

# **Power Management IC Series for Automotive Body Control**



# **Motor Driver**

**BD6941FM** No.09039EAT02

## Description

BD6941FM is the reversible motor driver for output 1.25A (1Motor), and can control a DC motor in four modes (Forward, Reverse, Standby, Brake) corresponding to two control logic inputs.

## Features

- 1) 1 ch DMOS H bridge output
- 2) Four output states (Forward, Reverse, Standby, Brake) by two control logic
- 3) Built-in surge-absorbing diodes
- 4) Low standby current
- 5) Output overcurrent protection with timer.
- 6) Over voltage detection switch off
- 7) TSD detects junction temperature and circuitry switches off the outputs at high temperature.
- 8) Built-in protection monitor pin (PO)

# Applications

Onboard devices(Vehicle equipment etc)

# ● Absolute Maximum Ratings (Ta=25°C)

PARAMETER	SYMBOL	LIMIT	UNIT
SUPPLY VOLTAGE	Vcc	50	V
INPUT VOLTAGE	V <sub>INP</sub> , V <sub>INN</sub>	-0.3~20	V
OUTPUT CURRENT	Io	1.25 (*1)	А
POWER DISSIPATION	Pd	2.8 (*2)	W
OPERATING TEMPERATURE	Topr	-40~105	°C
STORAGE TEMPERATURE	Tstg	-55~150	°C
JUNCTION TEMPERATURE	Tjmax	150 °C	

<sup>\*1</sup> Not to exceed Pd and ASO.

To use at temperature above Ta=25°C reduce 22.4mW/°C.

# Operating Range

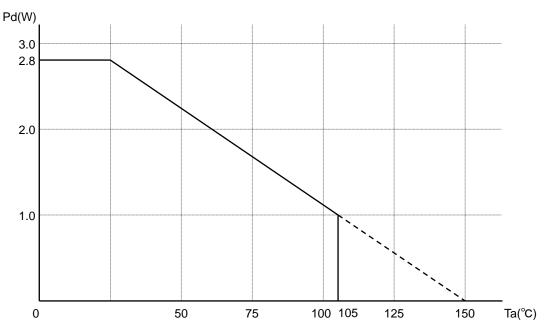
PARAMETER	SYMBOL	LIMIT	UNIT
SUPPLY VOLTAGE	Vcc	8.0~16.0	V

<sup>\*2</sup> Mounted on a glass epoxy PCB (70mm × 70mm × 1.6mm).

● Electrical Characteristics (Unless otherwise specified, Vcc=8V~16V, Ta=-40°C~105°C)

DADAMETED	CVMDOL	LIMIT		LINIT	CONDITIONS	
PARAMETER	SYMBOL	MIN.	TYP.	MAX	UNIT	CONDITIONS
Circuit current 1	lcc1	-	0	10	μΑ	Standby mode
Circuit current 2	lcc2	-	3	8	mA	Forward or reverse mode
Circuit current 3	Icc3	-	3	8	mA	Brake mode
Input Voltage "H" level	V <sub>IH</sub>	3.0	-	•	V	
Input Voltage "L" level	$V_{IL}$	-	-	1.0	V	
"H" level input current	I <sub>IH</sub>	-	50	100	μΑ	V <sub>IN</sub> =5.0V, flowing in current
"L" level input current	I <sub>IL</sub>	-	0	10	μΑ	V <sub>IN</sub> =0V, flowing out current
Output on voltage 1	V <sub>ON1</sub>	-	0.84	1.5	V	Vcc=12V, I <sub>out</sub> =0.5A, total drop
Output on voltage 2				1.7	V	Vcc=8~16V, I <sub>out</sub> =0.5A,
Output on voltage 2	V <sub>ON2</sub>	-	-	1.7	V	total drop
Output leakage current "H"	I <sub>LH</sub>	-	0	10	μΑ	V <sub>OUT</sub> =0V
Output leakage current "L"	I <sub>LL</sub>	-	0	10	μΑ	V <sub>OUT</sub> =Vcc
Upper free-wheeling	$V_{FH}$	0.3	1.0	1.5	V	I <sub>F</sub> =0.6A
diode forward voltage	VFH	0.5	1.0	1.5	V	11-0.07
Lower free-wheeling	$V_{FL}$	0.3	1.0	1.5	V	I <sub>F</sub> =0.6A
diode forward voltage	VFL	0.5	1.0	1.5	V	
Protection monitor voltage	$V_{LPO}$	-	-	0.6	V	I <sub>PO</sub> =3mA
Protection monitor	l. ==	_	0	10	μΑ	V <sub>PO</sub> =Vcc
leakage current	I <sub>LPO</sub>		U	10	μΛ	V PO= V CC
Over current protection switch	I <sub>OCP</sub>	1.5	_	3.5	Α	
on current	IOCP	1.5	_	5.5		
Over Voltage Lockout	V <sub>OVP</sub>	25	30	35	V	
lockout switch on voltage	VOVP	20	50	55	v	

# ● Heat Reduction Curve



Mounted on a glass epoxy PCB (70mm  $\times$  70mm  $\times$  1.6mm)

To use at temperature above Ta=25°C reduce 22.4mW/°C.

