Low Power, Low Noise Ultrasound Receive Front-End Eight-Channels of LNA, VGA, AAF, CPS & 12-Bit, 50MHz ADCs

Features

- 1.8V Analog/Digital supply
- 3.3V supply for CW Doppler output bias
- Fully differential inputs and outputs
- SPI programmable LNA gain = 14dB/18dB
- LNA input range 480mV_{PP}/300mV_{PP}
- Dual mode active input impedance matching
- ▶ 1.1nV/√Hz Input Voltage Noise at 5.0MHz
- ▶ 1.0pA/√Hz Input Current Noise at 5.0MHz
- ▶ 0 to -47dB Linear-in-dB variable Gain of VCA
- 4 PGA Gain settings: 23.5, 29.0, 34.5 & 40.0dB
- Third Order Anti-Aliasing Filter (AAF)
- Program/Auto-tracking AAF (6.6~15MHz)
- Integrated 8×8 Cross-Point Switch (CPS)
- SNR 66dB, SFDR 74dB for ADC
- Built-in reference voltage
- LVDS per ANSI-644
- Fast overload recovery time
- ▶ Low power 95mW/ch, 50mW/ch CW

Applications

- Medical ultrasound imaging
- Portable ultrasound instrumentation
- Transducer signal processing

General Description

The MD3872 is an eight-channel front-end receiver for medical ultrasound imaging. Its excellent low power dynamic performance is especially suitable for portable ultrasound applications.

The circuit of each channel is composed of a 14dB/18dB low noise pre-amplifier (LNA), a voltage- controlled attenuator (VCA or TGC), a programmable gain amplifier (PGA), an anti-aliasing filter (AAF) and an analog-to-digital (ADC) converter. The gain and gain range of the VGA can be digitally configured separately. The gain of the PGA can be set to one of four discrete values: 23.5dB, 29dB, 34.5dB or 40dB. The VCA can be continuously varied by a control voltage from -47dB to a maximum of 0dB.

In CW mode, an integrated trans-conductance amplifier is driven by the LNA to generate differential output current. The resulting signal currents of each channel then connect to an 8×8 differential cross-point switch which can be programmed through the SPI.

The 12-bit ADC is based on a pipeline structure to provide high static linearity. The data, clock, and frame alignment signal outputs are serial LVDS in binary format for each channel.



Block Diagram

Ordering Information

Part Number	Package Option	Packing
MD3872HF-G	128-Lead TQFP (w/Heat Slug)	90/Tray



Absolute Maximum Ratings

Parameter	Value
AV _{DD} , Positive supply	-0.3V to +2.0V
DV _{DD} , Positive supply	-0.3V to +2.0V
CWV _{DD} , Positive supply	-0.3V to +3.75V
V_{IN} , Any input pin voltage range	-0.3V to AV_{\rm DD}
Storage temperature	-65°C to +150°C
Operating temperature	0°C to +70°C

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied. Continuous operation of the device at the absolute rating level may affect device reliability. All voltages are referenced to device ground.

Typical Thermal Resistance

Package	$oldsymbol{ heta}_{ja}$
128-Lead TQFP	21°C/W*

* 4"x3", 4-layer 1oz 16-via PCB

Pin Configuration



Package Marking



Package may or may not include the following marks: Si or

128-Lead TQFP

Operating Supply Voltages

(Over operating conditions unless otherwise specified, $AV_{pp} = DV_{pp} = PV_{pp} = 1.8V$, $CWV_{pp} = +3.3V$, $R_{sel} = Hi$, $R_s = 50\Omega$, $T_a = 25^{\circ}C$)

Sym	Parameter	Min	Тур	Max	Units	Conditions
AV _{DD}	Analog circuit supply voltage	1.71	1.8	1.89	V	
	Digital circuit supply voltage	1.71	1.8	1.89	V	f _s = 40MHz
DV _{DD}	Digital circuit supply voltage	1.80	1.90	1.98	v	f _s = 50MHz
CWV _{DD}	CW switch supply voltage	3.14	3.3	3.47	V	
	AVDD per-chip	-	360	-	~^	
AVDD	CWD mode	-	190	-	mA	
	DVDD supply current	-	70	100		f _s = 40MHz
I _{DVDD}		-	94	140	mA	f _s = 50MHz
I _{CVDD}	CVDD supply current	-	0.80	1.0	mA	8-channel total
	Per-channel at 40MSPS	-	95	-		
Dawar	Per-channel at CW mode	-	50	-		
Power	Power-down	-	-	1.0	mW	
	Standby	-	100	-		8-channel total

Low Noise Preamplifier (Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $G_{LNA} = 18dB$, $T_A = 25^{\circ}C$)

Sym	Parameter	Min	Тур	Max	Units	Conditions
G _{LNA}	Pre-amplifier gain	-	14/18	-	dB	Selectable
R _{IN}	Input resistance	-	15	-	kΩ	Without active termination
C _{IN}	Input capacitance	-	10	-	pF	Without active termination
I _{BIAS}	Input bias current	-	1.0	-	nA	From ESD leakage
V	Input voltago rango	-	±240	-	m)/	GAIN _{LNA} = 1
V _{IN}	Input voltage range	-	±150	-	mV	GAIN _{LNA} = 0
V _{LNA-}	Input voltage noise, 5MHz	-	1.3	-	nV/√Hz	LNA Gain of 14dB
NOISE	Input voltage noise, sivinz	-	1.1	-		LNA Gain of 18dB
I	Input current noise	-	1.05	-	pA/√Hz	Without active termination
NE	Noice figure	-	4.4	-	dD	f = 5.0MHz, without active termination
NF	Noise figure	-	6.0	-	dB	$R_s = R_{IN} = 50\Omega$, f = 5.0MHz with active termination
BW	LNA -3dB bandwidth	-	65	-	MHz	Small signal bandwidth

