture, vibration and extreme temperatures for usage in the most demanding environments.



Durable and robust design The non-contacting design allows for an extra-long product lifetime of up to 50 million cycles.



Adaptable to your requirements Programmable transfer function and switch outputs as well as different output

protocols and redundancy levels

DESCRIPTION

The PSCM is a non-contacting multiturn rotary position sensor based on Hall-effect technology and a cost-effective replacement for absolute encoders. It is also perfectly suited to substitute wire actuated encoders by translating a linear movement into angular position. In the event of a power loss, the sensor will preserve the last measured position.

This compact and rugged sensor is configurable with angular ranges between 720 and 11.520 degrees (up to 32 revolutions). Connector assemblies are available on request.

The high level of ingress protection, vibration and temperature resistance makes it well suited for extreme environments of industrial, off-highway and transportation applications.

APPLICATIONS

Industrial / Machine tool **Off-Highway Vehicles** Material Handling



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Absolute Hall-Effect Multiturn Rotary Sensor

MECHANICAL SPECIFICATIONS		
Rotational life	Up to 50.000.000 cycles	
Mechanical range	360° (endless rotation)	
Shaft diameter	6mm	

ELECTRICAL SPECIFICATIONS

Linearity ¹	±1% (up to ±0.1% upon request)	
Electrical angular range	Configurable from 720° to 11520° degrees (2 to 32 turns)	
Output protocols ²	Analog (ratiometric)	
Output curve ² Standard Redundant		
Switch	Upon request	
Resolution	Up to 12 bit	
Supply voltage ³	5V ±10%	
Supply current Single version Redundant version		

Ferromagnetic materials close to the sensor (i.e. shaft, mounting surface) may affect the sensor's linearity.
Other output protocols / specifications available on request
Please note: Sensor saves last position if power is turned off, but does not count turns if not powered. For application instructions please reach out to Piher.

ENVIRONMENTAL SPECIFICATIONS		
Operating and storage temperature ¹	-40° to +85°C	
Shock	50g	
Vibration	10-2000 Hz; 10g; Amax 0,75 mm	

¹ Higher on request.

OUTPUT CURVE



Custom output functions available on request.

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DIMENSIONS (MM)



Sensor delivered at random position. Connector assembly on request.

CONNECTION SCHEME

Color	Simple output	Redundant output
Brown	Power supply	Power supply
Blue	Ground	Ground
Grey	Set to 0 (connect to power supply after calibration)	Set to 0 (connect to power supply after calibration)
Black	Output	Output 1
White	n/a	Output 2

More instructions of use on www.piher.net.

MOUNTING INSTRUCTIONS

- 1. Place the component on a flat surface.
- 2. Fit the actuator onto the shaft avoiding any mechanical play/wobble.
- 3. Fasten the two M4 screws (M4 washers are recommended).
- 4. To define the 0-degree position connect black wire to Ground for more than 100 ms.

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HOW TO ORDER (Example: PSCM-A-16S-05) PSCM А 05 Number of Output Series Output protocol Voltage supply turns² function³ S = standard / CW 05 = 5V ±10% 02 A = analogic 03 I = inverted / CCW 06 R = redundant 10 16 24 32

1 Other output protocols upon request. The analog output is ratiometric, proportional to input voltage.

2 Others on request

3 Other output functions available on request.







Please always use the latest updated datasheets and 3D models published on our website.

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