**Technical Note** 

# Reference Data

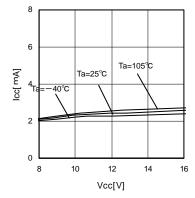
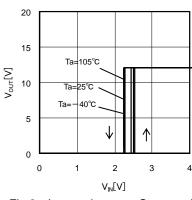


Fig.1 Circuit current (Forward · Reverse · Brake)



Input voltage vs. Output voltage

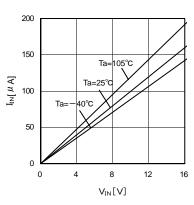
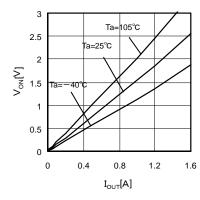


Fig.3 Input H current



Output on voltage (Vcc=12V)

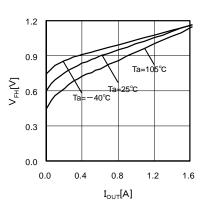


Fig.5 Upper free-wheeling diode forward voltage H

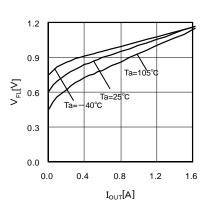


Fig.6 Upper free-wheeling diode forward voltage L

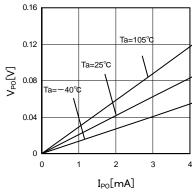


Fig.7 Protection monitor voltage

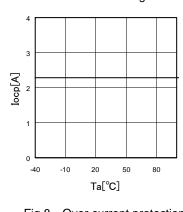


Fig.8 Over current protection switch on current

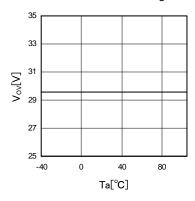


Fig.9 Over Voltage Lockout lockout switch on voltage

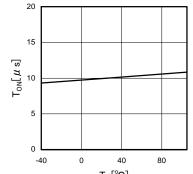


Fig.10 Over current protection monitor on time

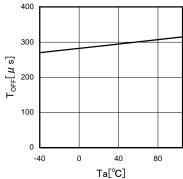
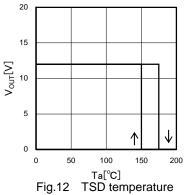
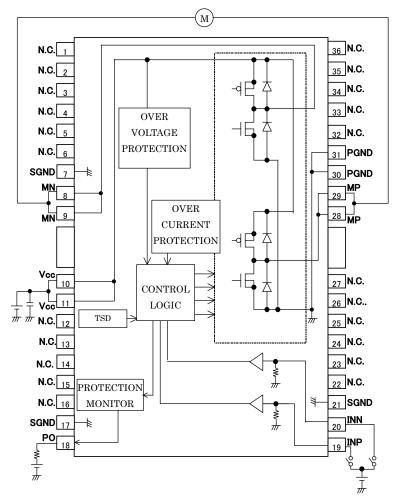


Fig.11 Over current protection monitor off time



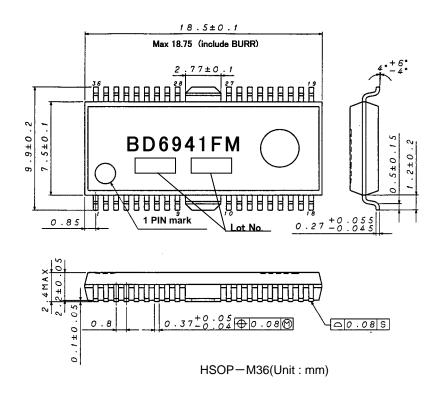
# Block Diagram



# ●Terminal Function Table

Terminal Name	Function	
N.C.	N.C.	
SGND	Signal GND Pin	
MN	Motor Output Pin	
MN	Motor Output Pin	
FIN	FIN	
Vcc	Power Supply Pin	
Vcc	Power Supply Pin	
N.C.	N.C.	
SGND	Signal GND Pin	
PO	Protection Monitor	
PO	Pin(Open drain)	
INP	Logic Input Pin	
INN	Logic Input Pin	
SGND	Signal GND Pin	
N.C.	N.C.	
FIN	FIN	
MP	Motor Output Pin	
MP	Motor Output Pin	
PGND	Power GND Pin	
PGND	Power GND Pin	
N.C.	N.C.	
	N.C. SGND MN MN FIN Vcc Vcc N.C. SGND PO INP INN SGND N.C. FIN MP MP PGND PGND	