Overall Channel Characteristics

((Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{ser} = Hi$, $R_s = 50\Omega$, $T_a = 25^{\circ}C$)

111		111, 11 _S 0012, 1 _A 20 0)				
Gain	Whole channel gain	-	58	-	dB	Without active termination, max. gain
$V_{\text{CH-NOISE}}$	Input voltage noise, 5.0MHz	-	2.0/1.5	-	nV/√Hz	LNA gain of 14 or 18dB
SFDR	Spurious-free dynamic	-	63.2	-	dBc	40Msps
SFUR	range, -1dBFS, 5MHz	-	62.1	-	ивс	50Msps
SNRFS	Signal to noise ratio at full	-	56.3	-	dDa	40Msps
SINKES	scale, -1dBFS, 5MHz	-	56.2	-	dBc	50Msps
HD2	Second harmonic distortion,	-	-72	-	dDa	40Msps
ΠD2	-1dBFS, 5MHz, 40dB gain	-	-68	-	dBc	50Msps
	Third harmonic distortion,	-	-63	-	dDa	40Msps
HD3	-1dBFS, 5MHz, 40dB gain	-	-62	-	dBc	50Msps
IMD	IMD, two-tone	-	-63	-	dBc	f1 = 5.0MHz , f2 = 6.0MHz, at -7.0dBFS, 40dB gain
CSTK	Crosstalk	-	-70	-	dB	1.0MHz, $1V_{PP}$ at adjacent channel
Δt_{gd}	Group delay variation	-	±2.0	-	ns	2.0 to 10MHz, max gain range
t _{olr}	Overload recovery time	-	5.0	-	ns	8dB gain, V_{IN} 10MHz 10m V_{PP} to 0.5 V_{PP} step
f _{CHP}	High-pass cutoff frequency	-	50	-	kHz	

Gain Control and Accuracy

(Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_{S} = 50\Omega$, $T_{A} = 25^{\circ}C$)

Sym	Parameter	Min	Тур	Max	Units	Conditions
V _{TGC}	Gain control voltage	0	-	1.8	V	Linear in dB, see Gain scaling diagram
V _{GSC}	Gain slope voltage	1.44	-	1.8	V	~62dB/V at 1.44V and 47.5dB/V at 1.8V
G _{RANGE}	Gain range	-	46.5	-	dB	GSC = 0 to +1.8V
G _{SLP}	Gain slope	-	47.5	-	dB/V	GSC = +1.8V
G _{MAT}	Ch. to ch. Gain matching	-	±1.5	-	dB	0.4 < 1/ <1.21/
E _{GAIN}	Gain error	-1.6	±0.5	+1.6	dB	0.4 < V _{TGC} <1.2V
V _{os}	Output offset voltage	-	15	-	LSB	EXT = Lo (internal reference)
R _{gsc}	Input resistance of GSC	-	90	-	kΩ	VTGC = 0V
I _{TGC}	Input current of TGC	-2.0	-	+2.0	μA	For the control range of 0V to 1.8V
td _{TGC}	Response time	-	500	-	ns	0 to 90% full Gain change

Logic Inputs Characteristics

(Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_s = 50\Omega$, $T_A = 25^{\circ}C$)

V _{IH}	High-level input voltage	$0.8V_{dD}$	-	-	V	
V _{IL}	Low-level input voltage	-	-	0.2V _{DD}	V	
I _{IH}	High-level input current	-	1.0	-	μA	
I	Low-level input current	-	1.0	-	μA	
V _{OH}	High-level output voltage $(I_{OH} = 0.5 \text{mA})$	-	1.79	-	V	
V _{ol}	Low-level output voltage $(I_{OL} = 0.5 \text{mA})$	-	0.05	-	V	
C _{IN}	Input capacitance	-	2.0	-	pF	

LVDS DC and Timing Characteristics (Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_s = 50\Omega$, $T_A = 25^{\circ}C$)

V _{DO}	Differential output voltage	250	-	450	mV	
V _{OCOM}	Output common-mode voltage	1.13	-	1.37	V	
R _{TERM}	LVDS termination resistor	-	100	-	Ω	
t _R	Rise time (20 % to 80 %)	-	800	-	ps	
t _F	Fall time (80 % to 20 %)	-	800	-	ps	
t _{DCLKWH}	DCLK output width high	-	4.1	-		
t _{DCLKWL}	DCLK output width low	-	4.1	-		F _s = 40Msps
t _{D2D}	Data valid to DCLK rise/fall	-	t _s /24	-	ns	
t _{F2D}	FCLK rise to DCLK rise	-	t _s /24	-		
t _{C2F}	CLK rise to FCLK rise	-	$t_s/2 + t_{_{PRP}}$	-		

Internal and External Reference Characteristics

(Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_S = 50\Omega$, $T_A = 25^{\circ}C$)

Sym	Parameter	Min	Тур	Max	Unit	Conditions
V _{REF+}	ADC reference top voltage	-	1.4	-	V	ADC reference voltages, decou- pling capacitors required
V _{REF-}	ADC reference bottom voltage	-	0.4	-	V	
V _{REF_EXT}	External reference voltage	-	1.0	-	V	EXT = Hi (select external V_{REF})
I _{REF_MAX}	Max reference output current	-	1.0	-	mA	

CW Doppler Mode Characteristics (Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_s = 50\Omega$, $T_A = 25^{\circ}C$)

	- ,	00	00	00	SLL 5	A ,
9 _m	Transconductance	-	9.5/15.2	-	mA/V	LNA Gain = 14/18dB
V _{COMM}	Common-mode voltage	1.5	-	3.6	V	CW Doppler output pins
V _{CW-NOISE}	Input-referred noise voltage	-	1.75/1.45	-	nV/√Hz	LNA Gain 14/18dB, $R_s = 0$, $R_{FB} = \infty$
I _{OUT-BIAS}	Output DC bias	-	2.8	-	mA	Per channel
I _{OUT-SWING}	Maximum output swing	-	±2.3	-	mA _{P-P}	