# ●Package



# ●Signal Table

# Input/Output Truth Table

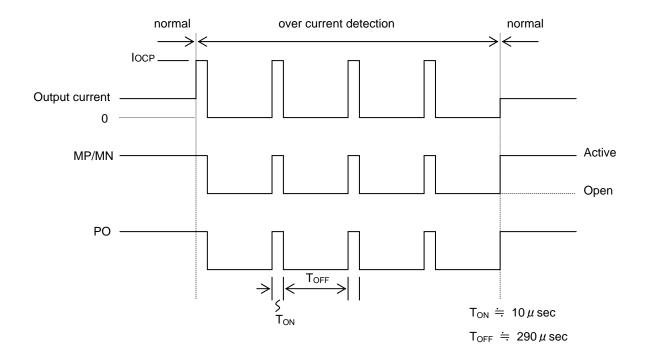
li li	N	OUT		MODE	
INP	INN	MP	MN	MODE	
Н	Н	L	L	BRAKE	
Н	L	Н	L	FORWARD	
L	Н	L	Н	REVERSE	
L	L	Open	Open	STANDBY	

# **Output Condition**

II	N	OUT		PO	
INP	INN	MODE	LOAD	PO	
	Н	DDAKE	NORMAL	Н	
Н		BRAKE	SHORT	L *2	
H/L	1.71.1	FORWARD/	NORMAL	Н	
H/L L/H	REVERSE	SHORT	L *2		
L	L	STANDBY	-	Н	

\* 2 refer to timing chart

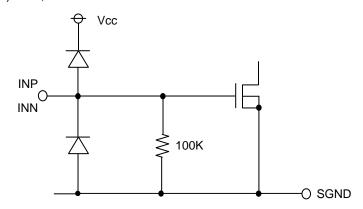
# ●PO Output Timing Chart

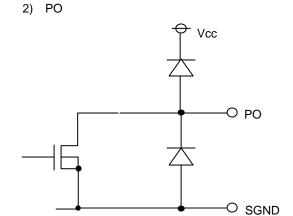


BD6941FM Technical Note

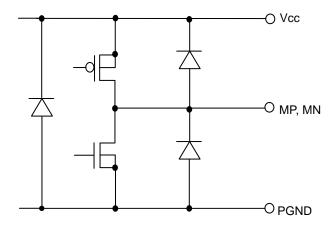
# ●I/O Circuit Diagram

# 1) INP, INN





#### 3) MP, MN



# Operating Notes

# 1) Absolute maximum ratings

Use of the IC in excess of absolute maximum ratings such as the applied voltage or operating temperature range may result in IC damage. Assumptions should not be made regarding the state of the IC (short mode or open mode) when such damage is suffered. A physical safety measuresuch as a fuse should be implemented when use of the IC in a special mode where the absolute maximum ratings may be exceeded is anticipated.

## 2) GND potential

Ensure a minimum GND pin potential in all operating conditions.

#### 3) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions.

## 4) Pin short and mistake mounting

Use caution when orienting and positioning the IC for mounting on printed circuit boards. Improper mounting may result in damage to the IC. Shorts between output pins and the power supply and GND pins caused by the presence of a foreign object may result in damage to the IC. Ensure a minimum GND pin potential in all operating conditions.

# 5) Actions in strong magnetic field

Keep in mind that the IC may malfunction in strong magnetic fields.

# 6) Testing on application boards

When testing the IC on an application board, connecting a capacitor to a pin with low impedance subjects the IC to stress. Always discharge capacitors after each process or step. Always turn the IC's power supply off before connecting it to or removing it from a jig or fixture during the inspection process. Ground the IC during assembly steps as an antistatic measure, and use similar caution when transporting or storing the IC.