Switching AC Characteristics

(Over operating conditions unless otherwise specified, $AV_{DD} = DV_{DD} = 1.8V$, $CWV_{DD} = +3.3V$, $R_{SEL} = Hi$, $R_{S} = 50\Omega$, $T_{A} = 25^{\circ}C$)

		00	80	00	SEL / S	A
F _s	ADC conversion rate	20	-	50	MSPS	
t _s	Clock period	20	-	50	ns	
t _{clkwh}	Clock pulse-width high	-	12.5	-	ns	
t _{clkwl}	Clock pulse-width low	-	12.5	-	ns	
t _{PRP}	ADC clock propagation delay	-	2.6	-	ns	
PLd	Pipeline latency delay	-	5.5	-	cycle	
t _{sby_dwn}	Time to standby	-	1.0	-	μs	
t _{sby_wup}	Time to wakeup	-	10	-	μs	
t _{PD_DWN}	Time to power down	-	1.0	-	μs	
t _{PD_UP}	Time to power up	-	10	-	ms	
t ₁	SDI valid to SCK setup time	0	2.0	-		
t ₂	SDI valid to SCK hold time	4.0	-	-		
t ₃	SCK high time	9.0	10	-		Coo coriel interface timing diagram
t ₄	SCK low time	9.0	10	-	ns	See serial interface timing diagram
t ₅	CSB pulse width	9.0	10	-		
t ₆	SCK high to CSB low	-	4.5	-		
f _{scк}	Serial clock max frequency	50	-	-	MHz	

12-Bit ADC Digital Output Coding Table

Level	ADC Input Voltage	Binary Digital Output	Notes
4094	V _{IN} > +0.999756V	1111 1111 1110	
2048	+0.000244V < V _{IN} < +0.000732V	1000 0000 0000	
2047	-0.000244V < V _{IN} < +0.000244V	0111 1111 1111	
0	V _{IN} < -0.999756V	0000 0000 0000	

SPI Registers Address and Data Table

MSB (shift	in first)				SPI Reg	gister Da	ta Word					LSB	
ADDR[3:0] Hex	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
0	-		STEP[2:0] ment Step		OUTDLY[5:0] (All channel OUTLVDS alignment delay setting)						ATP	ATP[1:0]	
1					TPD1[11	:0] (LVDS	Testing Pa	attern #1)					
2		CW1[5:0]	(Channel	1 CW mod	de control)			CW2[5:0]	(Channel	2 CW mod	de control))	
3		CW3[5:0] (Channel 3 CW mode control) CW4[5:0] (Channel 4 CW mode control)											
4		CW5[5:0] (Channel 5 CW mode control) CW6[5:0] (Channel 6 CW mode control)											
5		CW7[5:0] (Channel 7 CW mode control) CW8[5:0] (Channel 8 CW mode control)											
6	-	-	-	<u>CW/</u> TGC		CHOFF[7:0] (TGC	Per Chan	nel Power	Off, 0=ON	I 1=OFF)		
7	-	-	AAF	[1:0]	-	PDC	FLEX	-	SWLNA	GAIN- LNA	PG[1:0]		
8	-	-	CTL		PR[[5:2]		-		AAF	[5:2]		
9	-	-	-	-	A	DCPD[7:0] (ADC Pe	er Channe	Power Do	own, 0 = C	N 1 = OF	F)	
Α	-	-	-	-			R	Reserved	Default all	0			
В	5	SWING[2:0)]	-			R	Reserved	Default all	0			
С					TPDC[11	:0] (LVDS	Testing Pa	attern #C)					
D	FDDLY	/[5:0] (FCL	K and DC	LK alignm	ent delay	setting)	-	-	-	-	-	-	
E					R	Reserved	Default all	0					
F	AD	DR[3:0] to	o READ B	ack	-	-	-	-	-	-	-	-	

Note:

A bit marked as "-" means do-not-care whether it is set to "1" or "0".

TGC and GSC Voltage for Gain Scaling LNA Feedback Configurations







ADDR=0 D[10:8] STEP[2:01 LVDS Delay Step Size Control Table

STEP[2:0]	Delay Time Step Size					
000	100% (Default value)	120ps				
001	133%	160ps				
010	200%	240ps				
011	400%	480ps				
100	50% (min)	60ps				
101	57%	69ps				
110	67%	80ps				
111	80%	96ps				

Note:

1. LDVS delay time step size control. Each bit will change the delay step size by 120ps. Setting a different value than 00 will change the DLOUT[5:0] and FDDLY[5:0] delay-time's step-size.

2. If $f_s = 50$ MHz it is suggested that you use the minimum STEP[2:0] = 100.

ADDR=0 D[7:2] OUTDLY[5:0] LVDS ADC Data Output Delay Adjustment Table

OUTDLY[5:0]	Typical Rise Time Delay (ps)	Typical Fall Time Delay (ps)
00 0000	655	685
00 0001	766	805
	DELAY = 139.4 x FDDLY +655	DELAY = 148.5 x FDDLY + 699
11 1110	9241	9824
11 1111	9340	9951

Note:

OUTDLY[5:0] and ADDR = D, FDDLY[5:0] are for LVDS data OUT8-1, DCLK and FCLK alignment delay time setting.

ADDR=0 D[1:0] ATP[1:0] LVDS Alignment Test Pattern Control Table

D1	D0	LVDS Output Description
0	0	Latest ADC Results.
0	1	TPDC[11:0] data written in ADDR[C], the LVDS testing data #C.
1	0	Fixed predefined test pattern: "1000 0000 0000"
1	1	TPD1[11:0] data written in ADDR[1], the LVDS testing data #1.

ADDR=2,3,4 or 5 D[5:0] or D[11:6] CWn Cross-Point Switch Control Table (n=1 to 8 for Ch1 to Ch8)

C5	C4	C3	C2	C1	CO	Description			
0	Х	Х	Х	Х	Х				
1	0	Х	0	0	0	Differential mode CW1+, CW1-			
1	0	Х	0	0	1	Differential mode CW2+, CW2-			
1	0	Х	0	1	0	Differential mode CW3+, CW3-			
1	0	Х	0	1	1	Differential mode CW4+, CW4-			
1	0	Х	1	0	0	Differential mode CW5+, CW5-			
1	0	Х	1	0	1	Differential mode CW6+, CW6-			
1	0	Х	1	1	0	Differential mode CW7+, CW7-			
1	0	Х	1	1	1	Differential mode CW8+, CW8-			
1	1	0	0	0	0	Single-ended mode CW1+			
1	1	0	0	0	1	Single-ended mode CW2+			
1	1	0	0	1	0	Single-ended mode CW3+			
1	1	0	0	1	1	Single-ended mode CW4+			
1	1	0	1	0	0	Single-ended mode CW5+			
1	1	0	1	0	1	Single-ended mode CW6+			
1	1	0	1	1	0	Single-ended mode CW7+			
1	1	0	1	1	1	Single-ended mode CW8+			
1	1	1	0	0	0	Single-ended mode CW1-			
1	1	1	0	0	1	Single-ended mode CW2-			
1	1	1	0	1	0	Single-ended mode CW3-			
1	1	1	0	1	1	Single-ended mode CW4-			
1	1	1	1	0	0	Single-ended mode CW4-			
1	1	1	1	0	1	Single-ended mode CWS-			
1	1	1	1	1	0	Single-ended mode CW7-			
1	1	1	1	1	1	Single-ended mode CW8-			

ADDR=6 D[8] CW/TGC TGC or CW Mode Control

0	TGC mode. CH[8:1]=1 for TGC (LNA+VGA+AAF) channel 1-8 power down individually.
1	CW mode. MSB (C5) of CWn[5:0] per channel control power down channel individually.

Note:

See CWn Cross-Point Switch Control Table

ADDR=6 D[7:0]

CHOFF[7:0] TGC (LNA+VGA+AAF) Channel Power Control Table

D7	D6	D5	D4	D3	D2	D1	D0
TGC Ch8	TGC Ch7	TGC Ch6	TGC Ch5	TGC Ch4	TGC Ch3	TGC Ch2	TGC Ch1

Note:

0 = ON, 1 = OFF (power down)

ADDR=7 D[9:8] AAF[1:0] Cutoff Frequency and Control Table

A A E[4.0]	3rd Order Anti-Aliasing Filter Corner Freq fAAF						
AAF[1:0]	Min	Тур	Max	Units	Note		
00	6.6	FS/3	15	MHz	100% as default		
01		115	%	% of default			
10		Set by AAF[5:2]	MHz				
11		85	%	% of default			

ADDR=7 D[6] PDC Enable External Biasing

0	Disable external Biasing for VGA
1	Enable external Biasing for VGA

ADDR=7 D[5]

FLEX AAF Tracking Auto-Tuning Control

0	FLEX = 0 disable continuous auto-tuning for AAF tracking the input clock.
1	FLEX=1 enable continuous auto-tuning for AAF tracking the input clock,

Note:

FLEX must be set to "1" first then to "0" to turn off the AFF auto-tracking after the chip power on, although the poweron default is FLEX = 0.

ADDR=7 D[3]

SWLNA LNA Gain Switches Control

0	SW1~8 Off, disconnecting R ₁₂ to PA- terminal.
1	SWLNA=1 On, connecting R ₁₂ to PA- terminal.

ADDR=7 D[2] GAINLNA LNA Gain Control

0	LNA gain set to 18dB
1	LNA gain set to 14dB

ADDR=7 D[1:0] PG[1:0] Gain Setting

00	Select 23.5dB Gain Setting		
01	Select 29.0dB Gain Setting		
10	Select 34.5dB Gain Setting		
11	Select 40.0dB Gain Setting		

ADDR=8 D[9]

CTL AAF Frequency Programming Enable

0	AAF use AAF[5:2] tracking the sampling frequency.	
1	AAF use PR[5:2] programmed frequency.	

Note:

See AAF and PR tables

ADDR=8 D[8:5]	
PR[5:2] Cutoff Frequency Direct Control Table (CTL = 1)	

		Noto
PR[5:2]	Reference -3dB Cut-off Frequency (MHz)	Note
0000	15.8	Max. built-in AAF frequency
0001	14.3	
0010	12.9	
0011	11.8	
0100	10.8	
0101	9.9	
0110	9.2	
0111	8.6	
1000	8.0	
1001	7.6	
1010	7.1	
1011	6.8	_
1100	6.4	
1101	6.0	
1110	5.8	
1111	5.6	Min. built-in AAF frequency

ADDR=8 D[3:0] AAF[5:2] Cutoff Frequency Control Table (AAF[1:0]=10)

SPI	SPI Control Register Data Bits			Typical -3dB Cut-off Frequency (MHz)			
AAF5	AAF4	AAF3	AAF2	F _s =50MHz	F _s =40MHz	F _s =30MHz	F _s =20MHz
1	1	1	1	15.6	12.5	9.5	6.1
1	1	1	0	13.4	10.7	8.7	5.9
1	1	0	1	12.8	10.2	8.1	5.8
1	1	0	0	11.9	9.5	7.6	5.8
1	0	1	1	10.9	8.7	7.0	5.8
1	0	1	0	10.0	8.1	6.7	5.8
1	0	0	1	9.5	7.6	6.2	5.8
1	0	0	0	8.8	7.0	6.0	5.8

ADDR=9 D[7:0]