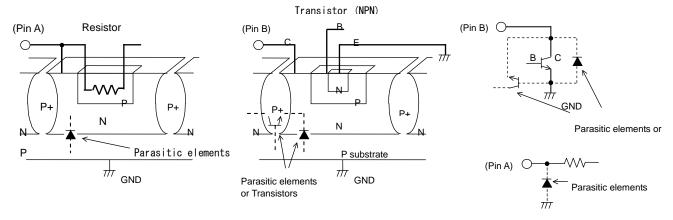
6/8

#### 7) IC terminal input voltage

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P/N junctions are formed at the intersection of these P layers with the N layers of other elements to create a variety of parasitic elements. For example, when the resistors and transistors are connected to the pins as shown in the following figure,

OThe P/N junction functions as a parasitic diode when GND > Pin A for the resistor or GND > Pin B for the transistor(NPN). OSimilarly, when GND > Pin B for the transistor (NPN), the parasitic diode described above combines with the N layer of other adjacent elements to operate as a parasitic NPN transistor.

The formation of parasitic elements as a result of the relationships of the potentials of different pins is an inevitable result of the IC's architecture. The operation of parasitic elements can cause interference with circuit operation as well as IC malfunction and damage. For these reasons, it is necessary to use caution so that the IC is not used in a way that will trigger the operation of parasitic elements, such as by the application of voltages lower than the GND (P substrate) voltage to input pins.



## 8) Input terminals

Do not apply the voltage to input pin when the Vcc is not applied. And when the Vcc is applied, the voltage of input pin must not exceed Vcc. It is feared that output get malfunction, as input voltage is sweeped slowly near the H, L threshold voltage. Please pay attention to input slew rate.

# 9) Back electro motive force (BEMF)

There is a possibility that the BEMF is changed by use of the operating condition, environment and the individual characteristics of motor. Please make sure there is no problem of operating the IC although the BEMF is occurred.

## 10) The note of pattern design at printed circuit

This IC flows large current between power supply for motor division and GND. So, it is feared that get undesirable result malfunction, oscillation and so on, as input lines is affected by large output current. Please consider pattern design at printed circuit doesn't have common impedance on output large current lines-input lines. Please consider to keep low impedance of power supply for fear of oscillation from power supply high impedance, also.

#### 11) Rash current

This IC doesn't have current limit circuit for rash current. Therefore physical security countermeasure, like current limit resistor is to be given.

# 12) Thermal shutdown circuit

This IC incorporates a built-in TSD circuit for the protection from thermal destruction. The IC should be used within the specified power dissipation range. However, in the event that the IC continues to be operated in excess of its power dissipation limits, the attendant rise in the junction temperature (Tj) will trigger the TSD circuit to turn off all output power elements. The circuit automatically resets once the junction temperature (Tj) drops. Operation of the TSD circuit presumes that the IC's absolute maximum ratings have been exceeded. Application designs should never make use of the TSD circuit.

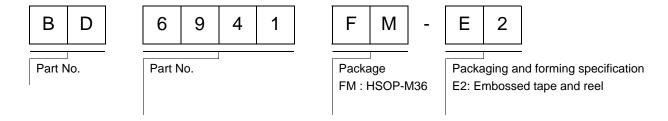
# 13) Over voltage lock out function

This IC has the function of turning off the output when detecting the over voltage. More than 30V(typ.) triggers this function. But in the standby mode, this function does not work. Although this IC has over voltage lockout function, the voltage that exceeds absolute maximum ratings might destroy the IC. Please do not exceed the absolute maximum ratings.

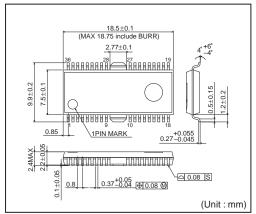
## 14) Over current protection

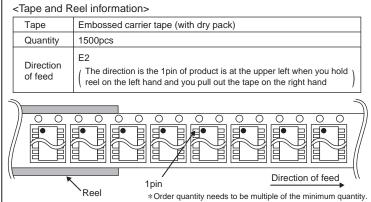
This IC has the function of turning off the output when detecting the over current. More than 2.25A(typ.) triggers this function. When detecting the over current for  $10\,\mu\,\text{sec}(\text{typ.})$ , this function turns off the output(output terminals become Hi-impedance) for  $290\,\mu\,\text{sec}(\text{typ.})$ . After the period of turning off time ( $290\,\mu\,\text{sec}$ ), the output current recovers. But if the over current is still detected, this function will work again. This function is for protecting IC because of the output short etc. but the continuing detection of over current might cause the extreme heat and damage the IC. It is recommended to change the IC's state to standby mode by the application. And please pay attention to the power dissipation.

# Ordering part number



# HSOP-M36





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JAPAN	USA	EU	CHINA	
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  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

## Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

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  - the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
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- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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