ADCPD[7:0]	ADC Channe	el Power down	Control Table	

D7	D6	D5	D4	D3	D2	D1	D0
ADC Ch8	ADC Ch7	ADC Ch6	ADC Ch5	ADC Ch4	ADC Ch3	ADC Ch2	ADC Ch1

Note:

0 = ON, 1 = OFF (power down)

ADDR=B D[11:9] SWING[2:0] LVDS Output Swing Control Table

SWING[2:0]	LVDS Output Swing Amplitude (mV)
000	350 (Default value)
001	263
010	175
011	88
100	700
101	613
110	525
111	438

ADDR=D D[11:6] FDDLY[5:0] LVDS FCLK & DCLK Delay Adjustment Table

L		
FDDLY[5:0]	Typical Rise Time Delay (ps)	Typical Fall Time Delay (ps)
00 0000	655	685
00 0001	766	805
	DELAY = 139.4 x FDDLY + 655	DELAY = 148.5 x FDDLY + 699
11 1110	9241	9824
11 1111	9340	9951

Note:

OUTDLY[5:0] and ADDR=D, FDDLY[5:0] are for LVDS data OUT8-1, DCLK and FCLK alignment delay time setting.

ADDR=F D[11:8] ADDR[3:0] Register Contain Read Back Address

0000	Read Back Register ADDR = 0x0				
0001	0001 Read Back Register ADDR = 0x1				
1110	Read Back Register ADDR = 0xE				

SPI Timing Diagram



SPI Data Diagram





LVDS Timing Diagram

General Description

The MD3872 has eight identical front-end receiver channels designed for medical ultrasound imaging. Each channel consists of a low noise preamplifier (LNA), a variable gain amplifier (VGA), an anti-aliasing filter (AAF), and a 12-bit analogto-digital converter (ADC). The VGA consists of two parts, a voltage controlled attenuator (VCA), and a programmable gain amplifier (PGA). The gain and gain range of the VGA can be digitally configured separately. The gain of the LNA is selectable. The differential outputs of each LNA can also be used to provide amplified RF signals for the CW Doppler beamforming processing. The voltage-controlled-gain TGC attenuator can be continuously varied by a control voltage at the TGC pin from -47dB to a maximum of 0dB. The gain of the TGC curve is linear-in-dB, and the slope of the curve can be adjusted by the input voltage of GSC pin for all the eight channels in the same chip.

The TGC attenuator output is AC-coupled into the PGA. PGA gain is programmed through the two gain bits (PG0 and PG1) in the SPI control register, and can be configured to four different gain settings of 23.5, 29, 34.5 and 40dB.

The AAF is a third-order Butterworth low-pass filter. The auto-tracking cutoff frequency is typically one-third of the sampling frequency, and is typically triggered by the FLEX command calibration. There are control bits in SPI for adjusting the auto-tracking cutoff frequency up to $\pm 15\%$ of the typical value for the anti-aliasing filter. In addition, the SPI control register AAF bits can set more frequency range options.

The ADC converters in the MD3872 use a very low power, high-speed, self-calibrated pipeline architecture that moves the samples through the pipeline stages every half clock-cycle. The converted digital results are serialized and sent through the LVDS output drivers. The total latency is 5.5 input clock cycles.

The following sections are detail descriptions of each programmable feature.

LNA Gain & Active Impedance Matching

The LNA consists of a differential voltage gain low noise amplifier. The LNA's inverting single-ended output gain is A = 4.0 and A = 2.5 when the LNA differential gain is 18dB and 14dB, respectively. With a known fixed gain, a feedback resistor can be connected between the LNA positive input pin (IN1+) and the inverting output pin (PA1-), and in series with a capacitor. This technique is well known as active termination and results in a better noise figure (NF) than passive termination. The effective input resistance is RIN = RFB/ (1+A). In addition, the MD3872 provides a dual mode feed-

back resistor option for connecting two feedback resistors in parallel through the SWx pins. The SWx pin is connected to the PAx pin with an internal switch which is controlled by the SWLNA bit in SPI.

TGC / CW Mode & Power Consumption

At power up, all the SPI register's data bits are reset to 0, and the MD3872 will go into the default: all TGC mode and the whole chip's current consumption is approximately 760mW if the sampling clock is 40MHz. When in the default state, CW/TGC = 0, (ADDR=6, D[7:0]='00000000'), ADCPD[7:0] ='00000000', all channels of LNA, VGA, AAF and ADC are turned on. At the same time, PLL and LVDS will be turned on in this mode.

To control each TGC (LNA+VGA+AAF) channel individually, ADDR = 6, CHOFF[7:0] provides selection of turning ON/ OFF for each TGC channel. For example, when MD3872 is in TGC mode, CW/TGC = 0 and CHOFF[7:0] = '01111111', only the TGC channel 8 is switched ON and other channels are switched OFF. In this condition, the whole chip's current consumption will be quite a bit less than when all channels are ON. To power off each ADC individually in TGC mode, ADDR = 9, ADCPD[7:0] can be programmed to state1. For example, ADCPD[7:0] = '10000000', ADC8 is powered down and the others are powered on. Note that in TGC mode, ADDR = 2, 3, 4 and 5 are meaningless.

If CW/TGC = 1, MD3872 will go into CW mode, all the VGA, ADC, AFF, LVDS and PLL will be shut down automatically and ADDR = 6, D[7:0] is meaningless. In CW mode, each channel's CW trans-conductance amplifiers ON and OFF are controlled by ADDR = 2,3,4 and 5 as shown in the CW cross-point switch control register table. For example, if CW/ TGC = 1, ADDR 2, D[11:0] ='100000100000', the MD3872 will be in CW mode and CW channels 1 and 2 will be turned on. At that time, LNA1 and LNA2 and CW-SW circuits will turn on, and the total CW output current coming from the channel 1 and channel 2 trans-conductance amplifiers will be differentially mixed into CW1+ and CW1-. The VDD current is about 25mA increasing per CW channel. If setting ADDR = 2 to 5 to CW mode ON state, all the LNA and CW trans-conductance amplifiers are switched ON.

Anti-Aliasing Filter

The MD3872 provides two options for setting the AAF corner frequency in TGC mode. The first option is the sampling frequency tracking method in which the corner frequency is tracked with 1/3 of the sampling frequency. It is achieved by the built-in six-bit resolution programmable RC value analog anti-aliasing filter for tracking with sampling frequency, temperature and process corner. It is enabled by CTL = 0 and FLEX bit/pin. The second option is the direct control method in which the corner frequency is set by directly programming the first four bits of the six-bit resolution. It is enabled by CTL = 1. However, in this mode, the corner frequency is not tracked with temperature and process. The tolerance can be up to +/- 20%. It is the easier method, as there is no need to trigger the FLEX pin/bit periodically. The direct control method is recommended if the application can tolerate a higher variation of the TGC bandwidth.

In sampling frequency tracking mode (CTL = 0), the ADDR = 7, D5 is FLEX to control the built-in AAF auto-tracking function. It is used only in TGC mode in which the AAF circuit is in operation. This SPI bit has the same function as the external FLEX pin. Either setting the SPI FLEX bit or setting the external pin can enable the AAF auto-tracking operation. If FLEX = 1, the auto-tracking circuit will function and the AAF corner frequency will track with the external sampling clock. The tacking lock-in process time is less than 50µs. The tracking program will keep on generating a new six-bit code in each cycle for all the analog filters. Thus, it needs to set FLEX back to 0 if the programming operation is completed for the whole ultrasound system, otherwise, it will generate extra noise for the chip, and therefore precautions need to be applied. Before enabling this mode, the ADDR = 7, AAF[1:0] and ADDR = 8, AAF[5:2] should be programmed first. The default state of AAF[1:0] sets the resultant tracking value to 100% of the 1/3 of the sampling frequency. As in some applications, it may need a around 15% higher or 15% lower of the 1/3 of the sampling frequency value or another more precise offset lower value (controlled by AAF[5:2]) with respect to the 1/3 sampling frequency to achieve an appropriate TGC bandwidth for better noise performance. The AAF[5:0] control bits descriptions are shown in the AAF control table.

In the direct control method (CTL = 1), ADDR = 8, D[8:5] is PR[5:2] to directly program the code for setting the AAF corner frequency as shown in the cut-off frequency direct control table. For example, if the signal tone is 3.0MHz and the application needs the lowest AAF corner frequency for the lowest noise bandwidth such that the SNR will be the highest, the PR[5:2] should be set to '1111'.

The ADDR = 7, D3 and D2 are SWLNA and GAINLNA to control the LNA feedback resistor switch and LNA gain as shown in data sheet SPI register table's notes-6 and -7. These bits will affect both TGC mode and CW mode. The feedback resistor switch option is for re-matching the input impendence externally if the LNA gain is changed. The ADDR = 7, D1 and D0 are PG[1:0] for the gain settings of VGA.

ADC Clock and PLL

ADC is the eight-channel analog to digital converter and is driven by the ADC sampling-frequency clock CLK+/CLK-LVDS input pair which normally operates from a low-jitter external 20 to 40MHz LVDS clock source. The built-in PLL phase-locked loop circuit will provide six times the input frequency as the DCLK serial data bit clock and a phase shifted version with the same frequency as the FCLK data-frame clock. The PLL also provides the ADC internal switching and conversion clocks. It is highly recommended routing the CLK+/CLK- input trace as a well controlled impedance differential LVDS line-pair, with a 100 Ω resistor as termination resistor right at the device CLK pins.

LVDS Data Alignment Pattern

There are two 12-bit digital output test binary pattern registers TPD1[11:0] and TPDC[11:0] available that can be programmed through the SPI. The SPI control register bit ATP[1:0] selects which pattern or data of ADC results to provide to the LVDS data output. These patterns allow the user to perform timing alignment adjustments among the ADCLK and LCLK, and output data.

LVDS Outputs and Clock Timing & Delay Adjustment

The differential outputs conform to a low power, reduced signal option of the ANSI-644 standard. The LVDS outputs are designed for interfacing with LVDS receivers in custom ASICs or FPGAs that have LVDS capability up to 480 MB/ sec with a 100 Ω termination resistor placed as close to the receiver as possible. It is recommended that the trace length be no longer than 12 inches and that the differential output traces be kept close together and at equal lengths.

The format of the output data is offset binary by default. An example of the output coding format can be found in the table above. Two output clocks are provided to assist in capturing data from the MD3872. DCLK± is used to clock the output data and is equal to six times the sampling clock rate. Data is clocked out of the MD3872 and must be captured on the rising and falling edges of the CLK± that supports double data rate (DDR) capturing. The frame clock output, CLK± is used to signal the start of a new output byte and is equal to the sampling clock rate. In addition, MD3872 provides LVDS ADC data OUT, FCLK and DCLK output time-delay and swing amplitude adjustment bits in SPI registers OUTDLY, FDDLY, SETP and SWING. For detailed timing, see the timing diagram and tables above.

CW Cross-point Switch and Control

MD3872 consists of an 8x8 CW cross-point switch matrix. There are eight differential inputs and eight differential outputs in the matrix. The differential inputs come from the outputs of a differential transconductance amplifier which is driven by the LNA directly. There are 16 output pins for the eight differential outputs. The outputs of the transconductance amplifier are current outputs, which can be easily routed via switches and perform summing operations for the CWD beamforming function. In single-end mode, only non-inverting transconductance amplifier output current is switched to the selected CW single-ended output. Inverting transconductance amplifier output current is disabled in this mode. All the cross-point switches in the CW switch matrix can be programmed individually through the SPI control interface. The whole CW mode operation occupies four registers in the SPI interface registers map.

Power-Down Mode

The ADDR = 7, D6 is the PDC bit to control where the LNA, CW-SW, VGA, AFF programmable reference current originates. If PDC = 0, the current usage of all four front-end circuits will be referenced from the internal front-end circuit current reference. Note that this circuit will not affect the current usage of PLL, ADC and LVDS circuit. If PDC = 1, the front-end circuits will refer to the external resistor current. In normal operation, it is strongly recommended that the internal reference be used, as it is optimized for the balance of front-end circuits' performance and power consumption. If a 10% reduction in current is desired, set PDC = 1 and connect an external bias resistor from EBC to GND. This will sacrifice a certain amount of performance. Thus, if PDC = 1 and no external resistor is connected to the EBC pin (N.C.), the total current consumption will be decreased to almost no referenced current state.





Note:

Green: sine wave input to MD3872 on the evaluation board Blue: some sine wave input to competitor on the evaluation board Both at $f_s = 40$ MHz, LNA RFB = 250Ω , Gain = 18dB, AAF = $1/3f_s$ Sample data length 32768 points FFT with Blackman-Harris Windowing

Fig. 4. MD3872 vs Competitor @7.0MHz





Fig. 10. Typical IMD2 and IMD3 Performance

12.5



70 60 50 40 dBFS 30 20 10 0⊾ 25 30 50 35 40 45 55 Sampling Frequency (MHz)



Fig. 11. Gain Error vs. TGC Voltage (at 25°C @ fs=50MHz, AAF fs/3)



Fig. 13. HD2 & HD3 vs. Sampling Frequency



Fig. 15. SFDR vs. Sampling Frequency

0

-15

-30

-45

-60

-75

-90

-105 -120

-135

2.5

5.0

7.5

10.0

Amplitude (dBFS)

Equivalent Circuits



Fig. 16 Equivalent LNA Input Circuit



Fig. 18 Equivalent Clock Input Circuit



Fig. 20 Equivalent SDO Output Circuit



Fig. 22 Equivalent SCK Input Circuit







Fig. 19 Equivalent SDI Output Circuit



Fig. 21 Equivalent Digital Output Circuit



Fig. 23 Equivalent RBIAS Circuit

Equivalent Circuits (cont.)



Fig. 24 Equivalent CSB Input Circuit





Fig. 25 Equivalent EXT Input Circuit



Fig. 26 Equivalent VREF Circuit



Fig. 28 Equivalent CW Output Circuit



Fig. 27 Equivalent TGC Input Circuit

Pin Description

Pin	Designator	Description	
1	GND	Ground	
2	AVDD2	Supply for ADC (1.8V)	
3	AVDD1	Supply for LNA & VGA (1.8V)	
4	SW5	Channel 5 LNA Output Complement	
5	PA5-	Channel 5 LNA Negative Output	
6	IN5+	Input Channel 5	
7	CM5	Channel 5 Common-mode decoupling, bypass to ground	
8	IN5-	Complementary Input Channel 5	
9	AVDD2	Supply for ADC (1.8V)	
10	AVDD1	Supply for LNA & VGA (1.8V)	
11	SW6	Channel 6 LNA Output Complement	
12	PA6-	Channel 6 LNA Negative Output	
13	IN6+	Input Channel 6	
14	CM6	Channel 6 Common-mode decoupling, bypass to ground	
15	IN6-	Complementary Input Channel 6	
16	AVDD2	Supply for ADC (1.8V)	
17	AVDD1	Supply for LNA & VGA (1.8V)	
18	SW7	Channel 7 LNA Output Complement	
19	PA7-	Channel 7 LNA Negative Output	
20	IN7+	Input Channel 7	
21	CM7	Channel 7 Common-mode decoupling, bypass to ground	
22	IN7-	Complementary Input Channel 7	
23	AVDD2	Supply for ADC (1.8V)	
24	AVDD1	Supply for LNA & VGA (1.8V)	
25	SW8	Channel 8 LNA Output Complement	
26	PA8-	Channel 8 LNA Negative Output	
27	IN8+	Input Channel 8	
28	CM8	Channel 8 Common-mode decoupling, bypass to ground	
29	IN8-	Complementary Input Channel 8	
30	GND	Ground	
31	CLK-	Negative clock input pin	
32	CLK+	Positive clock input pin	
33	AVDD4	Supply for Clock distribution circuit (1.8V)	
34	SDO	Serial Data Output	

Pin Description (cont.)

Pin	Designator	Description						
35	NC	Reserved, do not connect						
36	AVDD5	Supply for PLL (1.8V)						
37	DVDD	Supply for LVDS (1.8V)						
38	OUT8-	ADC LVDS output negative - Channel 8						
39	OUT8+	ADC LVDS output positive - Channel 8						
40	OUT7-	ADC LVDS output negative - Channel 7						
41	OUT7+	ADC LVDS output positive - Channel 7						
42	OUT6-	ADC LVDS output negative - Channel 6						
43	OUT6+	ADC LVDS output positive - Channel 6						
44	OUT5-	ADC LVDS output negative - Channel 5						
45	OUT5+	ADC LVDS output positive - Channel 5						
46	FCLK-	Negative LVDS frame clock output						
47	FCLK+	Positive LVDS frame clock output						
48	DCLK-	Negative LVDS data clock						
49	DCLK+	Positive LVDS data clock						
50	OUT4-	ADC LVDS output negative - Channel 4						
51	OUT4+	ADC LVDS output positive - Channel 4						
52	OUT3-	ADC LVDS output negative - Channel 3						
53	OUT3+	ADC LVDS output positive - Channel 3						
54	OUT2-	ADC LVDS output negative - Channel 2						
55	OUT2+	ADC LVDS output positive - Channel 2						
56	OUT1-	ADC LVDS output negative - Channel 1						
57	OUT1+	ADC LVDS output positive - Channel 1						
58	DVDD	Supply for LVDS (1.8V)						
59	N.C	Reserved, do not connect						
60	STBY	Standby						
61	PDWN	Power down						
62	AVDD6	Supply for SPI (1.8V)						
63	SCLK	Serial clock						
64	SDI	Serial data input						
65	CSB	Chip select bar						
66	NC	Reserved, do not connect						
67	NC	Reserved, do not connect						
68	IN1-	Complementary Input Channel 1						

Pin Description (cont.)

Pin	Designator	Description						
69	CM1	Channel 1 Common-mode decoupling, bypass to ground						
70	IN1+	Input Channel 1						
71	PA1-	Channel 1 LNA Negative Output						
72	SW1	Channel 1 LNA Output Complement						
73	AVDD1	Supply for LNA & VGA (1.8V)						
74	AVDD2	Supply for ADC (1.8V)						
75	IN2-	Complementary Input Channel 2						
76	CM2	Channel 2 Common-mode decoupling, bypass to ground						
77	IN2+	put Channel 2						
78	PA2-	hannel 2 LNA Negative Output						
79	SW2	channel 2 LNA Output Complement						
80	AVDD1	Supply for LNA & VGA (1.8V)						
81	AVDD2	Supply for ADC (1.8V)						
82	IN3-	Complementary Input Channel 3						
83	CM3	channel 3 Common-mode decoupling, bypass to ground						
84	IN3+	nput Channel 3						
85	PA3-	Channel 3 LNA Negative Output						
86	SW3	Channel 3 LNA Output Complement						
87	AVDD1	Supply for LNA & VGA (1.8V)						
88	AVDD2	Supply for ADC (1.8V)						
89	IN4-	Complementary Input Channel 4						
90	CM4	Channel 4 Common-mode decoupling, bypass to ground						
91	IN4+	Input Channel 4						
92	PA4-	Channel 4 LNA Negative Output						
93	SW4	Channel 4 LNA Output Complement						
94	AVDD1	Supply for LNA & VGA (1.8V)						
95	AVDD2	Supply for ADC (1.8V)						
96	GND	Ground						
97	GND	Ground						
98	FLEX	Enable automatic low-pass tuning 1 = on, 0 = off (default)						
99	AVDD7	Supply for auto-tuning circuit (1.8V)						
100	CW1+	CW Switch Output						
101	CW1-	CW Switch Output						
102	CW2+	CW Switch Output						

Pin Description (cont.)

Pin	Designator	Description							
103	CW2-	CW Switch Output							
104	CW3+	CW Switch Output							
105	CW3-	CW Switch Output							
106	CW4+	V Switch Output							
107	CW4-	CW Switch Output							
108	CVDD	W VDD (3.3V)							
109	RBIAS	ias Setting Resistor (50kΩ to GND)							
110	EXT	nternal/external reference select, Hi = External reference is selected							
111	VREF	Supply (1.0V)							
112	REF-	Differential reference (-), external decoupling capacitors $0.1\mu F//10\mu F$ to REF+, and $0.1\mu F$ to GND							
113	REF+	Differential reference (+), external decoupling capacitors $0.1\mu F//10\mu F$ to REF-, an 0.1µF to GND							
114	AVDD3	Supply for ADC reference circuit (1.8V)							
115	CVDD	CW VDD 3.3V							
116	CW5+	CW Switch Output							
117	CW5-	CW Switch Output							
118	CW6+	CW Switch Output							
119	CW6-	CW Switch Output							
120	CW7+	CW Switch Output							
121	CW7-	CW Switch Output							
122	CW8+	CW Switch Output							
123	CW8-	CW Switch Output							
124	AVDD0	Supply for LNA & VGA bias (1.8V)							
125	TGC	TGC attenuator control input for all channel, 0 to 1.8V							
126	GSC	TGC optional slope adjustment voltage input.							
127	CM0	Common-mode decoupling, bypass to ground							
128	EBC	External Current Bias, Do not connect							
Thermal Slug	GND	Thermal Slug must externally connect to the RF ground and PCB heat sink							

128-Lead TQFP (w/Heat Slug) Package Outline (HF) 14.00x14.00mm body, 1.20mm height (max), 0.40mm pitch



Note:

1. A Pin 1 identifier must be located in the index area indicated. The Pin 1 identifier can be: a molded mark/identifier; an embedded metal marker; or a printed indicator.

Symb	ol	Α	A1	A2	b	D	D1	D2	E	E1	E2	е	L	L1	L2	θ	θ1
Dimension (mm)	MIN	-	0.05	0.95	0.13	16.00 BSC	14.00 BSC	9.50 BSC	16.00 BSC	14.00 BSC	9.50 BSC	0.40 BSC	0.45	1.00 - REF	0.25 BSC	0 0	11 ⁰
	NOM	-	-	1.00	0.18								0.60			3.5 ⁰	12 ⁰
	MAX	1.20	0.15	1.05	0.23								0.75			7 0	13 ⁰

Drawings not to scale.

Supertex Doc. #: DSPD-128TQFPHF, Version NR011713.

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to <u>http://www.supertex.com/packaging.html</u>.)

Supertex inc. does not recommend the use of its products in life support applications, and will not knowingly sell them for use in such applications unless it receives an adequate "product liability indemnification insurance agreement." **Supertex inc.** does not assume responsibility for use of devices described, and limits its liability to the replacement of the devices determined defective due to workmanship. No responsibility is assumed for possible omissions and inaccuracies. Circuitry and specifications are subject to change without notice. For the latest product specifications refer to the **Supertex inc.** (website: http://www.supertex.com)

©2013 Supertex inc. All rights reserved. Unauthorized use or reproduction is prohibited.

